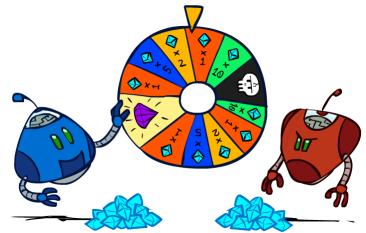
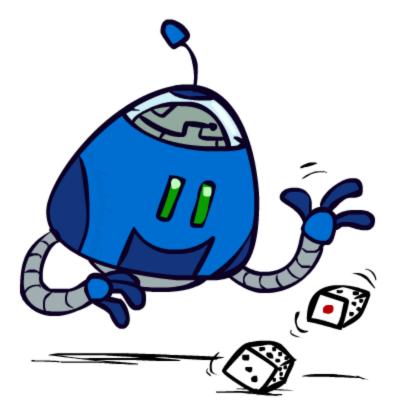
# CSE 473: Introduction to Artificial Intelligence

### Hanna Hajishirzi Expectimax – Complex Games

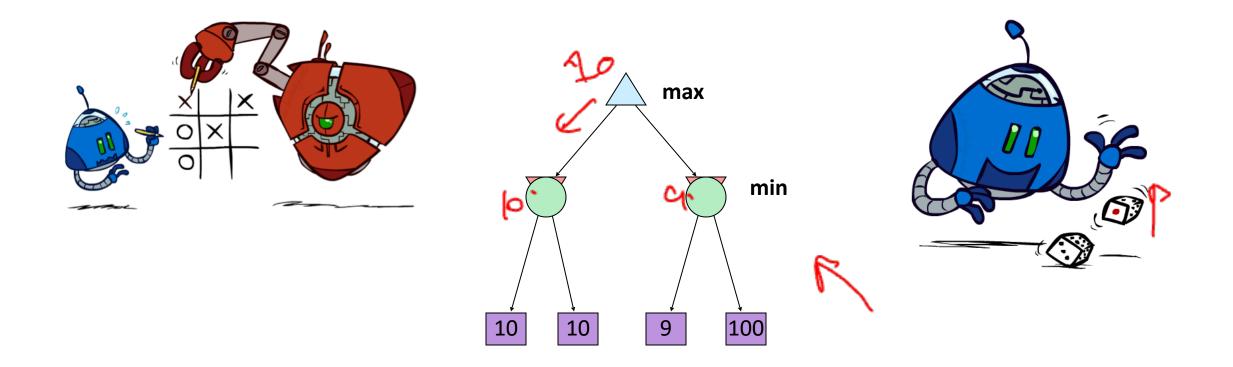
slides adapted from Dan Klein, Pieter Abbeel ai.berkeley.edu And Dan Weld, Luke Zettlemoyer



### **Uncertain Outcomes**

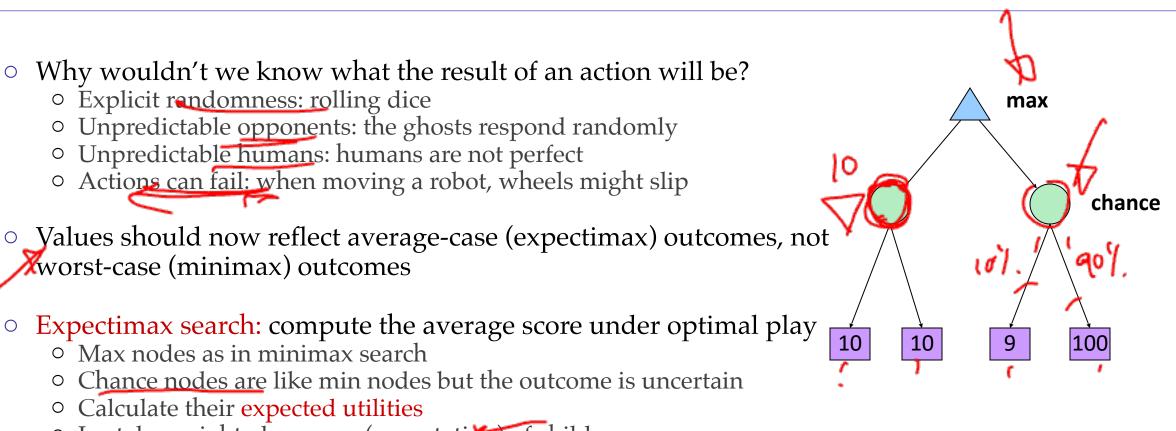


# Worst-Case vs. Average Case



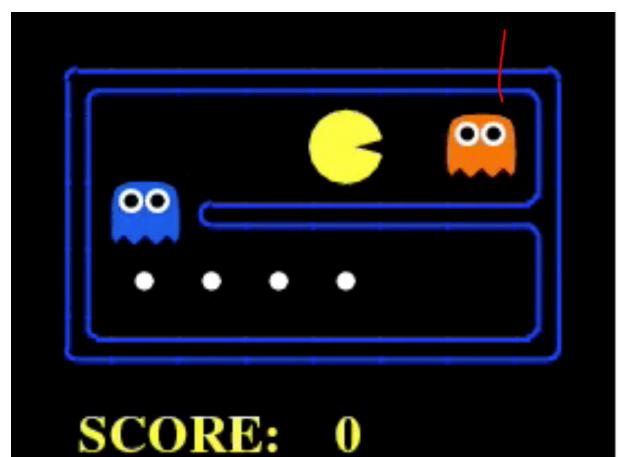
Idea: Uncertain outcomes controlled by chance, not an adversary!

