

CSE 451: Operating Systems Autumn 2009

Module 8 Semaphores and Monitors

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Semaphores

- Semaphore = a synchronization primitive
 - higher level of abstraction than locks
 - invented by Dijkstra in 1968, as part of the THE operating system
- A semaphore is:
 - a variable that is manipulated through two operations, P and V (Dutch for "wait" and "signal")
 - P(sem) (wait)
 - block until sem > 0, then subtract 1 from sem and proceed
 - V(sem) (signal)
 - add 1 to sem
- Do these operations *atomically*

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Blocking in semaphores

- Each semaphore has an associated queue of threads
 - when P (sem) is called by a thread,
 - if sem was "available" (>0), decrement sem and let thread continue
 - if sem was "unavailable" (<=0), place thread on associated queue; dispatch some other runnable thread
 - when V (sem) is called by a thread
 - if thread(s) are waiting on the associated queue, unblock one
 - place it on the ready queue
 - might as well let the "V-ing" thread continue execution
 - otherwise (when no threads are waiting on the sem), increment sem
 - the signal is "remembered" for next time P(sem) is called
- Semaphores thus have history

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Abstract implementation

- P/wait(sem)
 - acquire "real" mutual exclusion
 - if sem is "available" (>0), decrement sem; release "real" mutual exclusion; let thread continue
 - otherwise, place thread on associated queue; release "real" mutual exclusion; run some other thread
- V/signal(sem)
 - acquire "real" mutual exclusion
 - if thread(s) are waiting on the associated queue, unblock one (place it on the ready queue)
 - if no threads are on the queue, sem is incremented
 - » the signal is "remembered" for next time P(sem) is called
 - release "real" mutual exclusion
 - [the "V-ing" thread continues execution, or may be preempted]

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Two types of semaphores

- Binary semaphore (aka mutex semaphore)
 - sem is initialized to 1
 - guarantees mutually exclusive access to resource (e.g., a critical section of code)
 - only one thread/process allowed entry at a time
- Counting semaphore
 - sem is initialized to N
 - N = number of units available
 - represents resources with many (identical) units available
 - allows threads to enter as long as more units are available

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Usage

- From the programmer's perspective, P and V on a binary semaphore are just like Acquire and Release on a lock

```
P(sem)
:
:
do whatever stuff requires mutual exclusion; could conceivably
be a lot of code
:
:
V(sem)
```
- same lack of programming language support for correct usage
- Important differences in the underlying implementation, however

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Pressing questions

- How do you acquire "real" mutual exclusion?
- Why is this any better than using a spinlock (test-and-set) or disabling interrupts (assuming you're in the kernel) in lieu of a semaphore?
- What if some bozo issues an extra V?
- What if some bozo forgets to P before manipulating shared state?

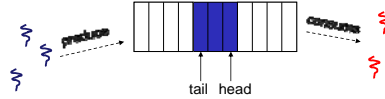
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Example: Bounded buffer problem

- AKA "producer/consumer" problem
 - there is a buffer in memory with N entries
 - producer threads insert entries into it (one at a time)
 - consumer threads remove entries from it (one at a time)
- Threads are concurrent
 - so, we must use synchronization constructs to control access to shared variables describing buffer state



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Bounded buffer using semaphores (both binary and counting)

```
var mutex: semaphore = 1 ; mutual exclusion to shared data
    empty: semaphore = n ; count of empty buffers (all empty to start)
    full: semaphore = 0 ; count of full buffers (none full to start)
```

```
producer:
P(empty) ; one fewer buffer, block if none available
P(mutex) ; get access to pointers
<add item to buffer>
V(mutex) ; done with pointers
V(full) ; note one more full buffer
```

Note 1:
I have elided all the code concerning which is the first full buffer, which is the last full buffer, etc.

```
consumer:
P(full) ; wait until there's a full buffer
P(mutex) ; get access to pointers
<remove item from buffer>
V(mutex) ; done with pointers
V(empty) ; note there's an empty buffer
<use the item>
```

Note 2:
Try to figure out how to do this without using counting semaphores!

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Example: Readers/Writers

- Description:
 - A single object is shared among several threads/processes
 - Sometimes a thread just reads the object
 - Sometimes a thread updates (writes) the object
- **We can allow multiple readers at a time**
 - why?
- **We can only allow one writer at a time**
 - why?

