

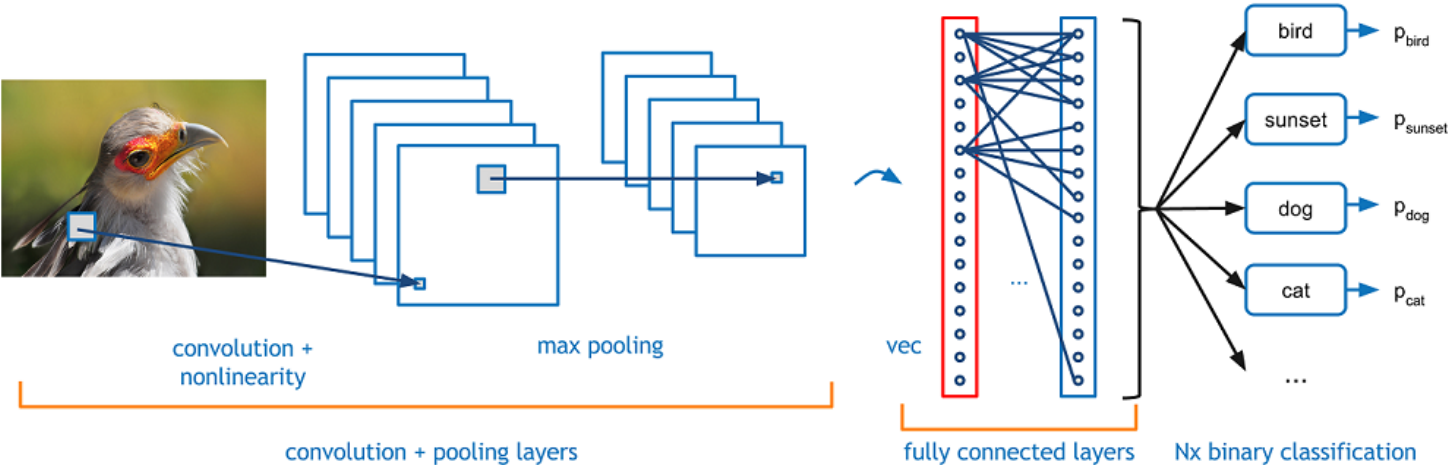
Basics for Convolutional Neural Network

CSE 455

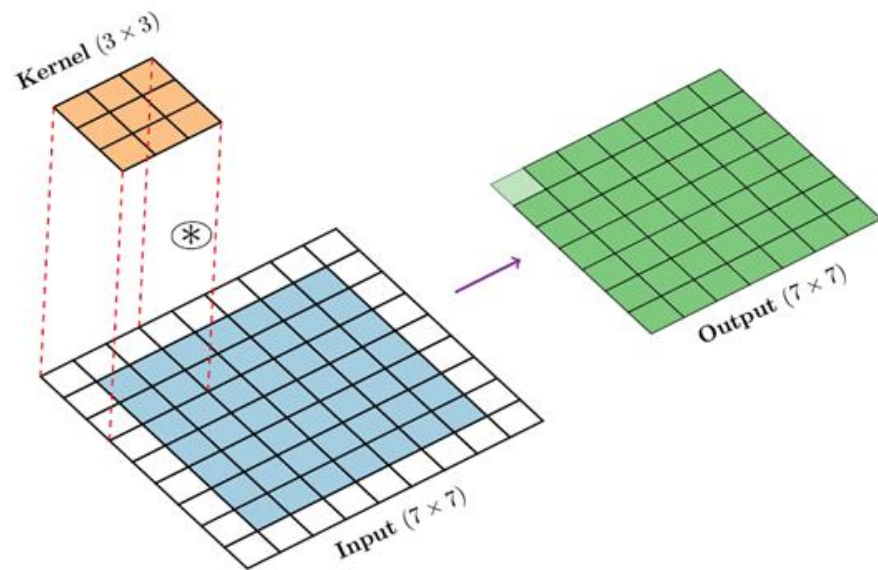
Beibin Li

2020-05-26

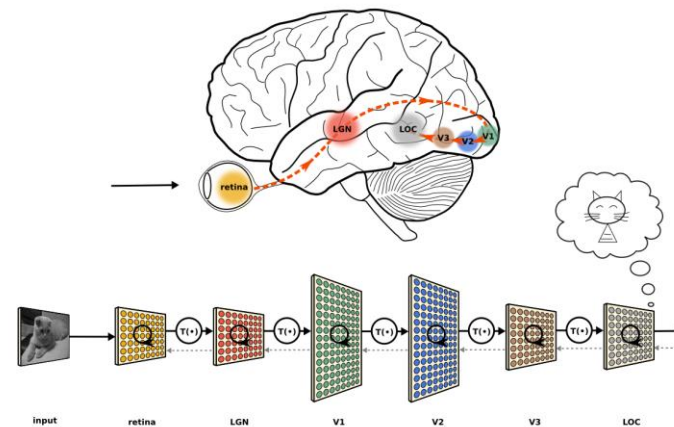
CNN



Convolution Operation



Nowadays, we learn kernels from the data.



Learning

$$\begin{array}{|c|c|} \hline O_{11} & O_{12} \\ \hline O_{21} & O_{22} \\ \hline \end{array} = \text{Convolution} \left(\begin{array}{|c|c|c|} \hline X_{11} & X_{12} & X_{13} \\ \hline X_{21} & X_{22} & X_{23} \\ \hline X_{31} & X_{32} & X_{33} \\ \hline \end{array}, \begin{array}{|c|c|} \hline F_{11} & F_{12} \\ \hline F_{21} & F_{22} \\ \hline \end{array} \right)$$