# Expectimax Search



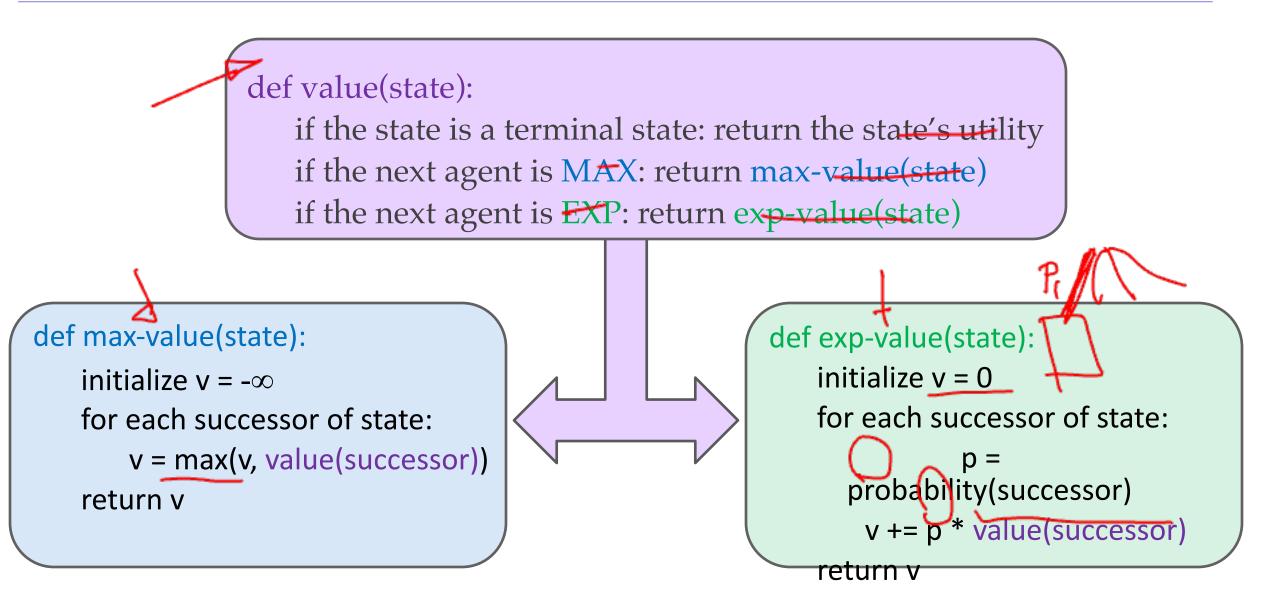
- I.e. take weighted average (expectation) of children
- Later, we'll learn how to formalize the underlying uncertain-result problems as Markov Decision Processes

