Pointer and Alias Analysis

Aliases:

two expressions that denote same mutable memory location

Introduced through

- pointers
- · call-by-reference
- · array indexing
- · C unions, Fortran common, equivalence

Applications of alias analysis:

- improved side-effect analysis: if assign to one expression, what other expressions are modified?
 - · if certain modified or not modified, not a problem
 - · if uncertain, things can get ugly
- eliminate redundant loads/stores & dead stores (CSE & dead assign elim, for pointer ops)
- automatic parallelization of code manipulating data structures

• ...

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Kinds of alias info

Points-to analysis

- at each program point, calculate set of p→x bindings, if p points to x
- · two variations:
 - may points-to: p might point to x
 - must points-to: p definitely points to x

Alias-pair analysis

- at each program point, calculate set of (expr₁,expr₂)
 pairs, if expr₁ and expr₂ reference the same memory
- may and must alias-pair versions
- + can handle aliasing of variables, unlike pts-to analysis
- potentially infinite number of alias pairs, so want the "minimal" set

Storage shape analysis

 at each program point, calculate an abstract description of the structure of pointers etc., e.g. list-like, or tree-like, or DAG-like, or ...

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A points-to analysis

At each program point, calculate set of $p \rightarrow x$ bindings, if p points to x

Outline:

- define may version first, then consider must version
- · develop algorithm in increasing stages of complexity
- · pointers only to vars of scalar type
- · add pointers to pointers
- · add pointers to and from structures
- · add pointers to dynamically-allocated storage
- · add pointers to array elements

May-point-to scalars

Domain: Pow($Var \times Var$)

- each variable may point to any number of other variables
- may-point-to_{PP}(P) = { $X \mid P \rightarrow X \in Soln(MayPT, PP)$ }

Forward flow functions:

$$\mathsf{MayPT}_{P} := {}_{\mathscr{E}X}(\mathsf{in}) = \mathsf{in} - \{P {\rightarrow}^*\} \cup \{P {\rightarrow} X\}$$

$$\mathsf{MayPT}_{P} := \mathcal{O}(\mathsf{in}) = \mathsf{in} - \{P \rightarrow^*\} \cup \{P \rightarrow Y \mid Q \rightarrow Y \in \mathsf{in}\}$$

$$\begin{aligned} \mathsf{MayPT}_{X} := {}^{\star_{\mathcal{P}}}(\mathsf{in}) = \mathsf{in} & (\mathsf{assuming} \ \mathcal{P} \ \mathsf{can't} \ \mathsf{point} \ \mathsf{to} \ \mathsf{a} \ \mathsf{ptr}) \\ \mathsf{MayPT}_{{}^{\star_{\mathcal{P}}}} := {}_{X}(\mathsf{in}) = \mathsf{in} & (\mathsf{assuming} \ \mathcal{P} \ \mathsf{can't} \ \mathsf{point} \ \mathsf{to} \ \mathsf{a} \ \mathsf{ptr}) \end{aligned}$$

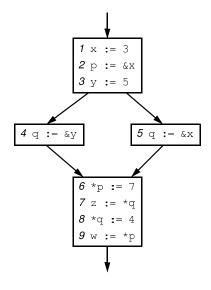
Meet function: union

What about nil?

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Example



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Must-point-to

How to define must-point-to analysis?

Option 1: analogous to may-point-to, but as must problem

· meet function: intersection

Option 2: interpretation of may-point-to results

• if P may point only to X, then P must point to X, i.e.,

must-point-to_{PP}(
$$P$$
) = { $X | \{X\} = may$ -point-to_{PP}(P) }

• what if P may point to nil? P assigned an integer?