$$O_{11} = F_{11}X_{11} + F_{12}X_{12} + F_{21}X_{21} + F_{22}X_{22}$$

$$O_{12} = F_{11}X_{12} + F_{12}X_{13} + F_{21}X_{22} + F_{22}X_{23}$$

$$O_{21} = F_{11}X_{21} + F_{12}X_{22} + F_{21}X_{31} + F_{22}X_{32}$$

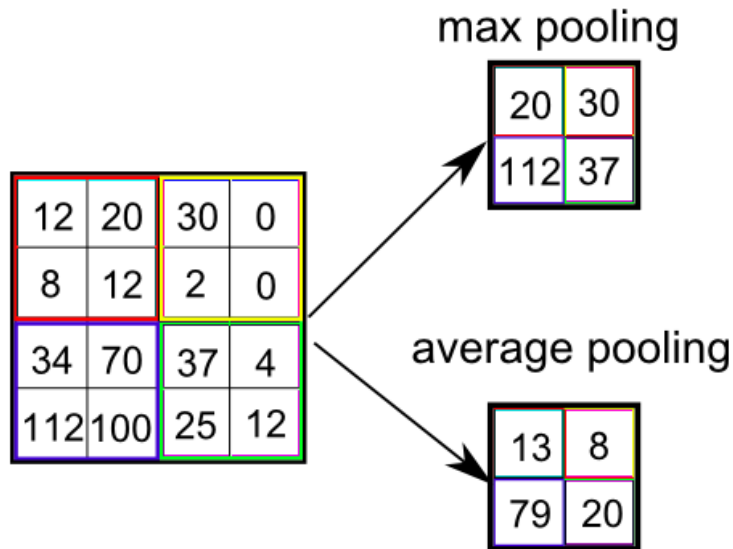
$$O_{22} = F_{11}X_{22} + F_{12}X_{23} + F_{21}X_{32} + F_{22}X_{33}$$

- Details:
- <https://www.slideshare.net/EdwinEfranJimnezLepe/example-feedforward-backpropagation>
- <https://medium.com/@2017csm1006/forward-and-backpropagation-in-convolutional-neural-network-4dfa96d7b37e>

Pooling

e.g. kernel size = 2, stride = 2 for both width and height.

The kernel size for pooling can be an even number.