# Video of Demo Min vs. Exp (Min)

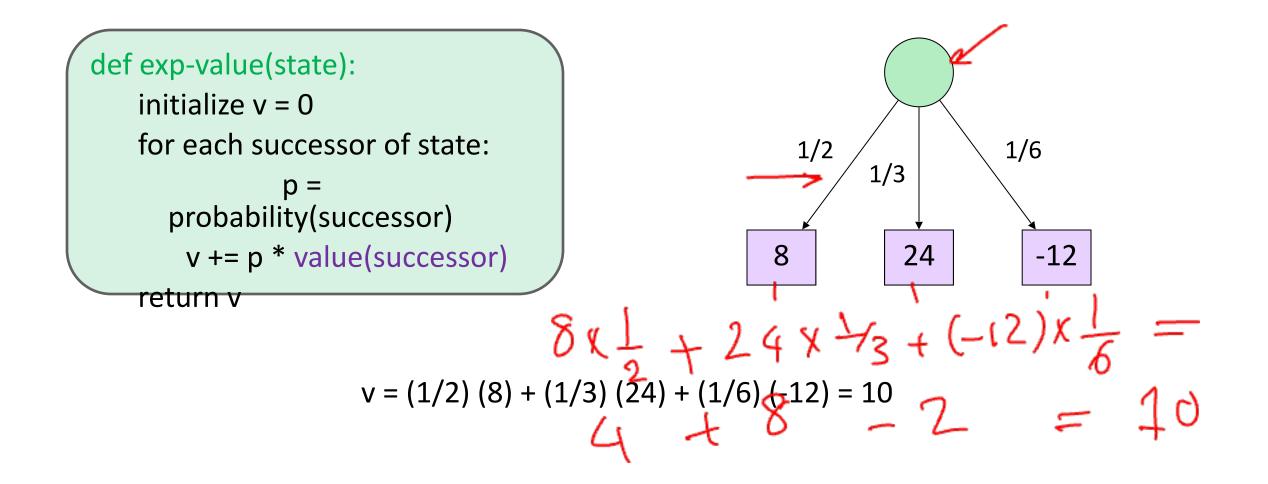




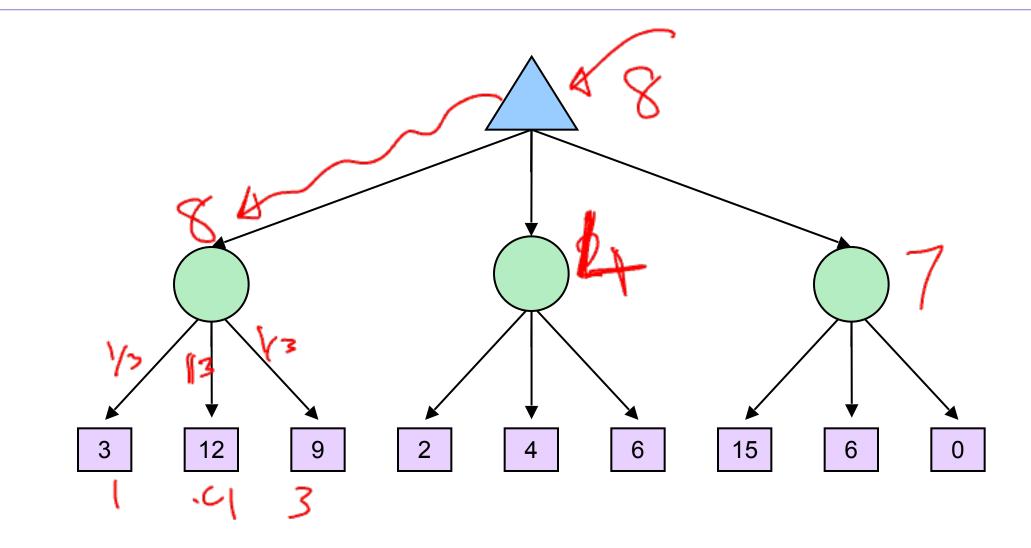
# Expectimax Pseudocode



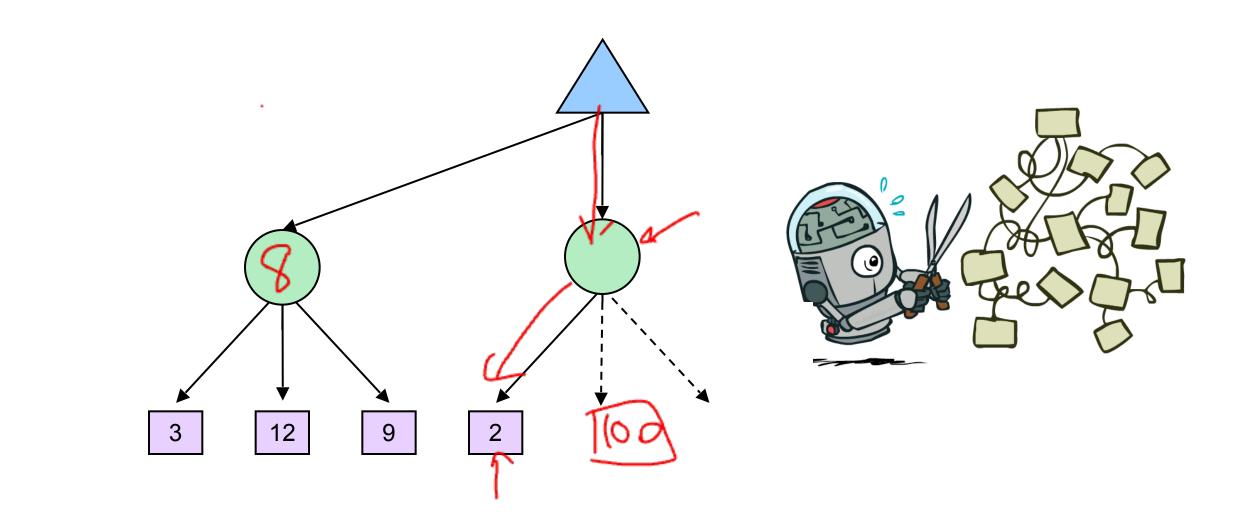
# Expectimax Pseudocode



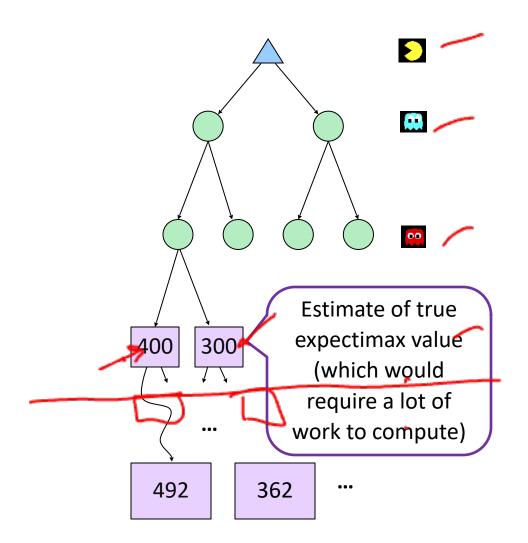
# Expectimax Example



# Expectimax Pruning?



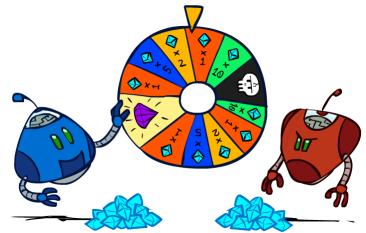
