

Announcements

- Reader is in the **BOOK STORE** (not Comm Bldg.)
- Mailing list: cse455@cs.washington.edu
 - you should have received messages
- Office hours [online](#)
 - start next week
 - » this week: by appt. only
- Project 1 out today (due in two weeks)
 - posted on [course web page](#)
 - help session today
- Your ID card should open Sieg 327
 - check to make sure ASAP

Image Scissors

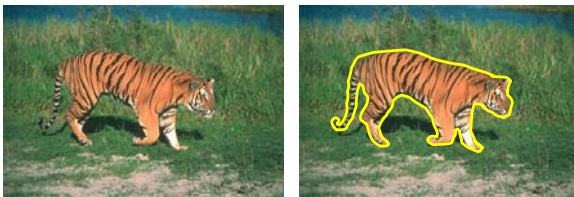


[Aging Helen Mirren](#)

Today's Readings

- [Intelligent Scissors](#), Mortensen et. al, SIGGRAPH 1995

Extracting objects



How could this be done?

- hard to do manually
- hard to do automatically ("image segmentation")
- easy to do *semi-automatically*

Intelligent Scissors (demo)

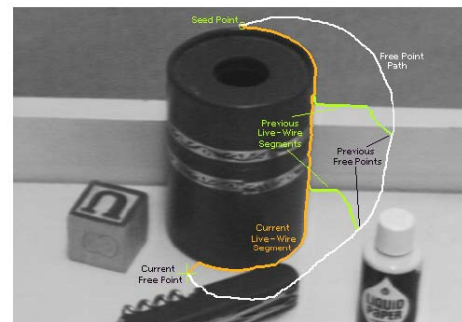


Figure 2: Image demonstrating how the live-wire segment adapts and snaps to an object boundary as the free point moves (via cursor movement). The path of the free point is shown in white. Live-wire segments from previous free point positions (t_0 , t_1 , and t_2) are shown in green.

Intelligent Scissors

Approach answers a basic question

- Q: how to find a path from seed to mouse that follows object boundary as closely as possible?
- A: define a path that stays as close as possible to edges

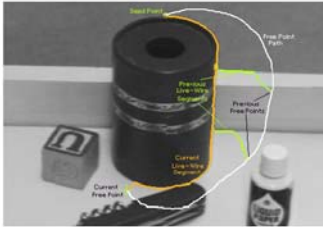
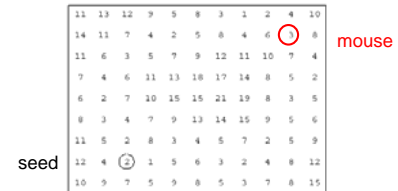


Figure 2: Image demonstrating how the live-wire segment adapts and snaps to an object boundary as the free point moves (via cursor movement). The path of the free point is shown in white. Live-wire segments from previous free point positions (t_0 , t_1 , and t_2) are shown in green.

Intelligent Scissors

Basic Idea

- Define edge score for each pixel
 - edge pixels have low cost
- Find lowest cost path from seed to mouse



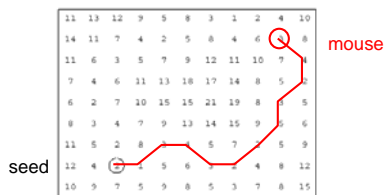
Questions

- How to define costs?
- How to find the path?

Intelligent Scissors

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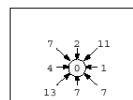
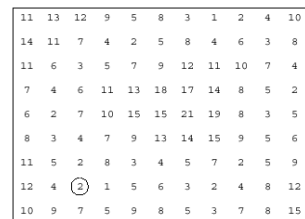
Questions

- How to define costs?
- How to find the path?