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Readers/Writers using semaphores

```
var mutex: semaphore = 1 ; controls access to readcount
    wrt: semaphore = 1 ; control entry for a writer or first reader
    readcount: integer = 0 ; number of active readers
```

```
writer:
P(wrt) ; any writers or readers?
<perform write operation>
V(wrt) ; allow others
```

```
reader:
P(mutex) ; ensure exclusion
readcount++ ; one more reader
if readcount == 1 then P(wrt) ; if we're the first, synch with writers
V(mutex)
<perform read operation>
P(mutex) ; ensure exclusion
readcount-- ; one fewer reader
if readcount == 0 then V(wrt) ; no more readers, allow a writer
V(mutex)
```

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Readers/Writers notes

- Notes:
 - the first reader blocks on P(wrt) if there is a writer
 - any other readers will then block on P(mutex)
 - if a waiting writer exists, the last reader to exit signals the waiting writer
 - can new readers get in while a writer is waiting?
 - does this cause any problems?
 - when writer exits, if there is both a reader and writer waiting, which one goes next?

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Semaphores vs. Locks

- Threads that are blocked at the level of program logic (that is, by the semaphore P operation) are placed on queues, rather than busy-waiting
- Busy-waiting may be used for the "real" mutual exclusion required to implement P and V
 - but these are very short critical sections – totally independent of program logic
 - and they are not implemented by the application programmer
- In the not-very-interesting case of a thread package implemented in an address space "powered by" only a single kernel thread, it's even easier that this

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Problems with semaphores (and locks)

- They can be used to solve any of the traditional synchronization problems, but:
 - semaphores are essentially shared global variables
 - can be accessed from anywhere (bad software engineering)
 - there is no connection between the semaphore and the data being controlled by it
 - used for both critical sections (mutual exclusion) and for coordination (scheduling)
 - no control over their use, no guarantee of proper usage
- Thus, they are prone to bugs
 - another (better?) approach: use programming language support

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One More Approach: Monitors

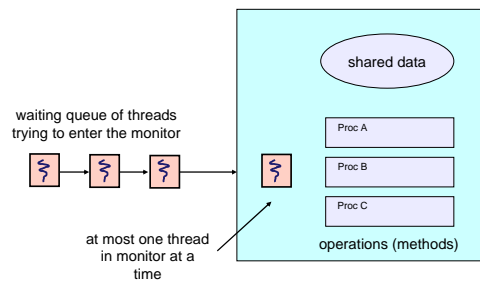
- A *monitor* is a programming language construct that supports controlled access to shared data
 - synchronization code is added by the compiler
 - why does this help?
- A monitor encapsulates:
 - **shared data** structures
 - **procedures** that operate on the shared data
 - **synchronization** between concurrent threads that invoke those procedures
- Data can only be accessed from within the monitor, using the provided procedures
 - protects the data from unstructured access
- Addresses the key usability issues that arise with semaphores

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A monitor



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Monitor facilities

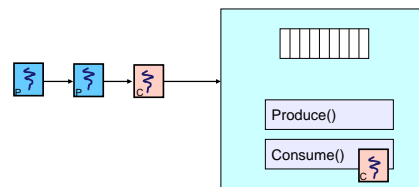
- "Automatic" mutual exclusion
 - only one thread can be executing inside at any time
 - thus, synchronization is implicitly associated with the monitor – it "comes for free"
 - if a second thread tries to execute a monitor procedure, it blocks until the first has left the monitor
 - more restrictive than semaphores
 - but easier to use (most of the time)
- But, there's a problem...

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Problem: Bounded Buffer Scenario



- Buffer is empty
- Now what?

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Problem: Bounded Buffer Scenario

- Buffer is full
- Now what?

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Condition variables

- A place to wait; sometimes called a rendezvous point
- “Required” for monitors
 - So useful they’re often provided even when monitors aren’t available
- Three operations on condition variables
 - wait(c)
 - release monitor lock, so somebody else can get in
 - wait for somebody else to signal condition
 - thus, condition variables have associated wait queues
 - signal(c)
 - wake up at most one waiting thread
 - “Hoare” monitor: wakeup immediately, signaller steps outside
 - if no waiting threads, signal is lost
 - this is different than semaphores: no history!
 - broadcast(c)
 - wake up all waiting threads

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Bounded buffer using (Hoare) monitors

```

Monitor bounded_buffer {
  buffer resources[N];
  condition not_full, not_empty;

  produce(resource x) {
    if (array "resources" is full, determined maybe by a count)
      wait(not_full);
    insert "x" in array "resources";
    signal(not_empty);
  }

  consume(resource *x) {
    if (array "resources" is empty, determined maybe by a count)
      wait(not_empty);
    *x = get resource from array "resources";
    signal(not_full);
  }
}

```

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Problem: Bounded Buffer Scenario

- Buffer is full
- Now what?

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Bounded Buffer Scenario with CV's

- Buffer is full
- Now what?