# Depth-Limited Expectimax

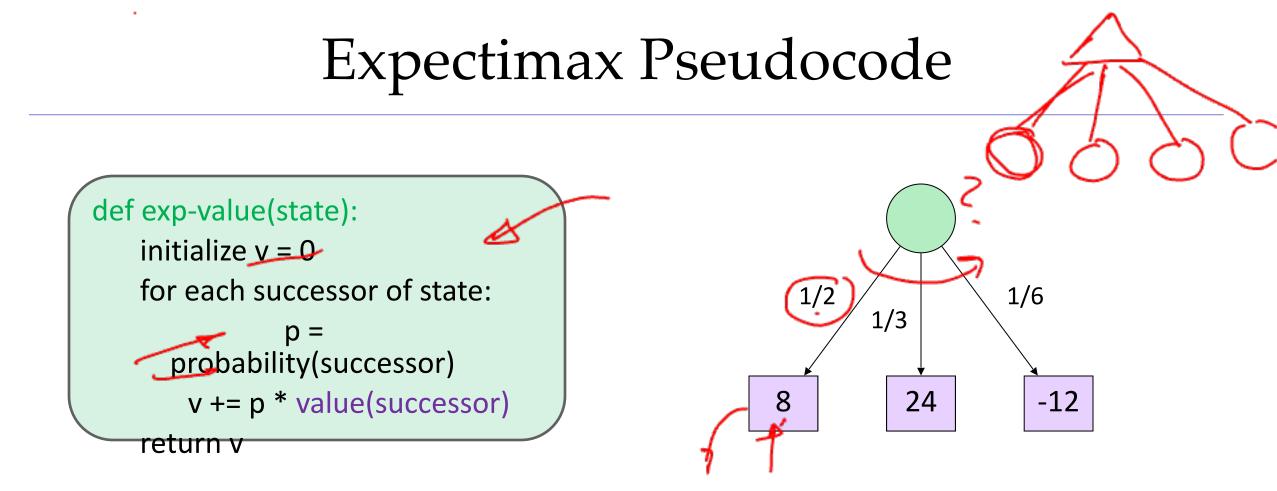


# CSE 473: Introduction to Artificial Intelligence

### Hanna Hajishirzi Expectimax – Complex Games

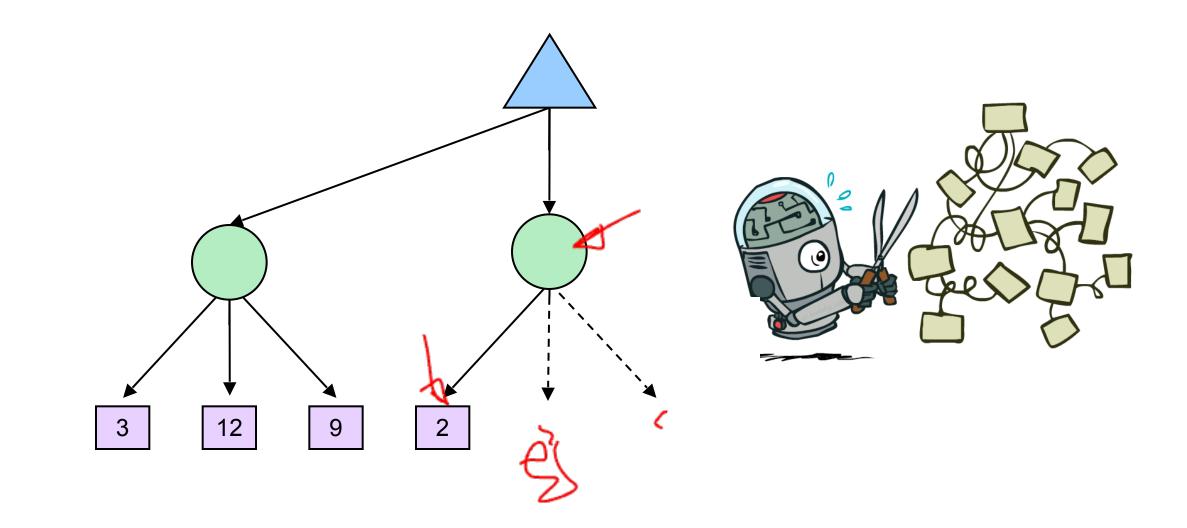
slides adapted from Dan Klein, Pieter Abbeel ai.berkeley.edu And Dan Weld, Luke Zettlemoyer