CNN Structures

Image Classification

Image Classification



Convolutional
Unit



Fully-connected
Or Linear Layer



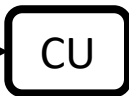
Down-sampling
Unit



Global Avg.
Pooling



28 x 28
= $[28]^2$



$[28]^2$



$[14]^2$



$[14]^2$



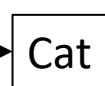
$[7]^2$



$[7]^2$



$[1]^2$



Convolutional Unit (CU) - VGG

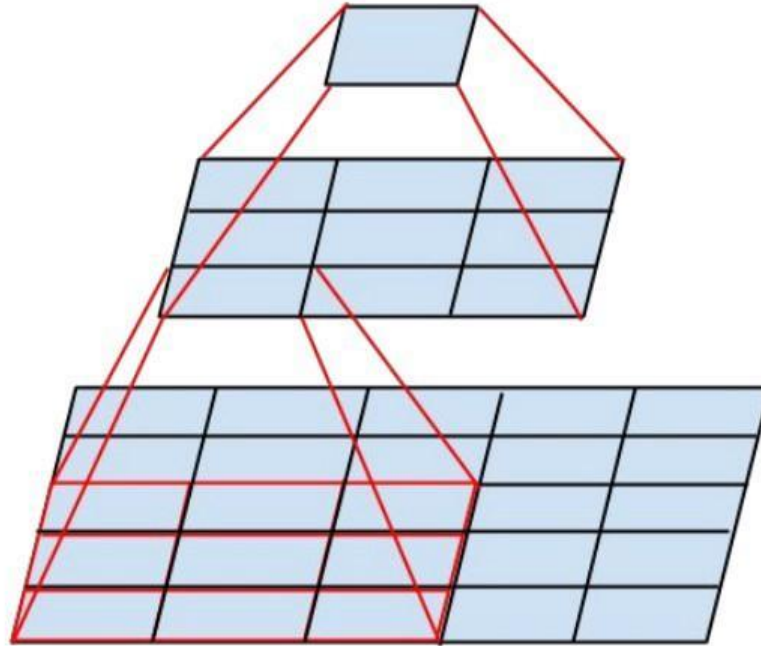
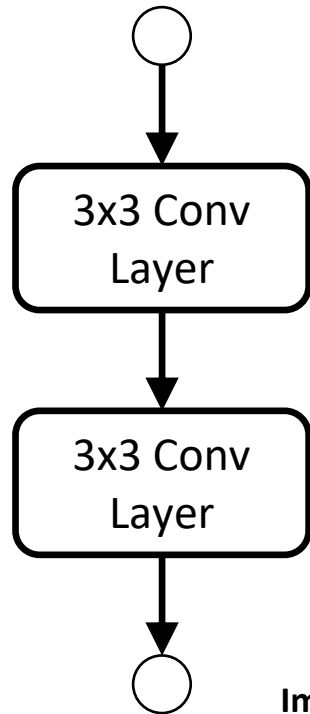
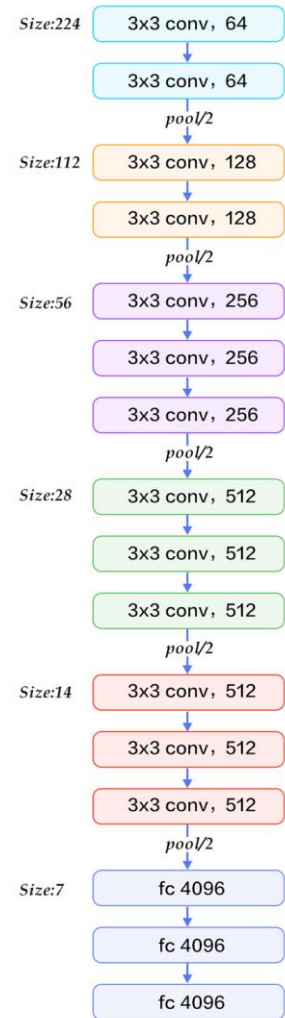
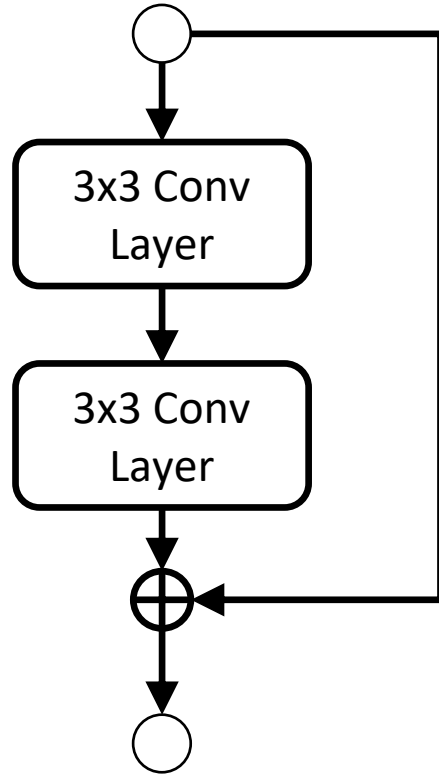


Image Source (Inception): Szegedy, Christian, et al. "Rethinking the inception architecture for computer vision." *CVPR*. 2016.