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Using alias info

E.g. reaching definitions

At each program point, calculate set of $X \rightarrow S$ bindings, if X might get its definition from stmt S

Simple flow functions:

$$RD_{S:X} := ...(in) = in - \{X \rightarrow^*\} \cup \{X \rightarrow S\}$$

$$\mathsf{RD}_{\mathcal{S}:\,^{\star}P} := \dots (\mathsf{in}) = \mathsf{in} - \{X {\rightarrow}^{\star} \mid X \in \mathsf{must}\text{-point-to}(P)\}$$

$$\cup \{X {\rightarrow} \mathcal{S} \mid X \in \mathsf{may}\text{-point-to}(P)\}$$

Reaching "right hand sides"

A variation on reaching definitions that skips through trivial copies

 $X \rightarrow S$ in set if X might get its definition from rhs of stmt S, skipping through trivial variable and pointer copies where possible

Can use reaching right-hand sides to construct def/use chains that skip through copies, e.g. for better constant propagation

Additional flow functions:

$$\mathsf{RD}_{S:X} := Y (\mathsf{in}) = \mathsf{in} - \{X \rightarrow^*\} \cup \{X \rightarrow S' \mid Y \rightarrow S' \in \mathsf{in}\}$$

$$\mathsf{RD}_{S:X} := {}^*\mathcal{P}(\mathsf{in}) = \mathsf{in} - \{X {\rightarrow}^*\}$$

$$\cup \{X {\rightarrow} S' | Y \in \mathsf{may-point-to}(P) \land Y {\rightarrow} S' \in \mathsf{in}\}$$

$$\mathsf{RD}_{S:\,^{\star}P\,:=\,Y}\ (\mathsf{in}) = \mathsf{in} - \{X {\rightarrow}^{\star} \mid X \in \mathbf{must}\text{-point-to}(P)\} \\ \cup \{X {\rightarrow} S' \mid X \in \mathbf{may}\text{-point-to}(P) \land \\ Y {\rightarrow} S' \in \mathsf{in}\}$$

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Another use: "scalar replacement"

If we know that a pointer expression *P aliases a variable X (P must point to X) at some point, then can replace *P with X

• both for load & store

Example:

a := 5
...
w := &a
...
b := *w

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Adding pointers to pointers

Now allow a pointer to point to a pointer

· loads may return pointers, stores may store pointers

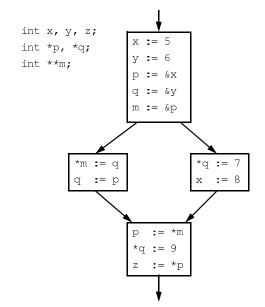
Revised flow functions for loads and stores:

$$\begin{aligned} \mathsf{MayPT}_{P} \; := \; {}^\star \mathcal{Q}(\mathsf{in}) = \mathsf{in} - \{P {\longrightarrow}^\star\} \\ & \cup \{P {\longrightarrow} X \mid \mathcal{Q} {\longrightarrow} R \in \mathsf{in} \land R {\longrightarrow} X \in \mathsf{in}\} \end{aligned}$$

$$\begin{aligned} \mathsf{MayPT}_{\star_P} &:= \varrho(\mathsf{in}) = \mathsf{in} - \{ R {\rightarrow}^\star \mid \{ R \} = \mathsf{in}(P) \} \\ & \cup \{ R {\rightarrow} X \mid P {\rightarrow} R \in \mathsf{in} \land \varrho {\rightarrow} X \in \mathsf{in} \} \end{aligned}$$

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Example



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Adding pointers to structs/records/objects/...

A variable can be a structure with a collection of named fields

- a pointer can point to a field of a structure variable
- a field can hold a pointer

Introduce location domain: $Loc = Var \cup Loc \times Field$

• either a variable or a location followed by a field name Old PT domain: sets of $v_1 \rightarrow v_2$ pairs = Pow($Var \times Var$) New PT domain: sets of $l_1 \rightarrow l_2$ pairs = Pow($Loc \times Loc$)