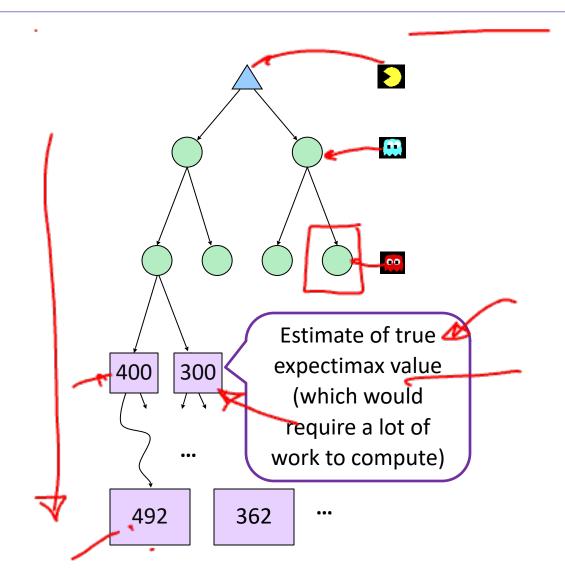


v = (1/2) (8) + (1/3) (24) + (1/6) (-12) = 10

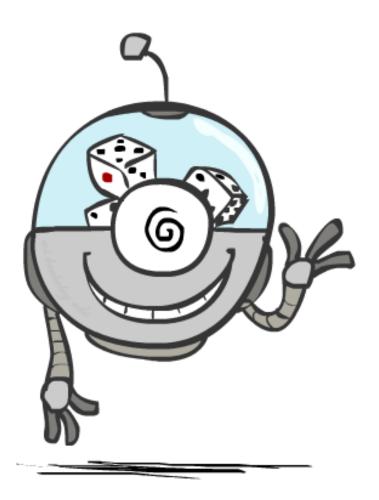




# Depth-Limited Expectimax



# Probabilities



# Reminder: Probabilities

A random variable represents an event whose outcome is unknown
 A much ability distribution is an excision part of successful to the successful to th

- A probability distribution is an assignment of weights to outcomes
- Example: Traffic on freeway
  - Random variable **T** whether there's traffic
  - Outcomes: T in {none, light, heavy}
  - Distribution: P(T=none) = 0.25, P(T=light) 0.50, P(T=heavy) = 0.25

#### Some laws of probability (more later):

- Probabilities are always non-negative
- Probabilities over all possible outcomes sum to one
- As we get more evidence, probabilities may change:
  - P(T=heavy) = 0.25, P(T=heavy | Hour=8am) = 0.60
  - We'll talk about methods for reasoning and updating probabilities later









0.25



# **Reminder: Expectations**

30 min

Х

0.50

Ч С

35 min

60 min

0.25

- The expected value of a function of a random variable i the average, weighted by the probability distribution or outcomes
- Example: How long to get to the airport?

20 min

Х

0.25

Time:

Probability:

# What Probabilities to Use?

- In expectimax search, we have a probabilist model of how the opponent (or environment) behave in any state
  - Model could be a simple uniform distribution (roll a
  - Model could be sophisticated and require a great deal computation
  - We have a chance node for any outcome out of our control: opponent or environment
  - The model might say that adversarial actions are likely!
- For now, assume each chance node magically comes along with probabilities that specify the distribution over its outcomes

Having a probabilistic belief about another agent's action does not mean that the agent is flipping any coins!

 $\mathbf{\Sigma}$ 

00

 $\mathbf{\Sigma}$ 

# Quiz: Informed Probabilities

 Let's say you know that your opponent is actually running a depth 2 minimax, using the result 80% of the time, and moving randomly otherwise

• Question: What tree search should you use?