Path Search (basic idea)

Graph Search Algorithm

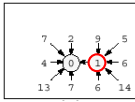
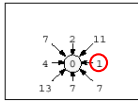
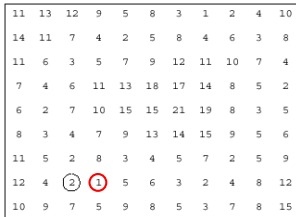
- Computes minimum cost path from seed to *all other pixels*



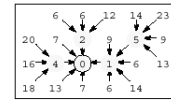
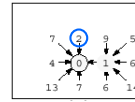
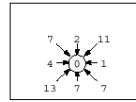
Path Search (basic idea)

Graph Search Algorithm

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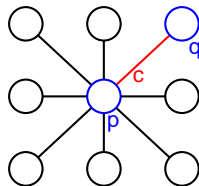


Path Search (basic idea)



Let's look at this more closely

Treat the image as a graph



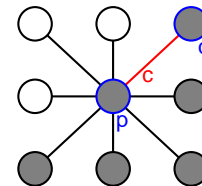
Graph

- node for every pixel **p**
- link between every adjacent pair of pixels, **p,q**
- cost **c** for each link

Note: each *link* has a cost

- this is a little different than the figure before where each pixel had a cost

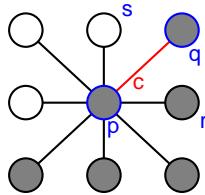
Defining the costs



Want to hug image edges: how to define cost of a link?

- the link should follow the intensity edge

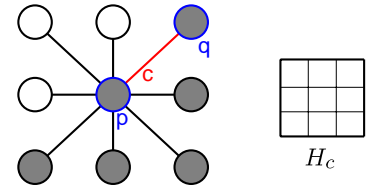
Defining the costs



Want to hug image edges: how to define cost of a link?

- the link should follow the intensity edge
 - want intensity to change rapidly \perp to the link
- $c \approx -\frac{1}{\sqrt{2}} |\text{intensity of } r - \text{intensity of } s|$

Defining the costs



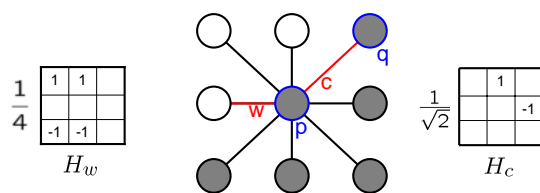
c can be computed using a cross-correlation filter

- assume it is centered at p

A couple more modifications

- Scale the filter response by length of link c . Why?
- Make c positive
 - Set $c = (\max \cdot |\text{filter response}| \cdot \text{length})$
 - where max = maximum $|\text{filter response}| \cdot \text{length}$ over all pixels in the image

Defining the costs



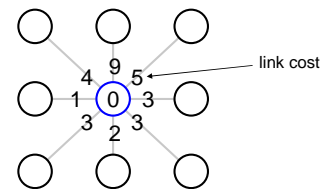
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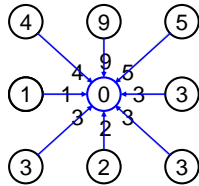
Dijkstra's shortest path algorithm



Algorithm

- init node costs to ∞ , set p = seed point, $\text{cost}(p) = 0$
- expand p as follows:
 - for each of p 's neighbors q that are not expanded
 - set $\text{cost}(q) = \min(\text{cost}(p) + c_{pq}, \text{cost}(q))$

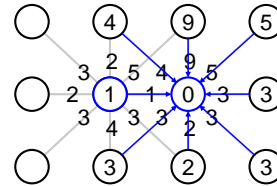
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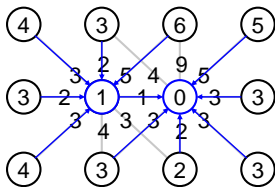
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4. repeat Step 2 for $p = r$

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Dijkstra's shortest path algorithm

Properties

- It computes the minimum cost path from the seed to every node in the graph. This set of minimum paths is represented as a *tree*
- Running time, with N pixels:
 - $O(N^2)$ time if you use an active list
 - $O(N \log N)$ if you use an active priority queue (heap)
 - takes fraction of a second for a typical (640x480) image
- Once this tree is computed once, we can extract the optimal path from any point to the seed in $O(N)$ time.
 - it runs in real time as the mouse moves
- What happens when the user specifies a new seed?

Results



[Jason Dang](#)



[Peter Davis](#)

<http://www.cs.washington.edu/education/courses/455/08wi/projects/project1/artifacts/index.html>

Help session—Ryan