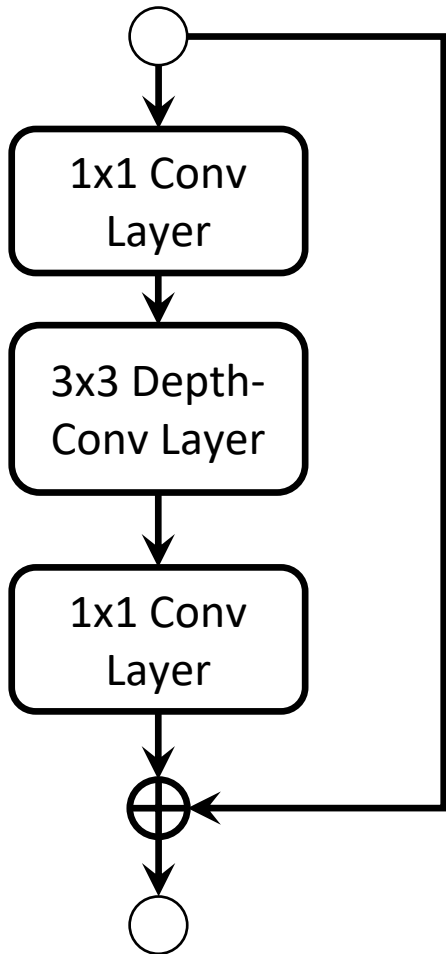


Basic Block in ResNet



ResNet: He, Kaiming, et al. "Deep residual learning for image recognition." CVPR. 2016.

- Residual Connection
- Element-wise addition of input and output
- Improves gradient flow and accuracy
- In ResNet-18 and ResNet-34
- Still computationally expensive
 - Hard to train very deep networks (> 100 layers)



Bottleneck in ResNet

- Used in ResNet-50, ResNet-101, ResNet-152, etc...
- Computationally Efficient

Influence:

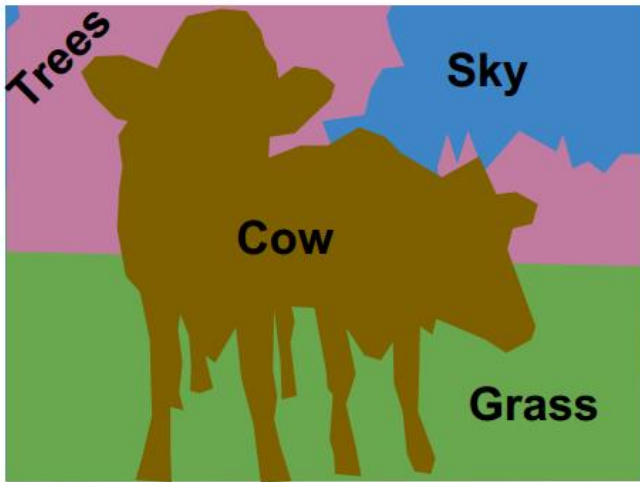
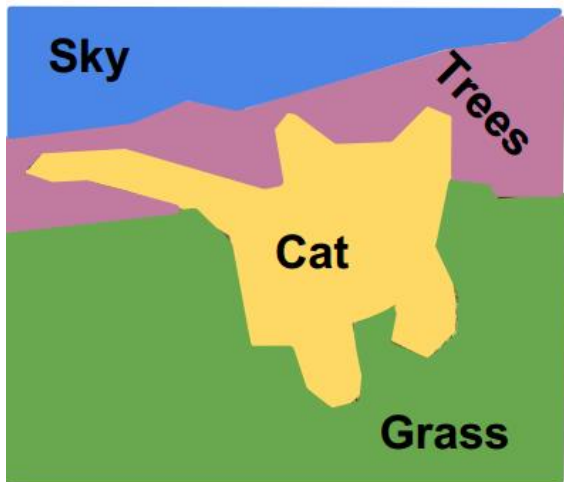
- Bottleneck unit with Depth-wise convs
 - MobileNetv2
 - ShuffleNetv2
- **MobileNetv2:** Sandler, Mark, et al. "Mobilenetv2: Inverted residuals and linear bottlenecks." CVPR, 2018.
- **ShuffleNetv2:** Ma, Ningning, et al. "Shufflenet v2: Practical guidelines for efficient cnn architecture design." ECCV, 2018.