0.9

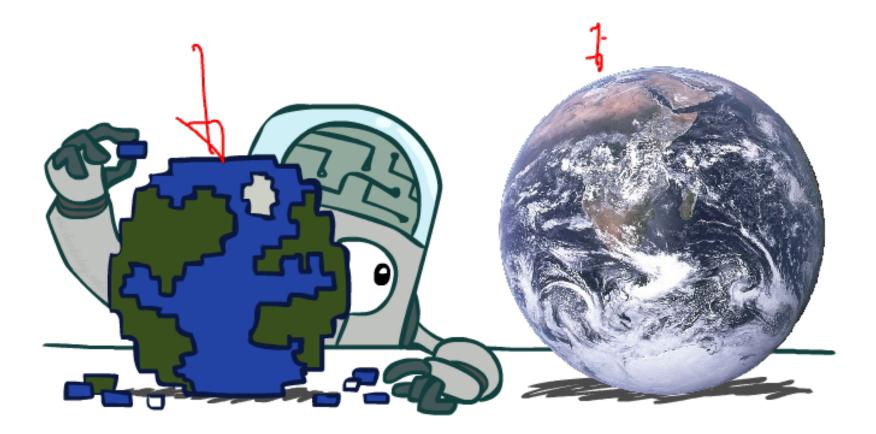
a180%

Expectimenc

Answer: Expectimax!

- To figure out EACH chance node's probabilities, you have to run a simulation of your opponent
- This kind of thing gets very slow very quickly
- Even worse if you have to simulate your opponent simulating you...
- … except for minimax and maximax, which have the nice property that it all collapses into one game tree

# Modeling Assumptions



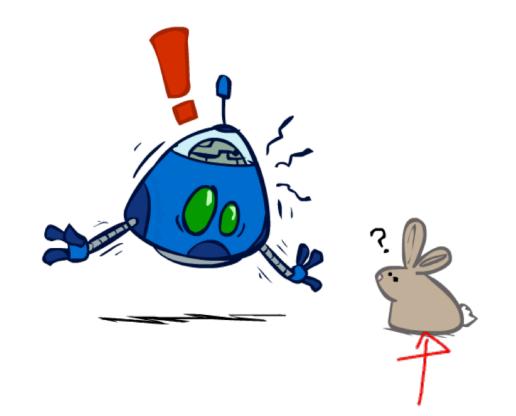
# The Dangers of Optimism and Pessimism

Dangerous Optimism Assuming chance when the world is adversarial

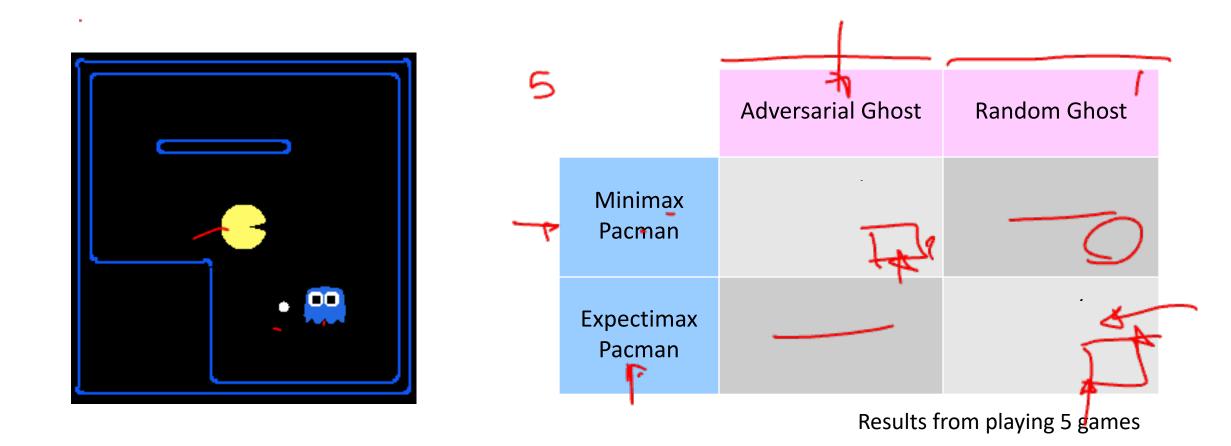


#### Dangerous Pessimism

Assuming the worst case when it's not likely



# Assumptions vs. Reality



Pacman used depth 4 search with an eval function that avoids trouble Ghost used depth 2 search with an eval function that seeks Pacman

#### Video of Demo World Assumptions Random Ghost – Expectimax Pacman



#### Video of Demo World Assumptions Adversarial Ghost – Minimax Pacman



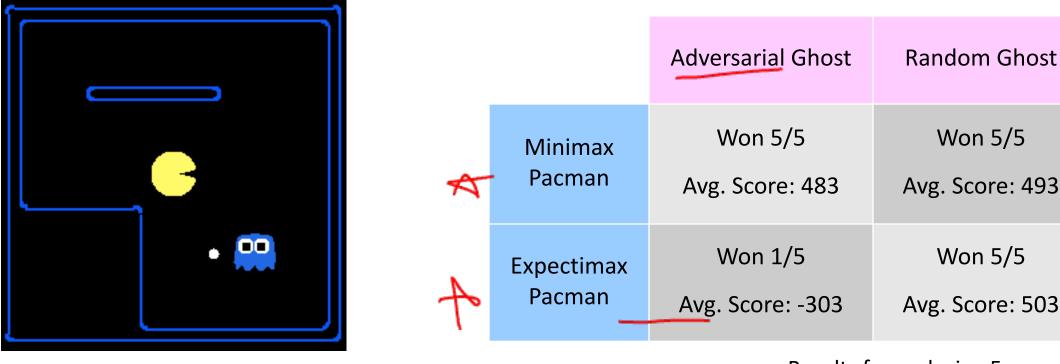
#### Video of Demo World Assumptions Random Ghost – Minimax Pacman



