

# CSE-505: Programming Languages

## Lecture 19 — Type-and-Effect Systems

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# Type-and-effect systems

New topic: An elegant framework to extend type systems to track “things that may happen” (effects) during evaluation

Plain-old type systems have judgments like  $\Gamma \vdash e : \tau$  to mean:

- ▶  $e$  won't get stuck
- ▶ If  $e$  produces a value, that value has type  $\tau$

Adding *effects* reuses the “plumbing” of typing rules to compute something about “how  $e$  executes”

- ▶ There are many things we may want to conservatively approximate
  - ▶ Example: What exceptions might get thrown
- ▶ All effect systems are very similar, especially treatment of functions
  - ▶ Example: All values have no effect since their “computation” does nothing

# First a type system

(In this example, exceptions raise constant strings  $s$ )

$$\begin{aligned} \tau & ::= \mathbf{bool} \mid \tau \rightarrow \tau \mid \tau * \tau \\ e & ::= x \mid \mathbf{true} \mid \mathbf{false} \mid \lambda x. e \mid e e \mid (e, e) \mid e.1 \mid e.2 \\ & \quad \mid \mathbf{if } e e e \mid \mathbf{raise } s \mid \mathbf{try } e \mathbf{ handle } s e \end{aligned}$$

$\Gamma \vdash e : \tau$	$\frac{}{\Gamma \vdash x : \Gamma(x)}$	$\frac{}{\Gamma \vdash \mathbf{true} : \mathbf{bool}}$	$\frac{}{\Gamma \vdash \mathbf{false} : \mathbf{bool}}$
$\frac{\Gamma, x : \tau_1 \vdash e : \tau_2}{\Gamma \vdash \lambda x. e : \tau_1 \rightarrow \tau_2}$	$\frac{\Gamma \vdash e_1 : \tau_2 \rightarrow \tau_1 \quad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash e_1 e_2 : \tau_1}$		
$\frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash (e_1, e_2) : \tau_1 * \tau_2}$	$\frac{\Gamma \vdash e : \tau_1 * \tau_2}{\Gamma \vdash e.1 : \tau_1}$	$\frac{\Gamma \vdash e : \tau_1 * \tau_2}{\Gamma \vdash e.2 : \tau_2}$	
	$\frac{\Gamma \vdash e_1 : \mathbf{bool} \quad \Gamma \vdash e_2 : \tau \quad \Gamma \vdash e_3 : \tau}{\Gamma \vdash \mathbf{if } e_1 e_2 e_3 : \tau}$		
$\frac{}{\Gamma \vdash \mathbf{raise } s : \tau}$	$\frac{\Gamma \vdash e_1 : \tau \quad \Gamma \vdash e_2 : \tau}{\Gamma \vdash \mathbf{try } e_1 \mathbf{ handle } s e_2 : \tau}$		

# Add effects

$\epsilon ::=$  ...sets of strings...  
 $\tau ::=$  **bool** |  $\tau \xrightarrow{\epsilon} \tau$  |  $\tau * \tau$   
 $e ::=$   $x$  | **true** | **false** |  $\lambda x. e$  |  $e e$  |  $(e, e)$  |  $e.1$  |  $e.2$   
 | **if**  $e e e$  | **raise**  $s$  | **try**  $e$  **handle**  $s e$

$\Gamma \vdash e : \tau; \epsilon$	$\frac{}{\Gamma \vdash x : \Gamma(x); \emptyset}$	$\frac{}{\Gamma \vdash \text{true} : \text{bool}; \emptyset}$	$\frac{}{\Gamma \vdash \text{false} : \text{bool}; \emptyset}$
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$\frac{\Gamma, x : \tau_1 \vdash e : \tau_2; \epsilon}{\Gamma \vdash \lambda x. e : \tau_1 \xrightarrow{\epsilon} \tau_2; \emptyset}$	$\frac{\Gamma \vdash e_1 : \tau_2 \xrightarrow{\epsilon_3} \tau_1; \epsilon_1 \quad \Gamma \vdash e_2 : \tau_2; \epsilon_2}{\Gamma \vdash e_1 e_2 : \tau_1; \epsilon_1 \cup \epsilon_2 \cup \epsilon_3}$
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$\frac{\Gamma \vdash e_1 : \tau_1; \epsilon_1 \quad \Gamma \vdash e_2 : \tau_2; \epsilon_2}{\Gamma \vdash (e_1, e_2) : \tau_1 * \tau_2; \epsilon_1 \cup \epsilon_2}$	$\frac{\Gamma \vdash e : \tau_1 * \tau_2; \epsilon}{\Gamma \vdash e.1 : \tau_1; \epsilon}$	$\frac{\Gamma \vdash e : \tau_1 * \tau_2; \epsilon}{\Gamma \vdash e.2 : \tau_2; \epsilon}$
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$\frac{\Gamma \vdash e_1 : \text{bool}; \epsilon_1 \quad \Gamma \vdash e_2 : \tau; \epsilon_2 \quad \Gamma \vdash e_3 : \tau; \epsilon_3}{\Gamma \vdash \text{if } e_1 e_2 e_3 : \tau; \epsilon_1 \cup \epsilon_2 \cup \epsilon_3}$
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$\frac{}{\Gamma \vdash \text{raise } s : \tau; \{s\}}$	$\frac{\Gamma \vdash e_1 : \tau; \epsilon_1 \quad \Gamma \vdash e_2 : \tau; \epsilon_2}{\Gamma \vdash \text{try } e_1 \text{ handle } s e_2 : \tau; (\epsilon_1 - \{s\}) \cup \epsilon_2}$
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## Key facts

Soundness: If  $\cdot \vdash e : \tau; \epsilon$  and  $e$  raises uncaught exception  $s$ , then  $s \in \epsilon$

- ▶ Corollary to Preservation and Progress (once you define the operational semantics for exceptions)

All effect systems work this way:

- ▶ Values effectless
- ▶ Functions have *latent effects*
- ▶ Conservative due to control-flow (if and try/handle)
- ▶ Often some way to *mask effects* (here, catch an exception)

Only a couple rules special to this effect system

- ▶ Also, not always sets and  $\cup$

## More general rules

Every effect system also substantially more expressive via appropriate subsumption:

- ▶ Typing rule for subeffecting (also useful for Preservation)
- ▶ Subtyping of function types is covariant in latent effects

$$\frac{\Gamma \vdash \tau : e; \epsilon \quad \epsilon \subseteq \epsilon'}{\Gamma \vdash \tau : e; \epsilon'}$$
$$\frac{\tau_3 \leq \tau_1 \quad \tau_2 \leq \tau_4 \quad \epsilon \subseteq \epsilon'}{\tau_1 \xrightarrow{\epsilon} \tau_2 \leq \tau_3 \xrightarrow{\epsilon'} \tau_4}$$

Not shown: Also want effect polymorphism (type variables ranging over effects) for higher-order functions like map

## Other examples

- ▶ Definitely terminates (true) or possibly diverges (false)
  - ▶ Give **fix**  $e$  effect *false*
  - ▶ Give values effect *true*
  - ▶ Treat  $\cup$  as *and*
  - ▶ No change to rules for functions, pairs, conditionals, etc.
- ▶ What type casts might occur
- ▶ Are certain variables always accessed in critical sections
- ▶ Does code obey a locking protocol
- ▶ Does code only access memory regions that haven't been deallocated
- ▶ ...

Really a general way to lift static analysis to higher-order functions

- ▶ Key is recognizing “from a mile away” when an effect system is the right tool