

#### Comparison

- ML (Maximum Likelihood): P(H) = 0.5 after 10 experiments (HTH<sup>8</sup>): P(H) = 0.9
- MAP (Maximum A Posteriori): P(H) = 0.9 after 10 experiments (HTH<sup>8</sup>): P(H) = 0.9
- Bayesian: P(H) = 0.68after 10 experiments (HTH<sup>8</sup>): P(H) = 0.9

#### Comparison

- ML (Maximum Likelihood):
- MAP (Maximum A Posteriori):

#### • Bayesian:

- Minimizes error => great when data is scarce
- Potentially much harder to compute

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  - Still easy to compute
  - Incorporates prior knowledge
- Bayesian:
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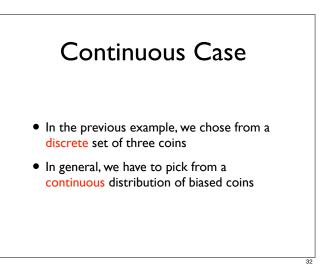
### Summary For Now

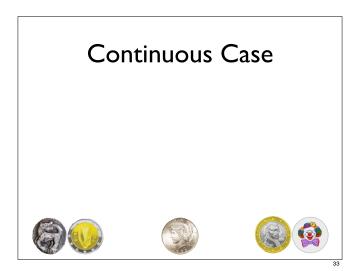
- Prior:
- Uniform Prior:
- Posterior:
- Likelihood:

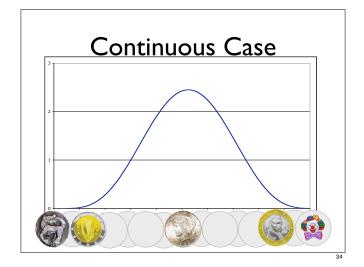
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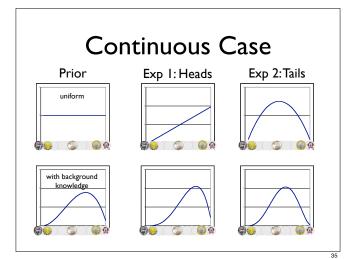
- **Prior**: Probability of a hypothesis before we see any data
- Uniform Prior: A prior that makes all hypothesis equaly likely
- **Posterior**: Probability of a hypothesis after we saw some data
- Likelihood: Probability of data given hypothesis

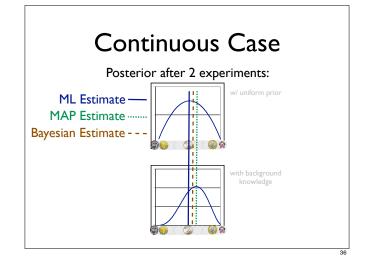
	Prior	Hypothesis
Maximum Likelihood Estimate	Uniform	The most likely
Maximum A Posteriori Estimate	Any	The most likely
Bayesian Estimate	Any	Weighted combination