CNN Structures

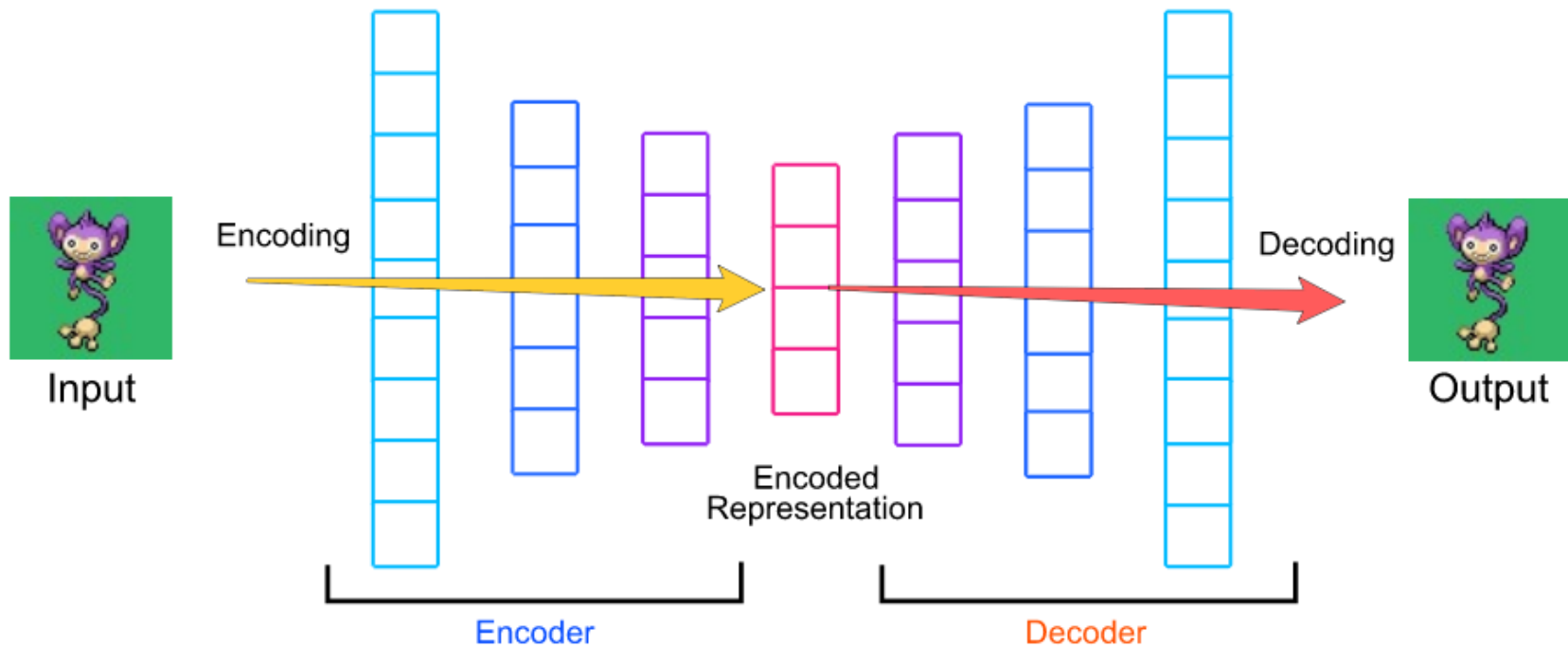
Semantic Segmentation



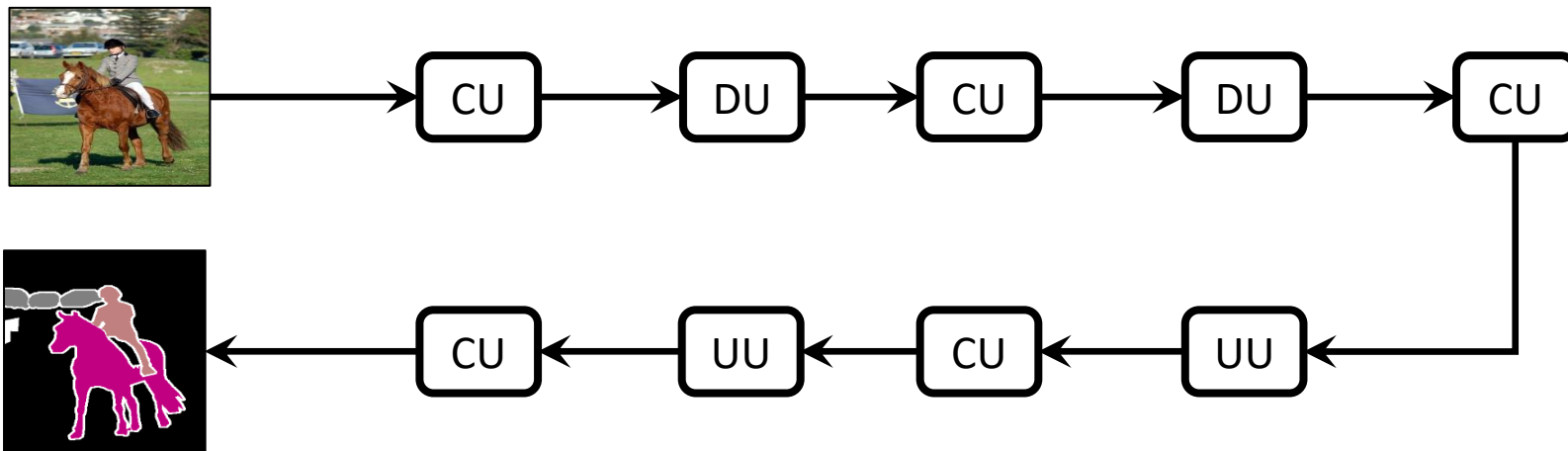
This image is [CC0 public domain](#)