#### Video of Demo World Assumptions Adversarial Ghost – Expectimax Pacman



# Assumptions vs. Reality



Results from playing 5 games

Pacman used depth 4 search with an eval function that avoids trouble Ghost used depth 2 search with an eval function that seeks Pacman

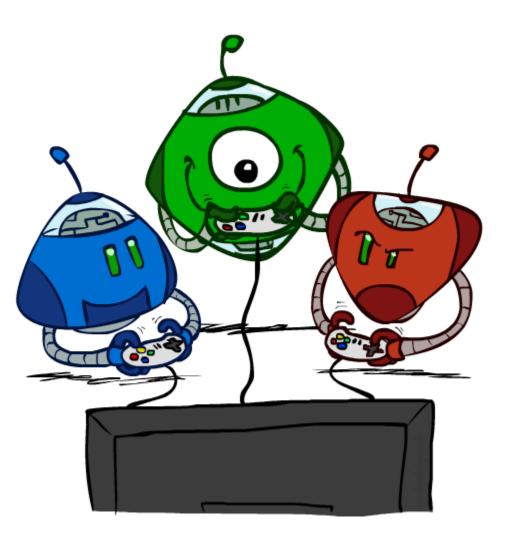
# Why not minimax?

• Worst case reasoning is too conservative

• Need average case reasoning

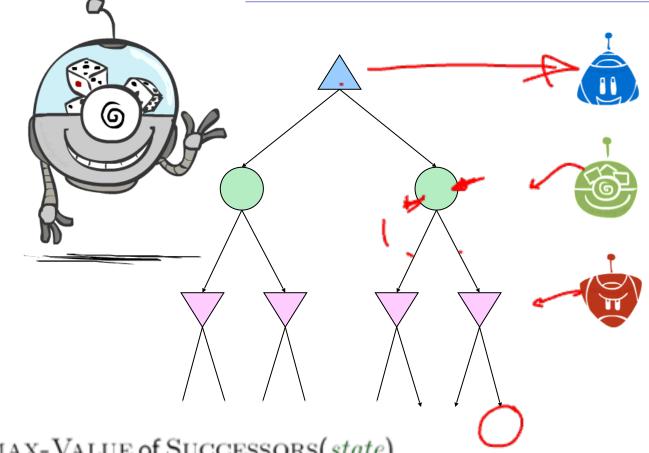


# Other Game Types



# Mixed Layer Types

- E.g. Backgammon
- Expecti-minimax
  - Environment is an extra "random agent" player that moves after each min/max agent
  - Each node computes the appropriate combination of its children



if state is a MAX node then
 return the highest EXPECTIMINIMAX-VALUE of SUCCESSORS(state)
if state is a MIN node then
 return the lowest EXPECTIMINIMAX-VALUE of SUCCESSORS(state)
if state is a chance node then
 return average of EXPECTIMINIMAX-VALUE of SUCCESSORS(state)

# Example: Backgammon

- Dice rolls increase *b*: 21 possible rolls with 2 dice
  - Backgammon  $\approx 20$  legal moves
  - Depth 2 =  $20 \times (21 \times 20)^3 = 1.2 \times 10^9$
- As depth increases, probability of reaching a given search node shrinks
  - So usefulness of search is diminished
  - So limiting depth is less damaging
  - But pruning is trickier...
- Historic AI: TDGammon uses depth-2 search + very good evaluation function + reinforcement learning:
   world-champion level play
- 1<sup>st</sup> AI world champion in any game!





### **Multi-Agent Utilities**

61

7,1,2

5,6,6

<mark>6,1,</mark>2

61,12

**7,2,**1

**5,1,7** 

5,2,5

5,157

**1,5,**2

7,7,1

5,2,5

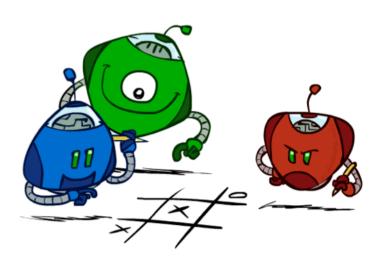
**5,2,**5

• What if the game is not zero-sum, or has multiple players?

1,6,6

**1,6**,6

- Generalization of minimax:
  - Terminals have utility tuples
  - Node values are also utility tuples
  - Each player maximizes its own component
  - Can give rise to cooperation and competition dynamically...