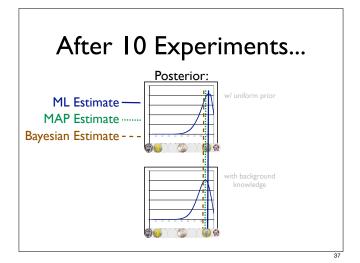


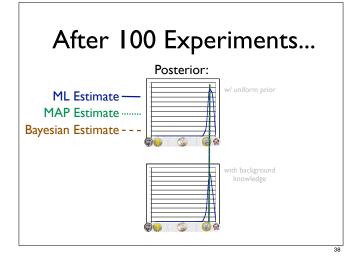


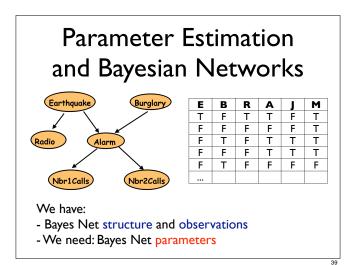


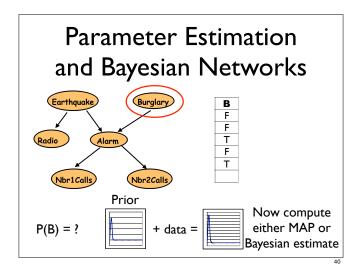


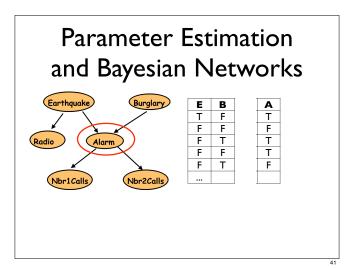


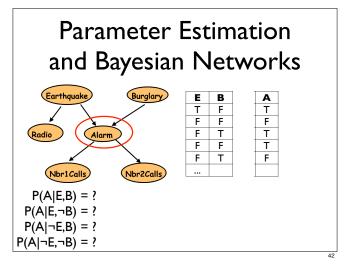


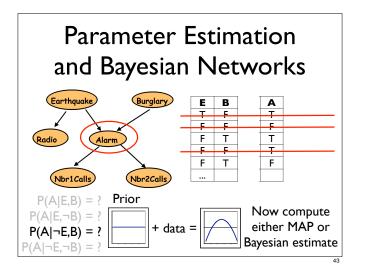


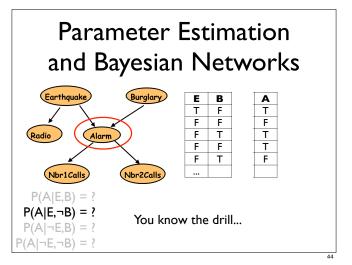




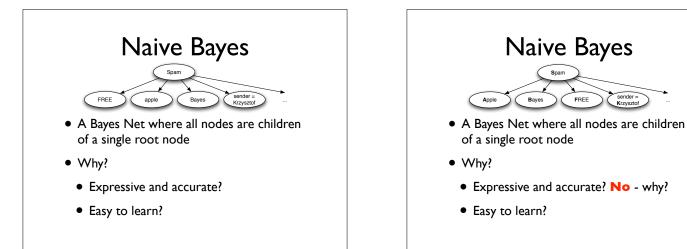


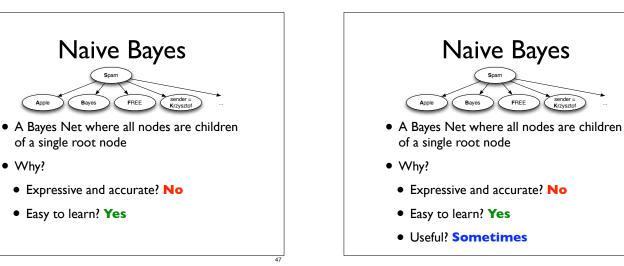


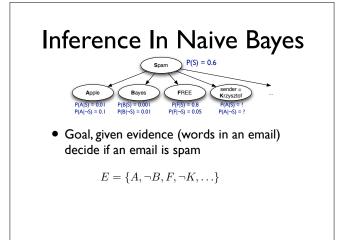


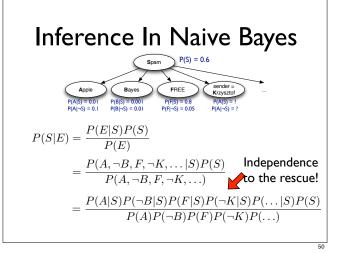


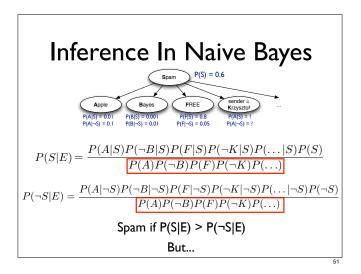
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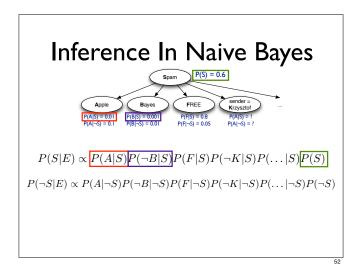