Encoder-Decoder



Encoder-Decoder in Semantic Segmentation



Up-sampling
Unit



Convolutional
Unit



Fully-connected
Or Linear Layer

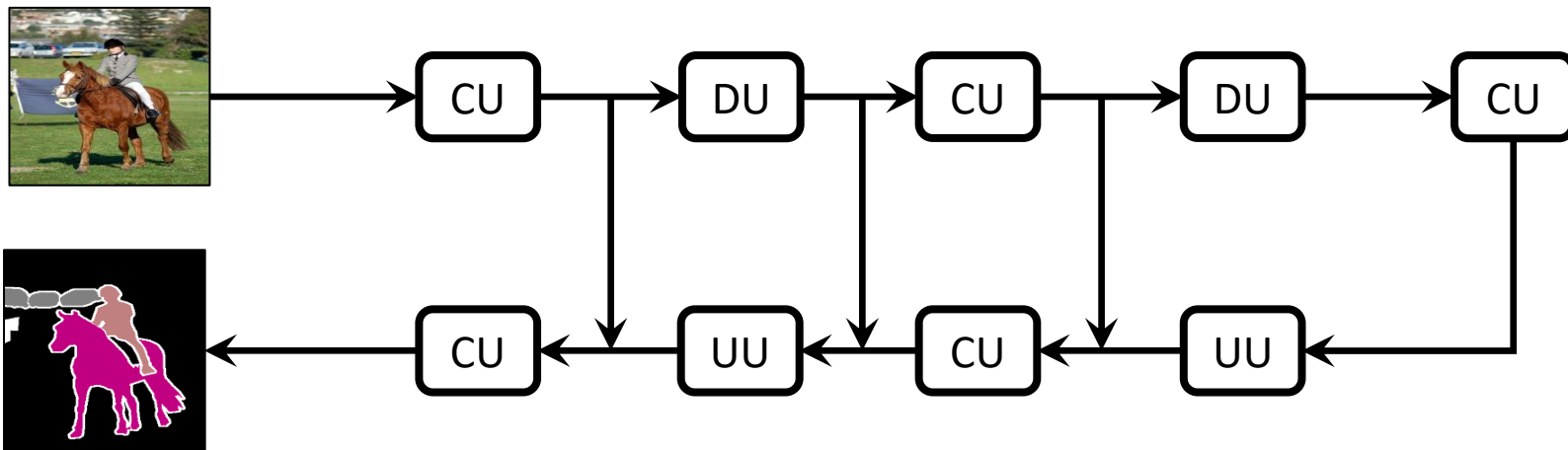


Down-sampling
Unit



Global Avg.
Pooling

U-Net



UU Up-sampling Unit

CU Convolutional Unit


FC Fully-connected Or Linear Layer

DU Down-sampling Unit

GAP Global Avg. Pooling

Deep Learning Libraries

