# CSE505: Graduate Programming Languages

Lecture 7 — Lambda Calculus

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#### Where we are

- ▶ Done: Syntax, semantics, and equivalence
  - ► For a language with little more than loops and global variables
- ▶ Now: Didn't IMP leave some things out?
  - ▶ In particular: scope, functions, and data structures
  - ▶ (Not to mention threads, I/O, exceptions, strings, ...)

Time for a new model...

#### Data + Code

Higher-order functions work well for scope and data structures

Scope: not all memory available to all code

```
let x = 1
let add3 y =
    let z = 2 in
    x + y + z
let seven = add3 4
```

▶ Data: Function closures store data. Example: Association "list"

```
let empty = (fun k -> raise Empty)
let cons k v lst = (fun k' -> if k'=k then v else lst k')
let lookup k lst = lst k
```

(Later: Objects do both too)

### Adding data structures

Extending IMP with data structures isn't too hard:

$$\begin{array}{lll} e & ::= & c \mid x \mid e + e \mid e * e \mid (e, e) \mid e.1 \mid e.2 \\ v & ::= & c \mid (v, v) \\ H & ::= & \cdot \mid H, x \mapsto v \end{array}$$

 $H ; e \Downarrow v$  all old rules plus:

$$\frac{H \ ; e_1 \Downarrow v_1 \quad H \ ; e_2 \Downarrow v_2}{H \ ; (e_1, e_2) \Downarrow (v_1, v_2)} \quad \frac{H \ ; e \Downarrow (v_1, v_2)}{H \ ; e.1 \Downarrow v_1} \quad \frac{H \ ; e \Downarrow (v_1, v_2)}{H \ ; e.2 \Downarrow v_2}$$

#### Notice:

- ▶ We allow pairs of values, not just pairs of integers
- We now have *stuck* programs (e.g., c.1)
  - ▶ What would C++ do? Scheme? ML? Java? Perl?
  - Division also causes stuckness

#### What about functions

But adding functions (or objects) does not work well:

$$e ::= ... | fun x -> s$$
 $v ::= ... | fun x -> s$ 
 $s ::= ... | e(e)$ 

$$H ; e \Downarrow v$$

$$H ; s \rightarrow H' ; s'$$

Additions:

$$rac{H \; ; \; e_1 \; \psi \; ext{fun} \; x hickspace s \; H \; ; \; e_2 \; \psi \; v}{H \; ; \; e_1(e_2) hickspace H \; ; \; x := v; s}$$

Does this match "the semantics we want" for function calls?

#### What about functions

But adding functions (or objects) does not work well:

$$\begin{array}{lll} e & ::= & \dots & \mid \text{fun } x \rightarrow s \\ v & ::= & \dots & \mid \text{fun } x \rightarrow s \\ s & ::= & \dots & \mid e(e) \end{array}$$

$$rac{H \; ; \; ext{fun} \; x hickspace > s \; \; \; H \; ; \; e_1 \; \psi \; ext{fun} \; x hickspace > s \; \; \; H \; ; \; e_2 \; \psi \; v}{H \; ; \; e_1(e_2) \; hickspace H \; ; \; x := v; s}$$

NO: Consider 
$$x := 1$$
; (fun  $x \rightarrow y := x$ )(2); ans  $:= x$ .

Scope matters; variable name doesn't. That is:

- Local variables should "be local"
- Choice of local-variable names should have only local ramifications

$$rac{H \; ; \, e_1 \downarrow ext{fun} \; x hickspace s \quad H \; ; \, e_2 \downarrow v \quad y \; ext{"fresh"}}{H \; ; \, e_1(e_2) hickspace h \; ; \, y := x; x := v; s; x := y}$$

$$rac{H \; ; \, e_1 \, \Downarrow \, ext{fun} \; x woheadrightarrows }{H \; ; \, e_1(e_2) woheadrightarrow H \; ; \, y := x; x := v; s; x := y}$$

"fresh" isn't very IMP-like but okay (think malloc)

$$rac{H \; ; \, e_1 \downarrow ext{fun} \; x hickspace s \quad H \; ; \, e_2 \downarrow v \quad y \; ext{``fresh''}}{H \; ; \, e_1(e_2) hickspace H \; ; \, y := x; x := v; s; x := y}$$

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- not a good match to how functions are implemented

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- yuck: the way we want to think about something as fundamental as a call?