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Runtime system calls for (Hoare) monitors

- EnterMonitor(m) {**guarantee mutual exclusion**}
- ExitMonitor(m) {**hit the road, letting someone else run**}
- Wait(c) {**step out until condition satisfied**}
- Signal(c) {**if someone's waiting, step out and let him run**}

- EnterMonitor and ExitMonitor are inserted automatically by the compiler.
- This guarantees mutual exclusion for code inside of the monitor.

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Bounded buffer using (Hoare) monitors

```

Monitor bounded_buffer {
  buffer resources[N];
  condition not_full, not_empty;

  procedure add_entry(resource x) { ..... EnterMonitor
    if (array "resources" is full, determined maybe by a count)
      wait(not_full);
    insert "x" in array "resources"
    signal(not_empty); ..... ExitMonitor
  }
  procedure get_entry(resource *x) { ..... EnterMonitor
    if (array "resources" is empty, determined maybe by a count)
      wait(not_empty);
    *x = get resource from array "resources"
    signal(not_full); ..... ExitMonitor
  }
}

```

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There is a subtle issue with that code...

- Who runs when the signal() is done and there is a thread waiting on the condition variable?
- **Hoare monitors:** signal(c) means
 - run waiter immediately
 - signaller blocks immediately
 - condition guaranteed to hold when waiter runs
 - but, signaller must **restore monitor invariants** before signalling!
 - cannot leave a mess for the waiter, who will run immediately!
- **Mesa monitors:** signal(c) means
 - waiter is made ready, but the signaller continues
 - waiter runs when signaller leaves monitor (or waits)
 - signaller need not restore invariant until it leaves the monitor
 - **being woken up is only a hint that something has changed**
 - signalled condition may no longer hold
 - must recheck conditional case

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Hoare vs. Mesa Monitors

- Hoare monitors: `if (notReady) wait(c)`
- Mesa monitors: `while (notReady) wait(c)`
- Mesa monitors easier to use
 - more efficient
 - fewer context switches
 - directly supports broadcast
- Hoare monitors leave less to chance
 - when wake up, condition guaranteed to be what you expect

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Runtime system calls for Hoare monitors

- EnterMonitor(m) {**guarantee mutual exclusion**}
 - if m occupied, insert caller into queue m
 - else mark as occupied, insert caller into ready queue
 - choose somebody to run
- ExitMonitor(m) {**hit the road, letting someone else run**}
 - if queue m is empty, then mark m as unoccupied
 - else move a thread from queue m to the ready queue
 - insert caller in ready queue
 - choose someone to run

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- Wait(c) {**step out until condition satisfied**}
 - if queue m is empty, then mark m as unoccupied
 - else move a thread from queue m to the ready queue
 - put the caller on queue c
 - choose someone to run
- Signal(c) {**if someone's waiting, step out and let him run**}
 - if queue c is empty then put the caller on the ready queue
 - else move a thread from queue c to the ready queue, and put the caller into queue m
 - choose someone to run

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Runtime system calls for Mesa monitors

- EnterMonitor(m) {**guarantee mutual exclusion**}
 - ...
- ExitMonitor(m) {**hit the road, letting someone else run**}
 - ...
- Wait(c) {**step out until condition satisfied**}
 - ...
- Signal(c) {**if someone's waiting, give him a shot after I'm done**}
 - if queue c is occupied, move one thread from queue c to queue m
 - return to caller

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- Broadcast(c) {food fight!}
 - move all threads on queue c onto queue m
 - return to caller

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Readers and Writers (stolen from Cornell ©)

```

Monitor ReadersNWriters {
  int WaitingWriters, WaitingReaders, NReaders, NWriters;
  Condition CanRead, CanWrite;

  Void BeginWrite()
  {
    if(NWriters == 1 || NReaders > 0)
    {
      ++WaitingWriters;
      wait(CanWrite);
      --WaitingWriters;
    }
    NWriters = 1;
  }
  Void EndWrite()
  {
    NWriters = 0;
    if(WaitingReaders)
      Signal(CanRead);
    else
      Signal(CanWrite);
  }

  Void BeginRead()
  {
    if(NWriters == 1 || WaitingWriters > 0)
    {
      ++WaitingReaders;
      Wait(CanRead);
      --WaitingReaders;
    }
    ++NReaders;
    Signal(CanRead);
  }
  Void EndRead()
  {
    if(--NReaders == 0)
      Signal(CanWrite);
  }
}

```

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Monitor Summary

- Language supports monitors
- Compiler understands them
 - compiler inserts calls to runtime routines for
 - monitor entry
 - monitor exit
 - signal
 - wait
 - Language/object encapsulation ensures correctness
 - Sometimes! With conditions, you *still* need to think about synchronization
- Runtime system implements these routines
 - moves threads on and off queues
 - ensures *mutual exclusion!*

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