 mxnet


TensorFlow

theano

 scikit
learn

 Caffe2

 Keras

PYTORCH

Homework 6

Homework 6

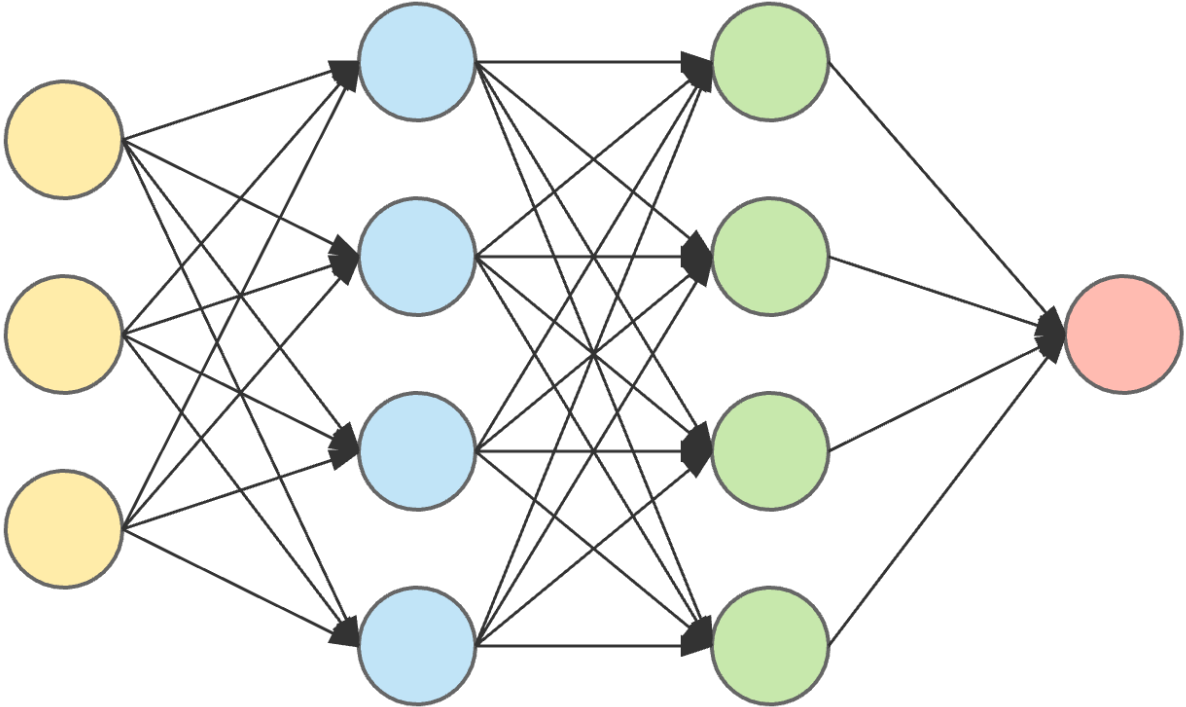
Convolutional Neural Networks

In PyTorch

(Optional Homework)

Due: June/4

Neural Network (Q1)



input layer

hidden layer 1

hidden layer 2

output layer

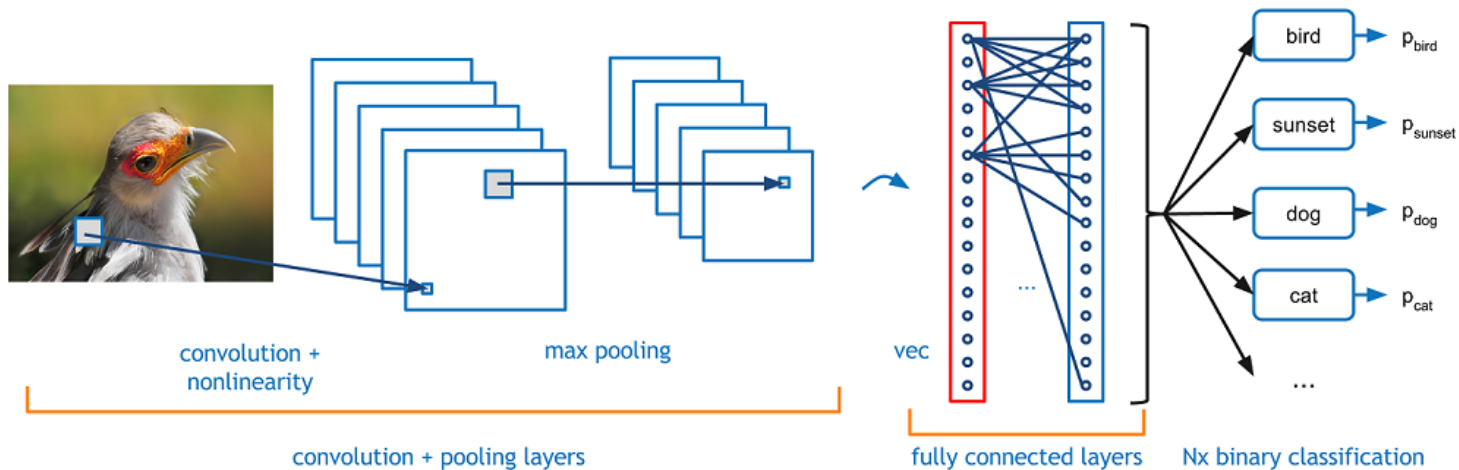
Convolutional Neural Network (Q2)