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- "fresh" isn't very IMP-like but okay (think malloc)
- not a good match to how functions are implemented
- yuck: the way we want to think about something as fundamental as a call?
- ▶ NO: wrong model for most functional and OO languages
  - (Even wrong for C if s calls another function that accesses the global variable x)

# The wrong model

$$\begin{array}{c} H \; ; \; e_1 \; \Downarrow \; \text{fun} \; x \; \neg > \; s \qquad H \; ; \; e_2 \; \Downarrow \; v \qquad y \; \text{``fresh''} \\ H \; ; \; e_1(e_2) \; \rightarrow \; H \; ; \; y := \; x; \; x := \; v; \; s; \; x := \; y \\ \\ \text{f}_1 := \; (\text{fun} \; x \; \neg > \; \text{f}_2 := \; (\text{fun} \; z \; \neg > \; \text{ans} \; := \; x \; + \; z)); \\ \text{f}_1(2); \\ \text{x} := \; 3; \\ \text{f}_2(4) \end{array}$$

"Should" set ans to 6:

ightharpoonup  $f_1(2)$  should assign to  $f_2$  a function that adds 2 to its argument and stores result in ans

"Actually" sets ans to 7:

▶ f<sub>2</sub>(2) assigns to f<sub>2</sub> a function that adds the current value of x to its argument

#### Punch line

Cannot properly model local scope via a global heap of integers.

▶ Functions are not syntactic sugar for assignments to globals

So let's build a new model that focuses on this essential concept

(can add back IMP features later)

Or just borrow a model from Alonzo Church

And drop mutation, conditionals, integers (!), and loops (!)

#### The Lambda Calculus

The Lambda Calculus:

```
e ::= \lambda x. e \mid x \mid e e
v ::= \lambda x. e
```

You apply a function by substituting the argument for the bound variable

► (There is an equivalent *environment* definition not unlike heap-copying; see future homework)

### **Example Substitutions**

$$e ::= \lambda x. e \mid x \mid e e$$

$$v ::= \lambda x. e$$

Substitution is the key operation we were missing:

$$(\lambda x.\ x)(\lambda y.\ y) 
ightarrow (\lambda y.\ y)$$
  $(\lambda x.\ \lambda y.\ y\ x)(\lambda z.\ z) 
ightarrow (\lambda y.\ y\ \lambda z.\ z)$   $(\lambda x.\ x\ x)(\lambda x.\ x\ x) 
ightarrow (\lambda x.\ x\ x)(\lambda x.\ x\ x)$ 

After substitution, the bound variable is gone, so its "name" was irrelevant. (Good!)

# A Programming Language

Given substitution  $(e_1[e_2/x] = e_3)$ , we can give a semantics:

$$egin{aligned} e 
ightarrow e' \ \hline rac{e[v/x] = e'}{(\lambda x.\ e)\ v 
ightarrow e'} & rac{e_1 
ightarrow e'_1}{e_1\ e_2 
ightarrow e'_1\ e_2} & rac{e_2 
ightarrow e'_2}{v\ e_2 
ightarrow v\ e'_2} \end{aligned}$$

A small-step, call-by-value (CBV), left-to-right semantics

lacktriangle Terminates when the "whole program" is some  $\lambda x.~e$ 

But (also) gets stuck when there's a free variable "at top-level"

lacktriangle Won't "cheat" like we did with H(x) in IMP because scope is what we're interested in

This is the "heart" of functional languages like Caml

▶ But "real" implementations don't substitute; they do something *equivalent* 

## Roadmap

- Motivation for a new model (done)
- CBV lambda calculus using substitution (done)
- Notes on concrete syntax
- Simple Lambda encodings (it's Turing complete!)
- Other reduction strategies
- Defining substitution

# Concrete-Syntax Notes

We (and Caml) resolve concrete-syntax ambiguities as follows:

- 1.  $\lambda x. e_1 e_2$  is  $(\lambda x. e_1 e_2)$ , not  $(\lambda x. e_1) e_2$
- 2.  $e_1 \ e_2 \ e_3$  is  $(e_1 \ e_2) \ e_3$ , not  $e_1 \ (e_2 \ e_3)$ 
  - Convince yourself application is not associative

