In-order vs. Out-of-order Execution

In-order instruction execution

- instructions are fetched, executed & committed in compilergenerated order
 - if one instruction stalls, all instructions behind it stall
- instructions are statically scheduled by the hardware
 - · scheduled in compiler-generated order
 - how many of the next n instructions can be issued, where n is the superscalar issue width
 - superscalars can have structural & data hazards within the n instructions
- advantage of in-order instruction scheduling: simpler implementation
 - > faster clock cycle
 - fewer transistors
 - > lower power
 - > faster design/development/debug time

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In-order vs. Out-of-order Execution

Out-of-order instruction execution

- · instructions are fetched in compiler-generated order
- instruction commit is in-order (today) or out-of-order (older computers)
- · in between they may be executed in some other order
- instructions are dynamically scheduled by the hardware
 - · hardware decides in what order instructions can be executed
 - instructions behind a stalled instruction can pass it if not dependent upon it
- · advantages: higher performance
 - · better at hiding latencies, less processor stalling
 - · higher utilization of functional units

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In-order instruction issue: Alpha 21164

2 styles of static instruction scheduling

- dispatch buffer & instruction slotting (Alpha 21164)
- shift register model (UltraSPARC-1)

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In-order instruction issue: Alpha 21164

Instruction slotting

- · can issue up to 4 instructions
 - · completely empty the instruction buffer before filling it again
 - compiler can pad with nops so a conflicting instruction is issued with the following instructions, not alone

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21164 Instruction Unit Pipeline

Fetch & issue

S0: instruction fetch

branch prediction bits read

S1: opcode decode

target address calculation

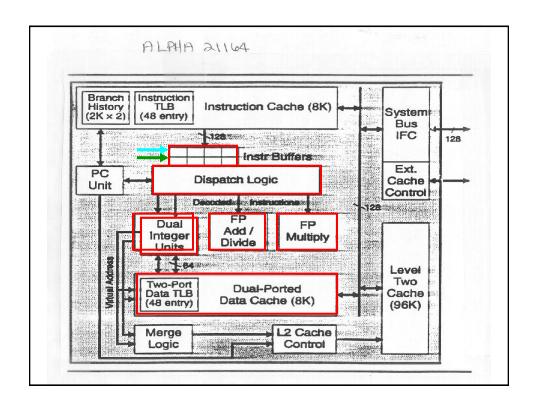
if predict taken, redirect the fetch

- **S2:** instruction slotting: decide which of the next 4 instructions can be issued
 - · intra-cycle structural hazard check
 - intra-cycle data hazard check
- S3: instruction dispatch
 - inter-cycle load-use hazard check
 - · register read

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In-order instruction issue: UltraSparc 1

Shift register model

- · can issue up to 4 instructions per cycle
- · shift in new instructions after every group of instructions is issued

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Code Scheduling on Superscalars

Original code

```
Loop: lw R1, 0 (R5)
addu R1, R1, R6
sw R1, 0 (R5)
addi R5, R5, -4
bne R5, R0, Loop
```

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Code Scheduling on Superscalars

Original code With load-latency-hiding code

Loop: lw R1, 0 (R5) Loop: lw R1, 0 (s1)
addu R1, R1, R6
sw R1, 0 (R5) addu R5, R5, -4
addu R1, R1, R6
addu R5, R5, -4
bne R5, R0, Loop bne R5, \$0, Loop

| | ALU/branch instructions | memory instructions | clock cycle |
|-------|-------------------------|---------------------|-------------|
| Loop: | | | 1 |
| | | | 2 |
| | | | 3 |
| | | | 4 |

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Code Scheduling on Superscalars: Loop Unrolling

| | ALU/branch instruction | Data transfer instruction | clock cycle |
|-------|------------------------|---------------------------|-------------|
| Loop: | addi R5, R5, -16 | lw R1, 0(R5) | 1 |
| | | lw R2, 12(R5) | 2 |
| | addu R1, R1, R6 | lw R3, 8(R5) | 3 |
| | addu R2, R2, R6 | lw R4, 4(R5) | 4 |
| | addu R3, R3, R6 | sw R1, 16(R5) | 5 |
| | addu R4, R4, R6 | sw R2, 12(R5) | 6 |
| | | sw R3, 8(R5) | 7 |
| | bne R5, R0, Loop | sw R4, 4(R5) | 8 |

What is the cycles per iteration? What is the IPC?

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| Code Scheduling on Superscalars: Loop Unrolling | | | | | |
|---|--------------------------------------|----|--|--|--|
| Advantages: + | | | | | |
| + | | | | | |
| Disadvantages: | | | | | |
| - | | | | | |
| - | | | | | |
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