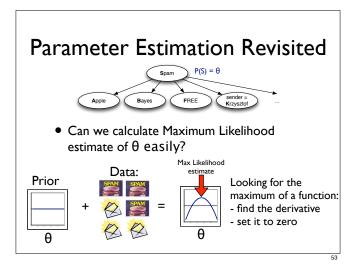


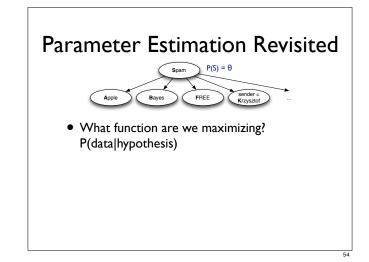


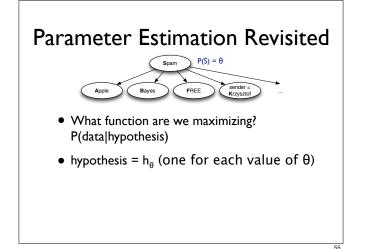








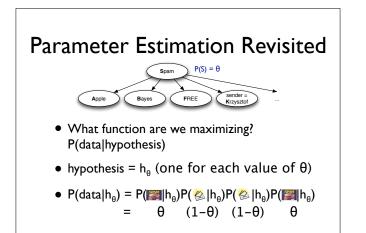


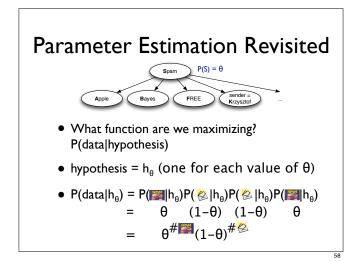


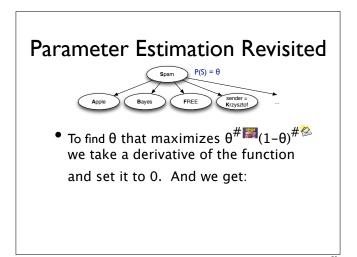
#### Parameter Estimation Revisited

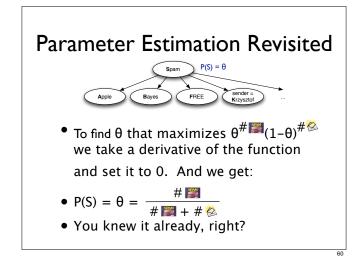


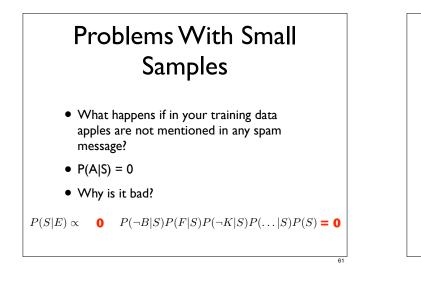
- What function are we maximizing? P(data|hypothesis)
- hypothesis =  $h_{\theta}$  (one for each value of  $\theta$ )
- $P(data|h_{\theta}) = P(\underline{m}|h_{\theta})P(\underline{\otimes}|h_{\theta})P(\underline{\otimes}|h_{\theta})P(\underline{m}|h_{\theta})$

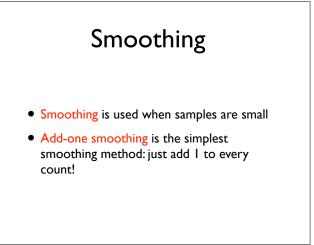


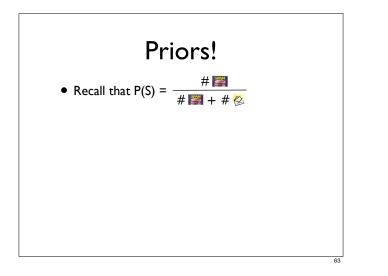


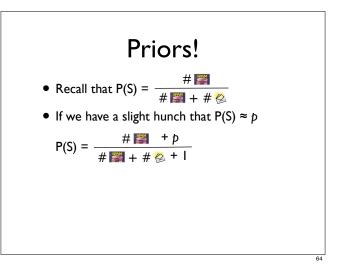


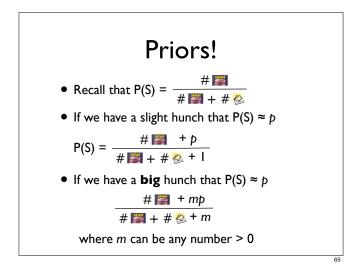


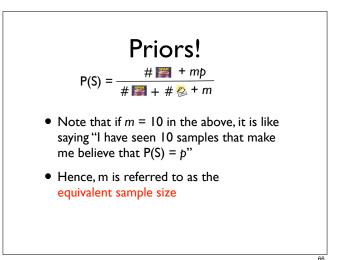


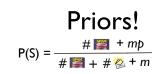












- Where should *p* come from?
- No prior knowledge => p=0.5
- If you build a personalized spam filter, you can use p = P(S) from some body else's filter!

#### Inference in Naive Bayes Revisited

• Recall that

 $P(S|E) \propto P(A|S)P(\neg B|S)P(F|S)P(\neg K|S)P(\ldots|S)P(S)$ 

Is there any potential for trouble here?

#### Inference in Naive Bayes Revisited

• Recall that

 $P(S|E) \propto P(A|S)P(\neg B|S)P(F|S)P(\neg K|S)P(\ldots|S)P(S)$ 

- We are multiplying lots of small numbers together => danger of underflow!
- Solution? Use logs!

#### Inference in Naive Bayes Revisited

 $log(P(S|E)) \propto log(P(A|S)P(\neg B|S)P(F|S)P(\neg K|S)P(\ldots |S)P(S))$ 

 $\propto log(P(A|S)) + log(P(\neg B|S)) + log(P(F|S)) + log(P(\neg K|S)) + log(P(\ldots |S)) + log(P(S)))$ 

• Now we add "regular" numbers -- little danger of over- or underflow errors!

### Learning The Structure of Bayesian Networks

- General idea: look at all possible network structures and pick one that fits observed data best
- Impossibly slow: exponential number of networks, and for each we have to learn parameters, too!
- What do we do if searching the space exhaustively is too expensive?

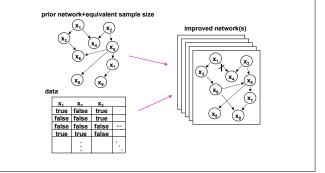
# Learning The Structure of Bayesian Networks

- Local search!
  - Start with some network structure
  - Try to make a change (add, delete or reverse node)
  - See if the new network is any better

### Learning The Structure of Bayesian Networks

- What network structure should we start with?
  - Random with uniform prior?
  - Networks that reflects our (or experts') knowledge of the field?

## Learning The Structure of Bayesian Networks



# Learning The Structure of Bayesian Networks

- We have just described how to get an ML or MAP estimate of the structure of a Bayes Net
- What would the Bayes estimate look like?
  - Find all possible networks
  - Calculate their posteriors
  - When doing inference: result weighed combination of all networks!