Conv

Pool

FC

Cross Entropy



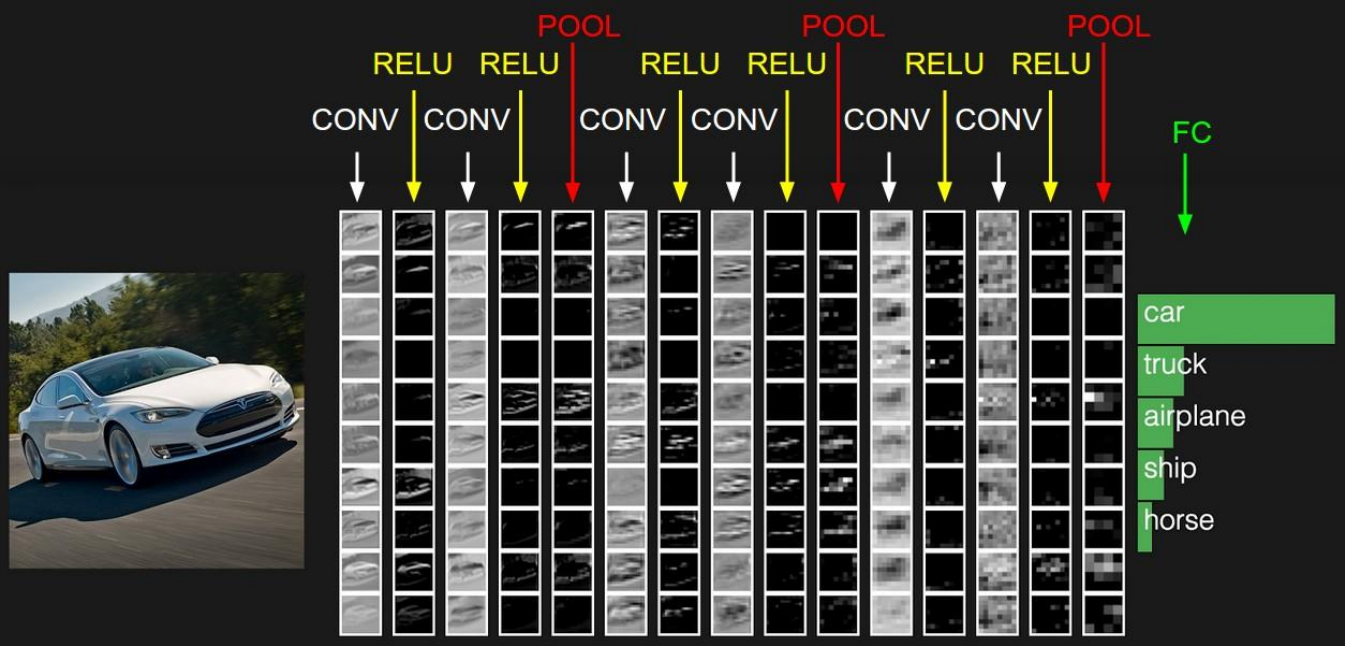
Yellow or Blue?



Color Normalization (Q3)



Deep Convolutional Neural Network (Q4)



Make the Design More Flexible

Input:

[8, 16, 32, "pool"]

Layer	Output Size	Output Channels
Input	30 x 30	3
Conv	28 x 28	8
ReLU	28 x 28	8
Conv	26 x 26	16
ReLU	26 x 26	16
Conv	24 x 24	32
ReLU	24 x 24	32
Max Pool	12 x 12	32
Linear	5	

Data Augmentation (Q5)

Random Affine Transformation



Data augmentation