#### More generally:

- 1. Function bodies extend to an unmatched right parenthesis Example:  $(\lambda x.\ y(\lambda z.\ z)w)q$
- 2. Application associates to the left Example:  $e_1 \ e_2 \ e_3 \ e_4$  is  $(((e_1 \ e_2) \ e_3) \ e_4)$
- Like in IMP, assume we really have ASTs (with non-leaves labeled λ or "application")
- Rules may seem strange at first, but it's the most convenient concrete syntax
  - ▶ Based on 70 years experience

# Lambda Encodings

Fairly crazy: we left out constants, conditionals, primitives, and data structures

In fact, we're *Turing complete* and can *encode* whatever we need (just like assembly language can)

Motivation for encodings:

- ► Fun and mind-expanding
- Shows we aren't oversimplifying the model ("numbers are syntactic sugar")
- ► Can show languages are too expressive (e.g., unlimited C++ template instantiation)

Encodings are also just "(re)definition via translation"

### **Encoding booleans**

#### The "Boolean ADT"

- ▶ There are two booleans and one conditional expression.
- ► The conditional takes 3 arguments (e.g., via currying). If the first is one boolean it evaluates to the second. If it's the other boolean it evaluates to the third.

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Here is one of an infinite number of encodings:

$$\begin{array}{lll} \text{"true"} & \lambda x. \ \lambda y. \ x \\ \text{"false"} & \lambda x. \ \lambda y. \ y \\ \text{"if"} & \lambda b. \ \lambda t. \ \lambda f. \ b \ t \ f \end{array}$$

Example: "if" "true"  $v_1 \ v_2 
ightharpoonup ^* v_1$ 

#### **Evaluation Order Matters**

Careful: With CBV we need to "thunk"...

"if" "true" 
$$(\lambda x.\ x)$$
  $\underbrace{((\lambda x.\ x\ x)(\lambda x.\ x\ x))}_{\text{an infinite loop}}$ 

diverges, but

"if" "true" 
$$(\lambda x.\ x)$$
  $\underbrace{(\lambda z.\ ((\lambda x.\ x\ x)(\lambda x.\ x\ x))\ z))}_{\text{a value that when called diverges}}$ 

does not

### **Encoding Pairs**

#### The "pair ADT":

- ▶ There is 1 constructor (taking 2 arguments) and 2 selectors
- ▶ 1st selector returns the 1st arg passed to the constructor
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"mkpair"
$$\lambda x.\ \lambda y.\ \lambda z.\ z\ x\ y$$
"fst" $\lambda p.\ p(\lambda x.\ \lambda y.\ x)$ "snd" $\lambda p.\ p(\lambda x.\ \lambda y.\ y)$ 

#### Example:

"snd" ("fst" ("mkpair" ("mkpair" 
$$v_1 \ v_2) \ v_3)) 
ightarrow ^* v_2$$

## Reusing Lambdas

Is it weird that the encodings of Booleans and pairs both used  $\lambda x$ .  $\lambda y$ . x and  $\lambda x$ .  $\lambda y$ . y for different purposes?

Is it weird that the same bit-pattern in binary code can represent an int, a float, an instruction, or a pointer?

Von Neumann: Bits can represent (all) code and data

Church (?): Lambdas can represent (all) code and data

Beware the "Turing tarpit"

### **Encoding Lists**

Rather than start from scratch, notice that booleans and pairs are enough to encode lists:

- ► Empty list is "mkpair" "false" "false"
- ▶ Non-empty list is  $\lambda h$ .  $\lambda t$ . "mkpair" "true" ("mkpair" h t)
- ▶ Is-empty is ...
- ► Head is ...
- ► Tail is ...

#### Note:

- Not too far from how lists are implemented
- ► Taking "tail" ("tail" "empty") will produce some lambda
  - ► Just like, without page-protection hardware, null->tail->tail would produce some bit-pattern

- Write a function that takes an f and calls it in place of recursion
  - Example (in enriched language):

$$\lambda f. \ \lambda x. \ \text{if} \ (x=0) \ \text{then} \ 1 \ \text{else} \ (x*f(x-1))$$

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- ► The details, especially for CBV, are icky; the point is it's possible and you define "fix" only once
- Not on exam:

  "fix"  $\lambda g. (\lambda x. g (\lambda y. x x y))(\lambda x. g (\lambda y. x x y))$

How about arithmetic?

► Focus on non-negative numbers, addition, is-zero, etc.