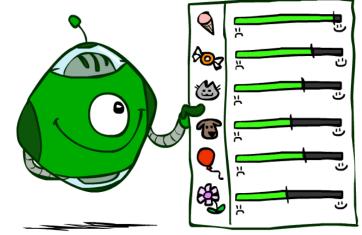


# Utilities

• Utilities: values that we assign to every state

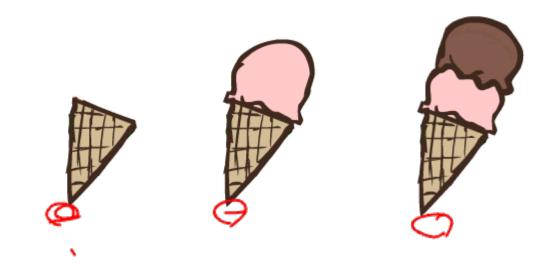
- Why should we average utilities? Why not minimax?
- Principle of maximum expected utility:
  - A rational agent should choose the action that maximizes its expected utility, given its knowledge





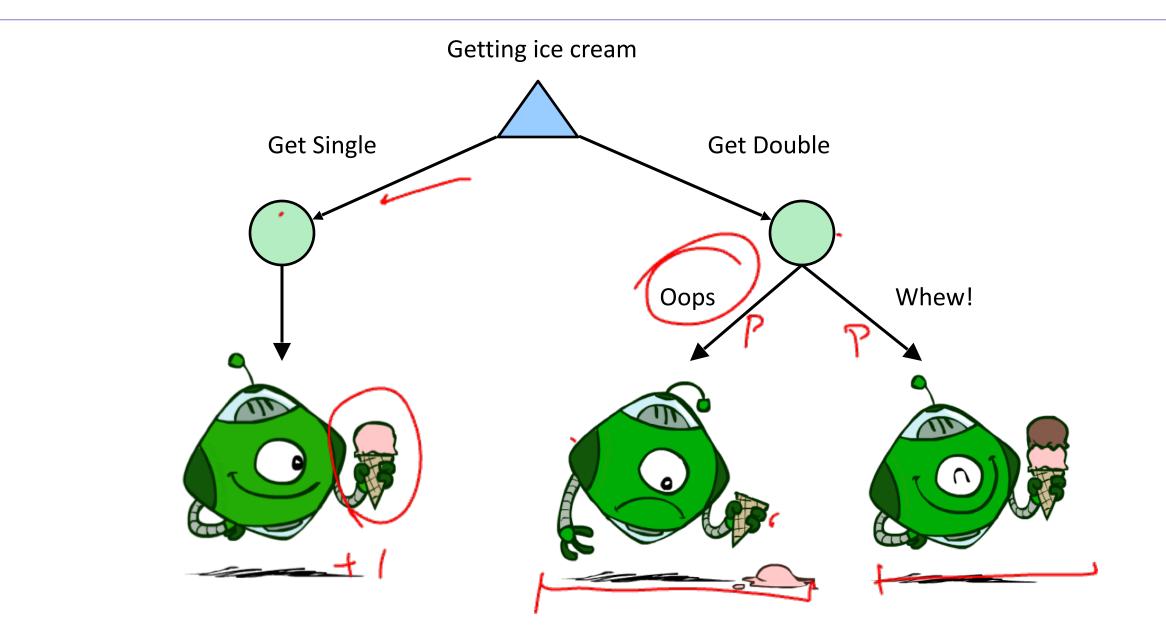
# Utilities

- Utilities are functions from outcomes (states of the world) to real numbers that describe an agent's preferences
- Where do utilities come from?
  - In a game, may be simple (+1/-1)
  - Utilities summarize the agent's goals

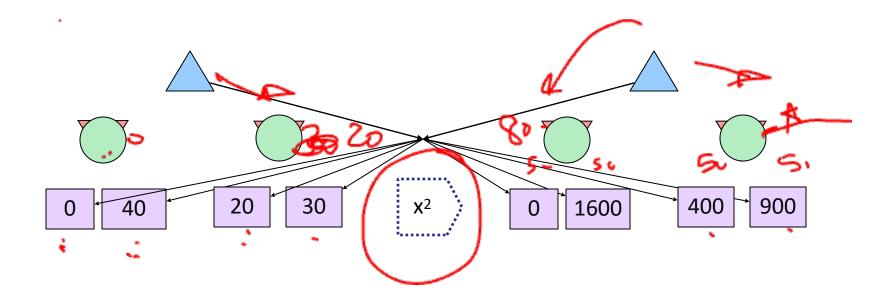


 We hard-wire utilities and let behaviors emerge

### Utilities: Uncertain Outcomes



# What Utilities to Use?



- For worst-case minimax reasoning, terminal function scale doesn't matter
   We just want better states to have higher evaluations (get the ordering right)
- For average-case expectimax reasoning, we need *magnitudes* to be meaningful

# **Review and Next Topics**

- Adversarial Games ·
  - Minimax search
  - α-β search
  - Evaluation functions
  - Multi-player, non-0-sum
  - Stochastic Games
    - Expectimax
    - Markov Decision Processes
    - Reinforcement Learning