Some new forward flow functions:

$$\mathsf{MayPT}_{P} := \&X.F(\mathsf{in}) = \mathsf{in} - \{P {\rightarrow}^*\} \cup \{P {\rightarrow} X.F\}$$

$$\begin{split} \mathsf{MayPT}_P &:= X.F & (\mathsf{in}) = \mathsf{in} - \{P {\rightarrow}^*\} \cup \{P {\rightarrow} L \mid X.F {\rightarrow} L \in \mathsf{in}\} \\ \mathsf{MayPT}_P &:= (*_Q)._F(\mathsf{in}) = \mathsf{in} - \{P {\rightarrow}^*\} \\ & \cup \{P {\rightarrow} L \mid Q {\rightarrow} R \in \mathsf{in} \land R._F {\rightarrow} L \in \mathsf{in}\} \end{split}$$

$$\begin{split} \mathsf{MayPT}_{X.F} &:= \ _{\mathcal{Q}} \quad \text{(in)} = \mathsf{in} - \{X.F \rightarrow^*\} \cup \{X.F \rightarrow L \mid \mathcal{Q} \rightarrow L \in \mathsf{in}\} \\ \mathsf{MayPT}_{(*P).F} &:= \ _{\mathcal{Q}}(\mathsf{in}) = \mathsf{in} - \{R.F \rightarrow^* \mid \{R\} = \mathsf{in}(P)\} \\ & \cup \{R.F \rightarrow L \mid P \rightarrow R \in \mathsf{in} \land \mathcal{Q} \rightarrow L \in \mathsf{in}\} \end{split}$$

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Adding pointers to dynamically-allocated memory

 $P := \text{new } \tau$

τ could be scalar, pointer, structure, ...

Issue: each execution of new creates a new location

Idea: introduce new set of possible memory locations: Mem

Extend *Loc* to also allow a location to be a *Mem*: $Loc = Var \cup Mem \cup Loc \times Field$

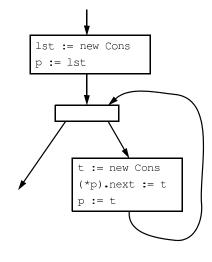
Flow function:

$$\mathsf{MayPT}_{P} := \mathsf{new}_{t}(\mathsf{in}) = \mathsf{in} - \{P \rightarrow^{\star}\} \cup \{P \rightarrow^{\star} \mathsf{newvar'}\}$$

· newvar: return next unallocated element of Mem

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Example



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A monotonic, finite approximation

Can't allocate a new memory location each time analyze new statement

- infinite Mem ⇒ infinite Loc ⇒ infinitely tall Pow(Loc × Loc)!
- · not a monotonic flow function!

One solution:

create a special summary node for each new stmt

• Loc = Var ∪ Stmt ∪ Loc×Field

Fixed flow function:

$$\mathsf{MayPT}_{S:P} := \mathsf{new}_{t}(\mathsf{in}) = \mathsf{in} - \{P \rightarrow^*\} \cup \{P \rightarrow S\}$$

Summary nodes represent a *set* of possible locations ⇒ cannot strongly update a summary node

$$\mathsf{MayPT}_{*P} := _{\mathcal{Q}}(\mathsf{in}) = \mathsf{in} - \{R {\to}^* \mid \{R\} = \mathsf{in}(P) \land \mathbf{R} \notin \mathbf{Stmt} \}$$
$$\cup \{R {\to} X \mid P {\to} R \in \mathsf{in} \land \mathcal{Q} {\to} X \in \mathsf{in} \}$$

Alternative summarization strategies:

- summary node for each type τ
- k-limited summary
 - maintain distinct nodes up to k links removed from root vars, then summarize together

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Adding pointers to array elements

Array index expressions can generate aliases:

a[i] aliases b[j] if:

- a aliases b and i equals j
- more generally, a and b overlap, and &a[i] = &b[j]

Can have pointers to array elements:

$$p := &a[i]$$

Can have pointer arithmetic, for array addressing:

$$p := &a[0]; ...; p++$$

How to model arrays?

Option 1: reason about array index expressions ⇒ array dependence analysis

Option 2: use a summary node to stand for all elements of the array

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