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How I would do it based on what we have so far:

- Lists of booleans for binary numbers
  - Zero can be the empty list
  - Use fix to implement adders, etc.
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But instead everybody always teaches Church numerals. Why?

- Tradition? Some sense of professional obligation?
- Better reason: You don't need fix: Basic arithmetic is often encodable in languages where all programs terminate
- ▶ In any case, we'll show some basics "just for fun"

```
"0" \lambda s. \lambda z. z
"1" \lambda s. \lambda z. s z
"2" \lambda s. \lambda z. s (s z)
"3" \lambda s. \lambda z. s (s (s z))
```

- Numbers encoded with two-argument functions
- ightharpoonup The "number i" composes the first argument i times, starting with the second argument
  - ightharpoonup z stands for "zero" and s for "successor" (think unary)
- lacktriangleright The trick is implementing arithmetic by cleverly passing the right arguments for s and z

"0" 
$$\lambda s. \ \lambda z. \ z$$
"1"  $\lambda s. \ \lambda z. \ s \ z$ 
"2"  $\lambda s. \ \lambda z. \ s \ (s \ z)$ 
"3"  $\lambda s. \ \lambda z. \ s \ (s \ (s \ z))$ 
"successor"  $\lambda n. \ \lambda s. \ \lambda z. \ s \ (n \ s \ z)$ 

successor: take "a number" and return "a number" that (when called) applies  $\boldsymbol{s}$  one more time

```
"0" \lambda s. \ \lambda z. \ z
"1" \lambda s. \ \lambda z. \ s \ z
"2" \lambda s. \ \lambda z. \ s \ (s \ z)
"3" \lambda s. \ \lambda z. \ s \ (s \ (s \ z))
"successor" \lambda n. \ \lambda s. \ \lambda z. \ s \ (n \ s \ z)
"plus" \lambda n. \ \lambda m. \ \lambda s. \ \lambda z. \ n \ s \ (m \ s \ z)
```

plus: take two "numbers" and return a "number" that uses one number as the zero argument for the other

```
"0" \lambda s. \ \lambda z. \ z
"1" \lambda s. \ \lambda z. \ s \ z
"2" \lambda s. \ \lambda z. \ s \ (s \ z)
"3" \lambda s. \ \lambda z. \ s \ (s \ (s \ z))
"successor" \lambda n. \ \lambda s. \ \lambda z. \ s \ (n \ s \ z)
"plus" \lambda n. \ \lambda m. \ \lambda s. \ \lambda z. \ n \ s \ (m \ s \ z)
"times" \lambda n. \ \lambda m. \ m. \ m \ (\text{"plus"} \ n) "zero"
```

times: take two "numbers" m and n and pass to m a function that adds n to its argument (so this will happen m times) and "zero" (where to start the m iterations of addition)

```
"0" \lambda s. \lambda z. z
"1" \lambda s. \lambda z. s z
"2" \lambda s. \lambda z. s (s z)
"3" \lambda s. \lambda z. s (s (s z))
"successor" \lambda n. \lambda s. \lambda z. s (n s z)
"plus" \lambda n. \lambda m. \lambda s. \lambda z. n s (m s z)
"times" \lambda n. \lambda m. m  ("plus" n) "zero"
"isZero" \lambda n. (\lambda x.  "false") "true"
```

isZero: an easy one, see how the two arguments will lead to the correct answer

```
"0"
                       \lambda s, \lambda z, z
"1"
                       \lambda s, \lambda z, s z
"2"
                       \lambda s. \lambda z. s (s z)
"3"
                       \lambda s. \ \lambda z. \ s \ (s \ (s \ z))
"successor"
                      \lambda n. \ \lambda s. \ \lambda z. \ s \ (n \ s \ z)
"plus"
                       \lambda n. \ \lambda m. \ \lambda s. \ \lambda z. \ n \ s \ (m \ s \ z)
"times"
                       \lambda n. \ \lambda m. \ m ("plus" n) "zero"
"isZero"
                       \lambda n. (\lambda x. "false") "true"
"predecessor"
                      (with 0 sticky) the hard one; see Wikipedia
"minus"
                       similar to times with pred instead of plus
                      subtract and test for zero
"isEqual"
```

## Roadmap

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- ► Simple Lambda encodings (it's Turing complete!) (done)
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### Then start type systems

 Later take a break from types to consider first-class continuations and related topics