

Readings: K&F 17.4, 18.1, 18.2, 18.3



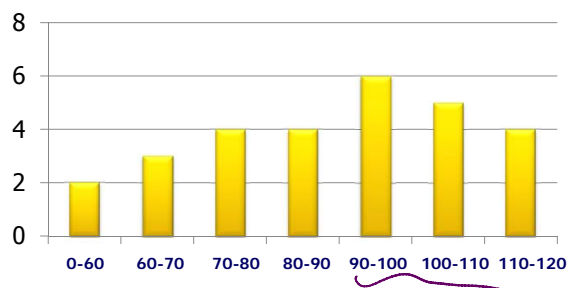
Parameter Estimation & Structure Learning

Lecture 10 – Apr 27, 2011
CSE 515, Statistical Methods, Spring 2011

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University of Washington, Seattle

Announcements

- Problem Set #1 has been graded.
 - Assuming Gaussian, **sufficient statistics**:
Mean: 89.17; Std: 19.86
- Graded HW will be handed back after class.



Bayesian Approach: General Formulation

- Joint distribution over D, θ $P(D, \theta) = P(D|\theta)P(\theta)$
 - As we saw, likelihood can be described compactly using sufficient statistics

- Posterior distribution over parameters

$$P(\theta|D) = \frac{P(D|\theta)P(\theta)}{P(D)}$$

- $P(D)$ is the marginal likelihood of the data

$$P(D) = \int_{\theta} P(D|\theta)P(\theta)d\theta \quad \left. \begin{array}{l} p(\theta) \\ p(\theta|D) \end{array} \right\}$$

- We want conditions in which posterior is also compact

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Conjugate Families

- A family of priors $P(\theta;\alpha)$ is **conjugate** to a model $P(\xi|\theta)$ if for any possible dataset D of i.i.d samples from $P(\xi|\theta)$ and choice of hyperparameters α for the prior over θ , there are hyperparameters α' that describe the posterior, i.e.,

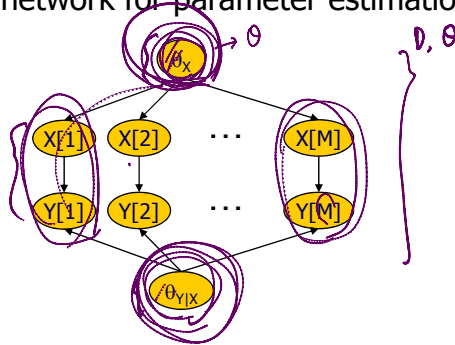
$$P(\theta;\alpha') \propto P(D|\theta)P(\theta;\alpha)$$

- Posterior has the same parametric form as the prior ←
- Dirichlet prior is a **conjugate family** for the multinomial likelihood
- Conjugate families are useful since:
 - Many distributions can be represented with hyperparameters
 - They allow for sequential update within the same representation
 - In many cases we have closed-form solutions for prediction

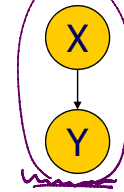
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Bayesian Estimation in BayesNets

Bayesian network for parameter estimation



Bayesian network

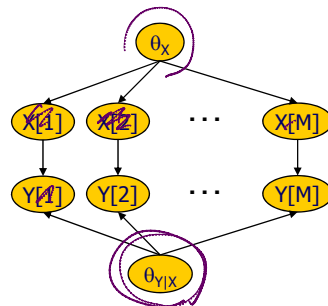


- Instances are independent given the parameters
 - $(x[m'], y[m'])$ are d-separated from $(x[m], y[m])$ given θ
- Priors for individual variables are a priori independent
 - Global independence of parameters $P(\theta) = \prod_i P(\theta_{x_i} | P_{\alpha X})$

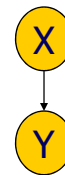
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Bayesian Estimation in BayesNets

Bayesian network for parameter estimation



Bayesian network

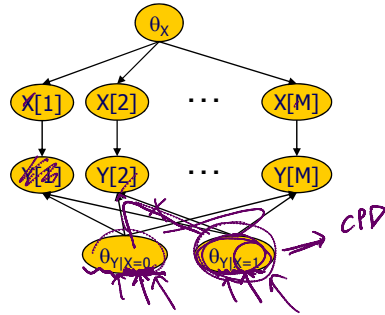


- Posteriors of θ are independent given complete data
 - Complete data d-separates parameters for different CPDs
 - $P(\theta_x, \theta_{y|x} | D) = P(\theta_x | D) P(\theta_{y|x} | D)$
 - As in MLE, we can solve each estimation problem separately

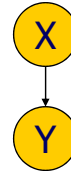
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Bayesian Estimation in BayesNets

Bayesian network for parameter estimation



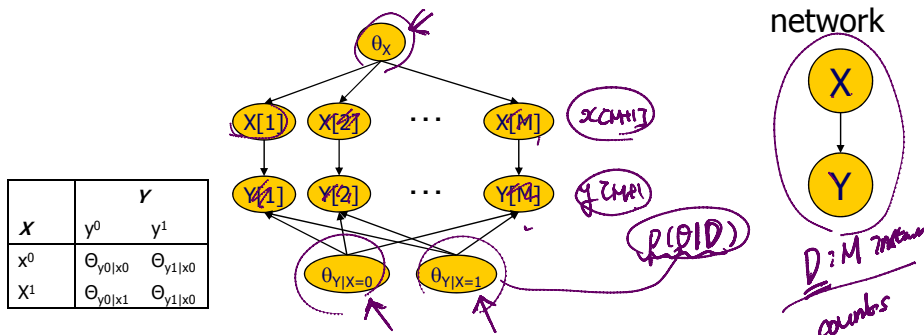
Bayesian network



- **Posteriors of θ are independent given complete data**
 - Also holds for parameters within families
 - Note context specific independence between $\theta_{Y|X=0}$ and $\theta_{Y|X=1}$ when given both X and Y

Bayesian Estimation in BayesNets

Bayesian network for parameter estimation



- **Posteriors of θ can be computed independently**
 - For multinomial $\theta_{x_i|pa_i}$, posterior is Dirichlet with parameters $\alpha_{x_i=1|pa_i} + M[X_i=1|pa_i], \dots, \alpha_{x_i=k|pa_i} + M[X_i=k|pa_i]$
 - $P(X_i[M+1]=x_i | Pa_i[M+1]=pa_i, D) = \frac{\alpha_{x_i|pa_i} + M[x_i, pa_i]}{\sum_i \alpha_{x_i|pa_i} + M[x_i, pa_i]}$

Parameter Estimation Summary

- Estimation relies on **sufficient statistics** $D: \langle Pa_i, X_i \rangle$

- For **multinomials** these are of the form $M[x_i, pa_i]$
- Parameter estimation

$$\hat{\theta}_{x_i, pa_i} = \frac{M[x_i, pa_i]}{M[pa_i]}$$

MLE

$$P(x_i, pa_i, D) = \frac{\alpha_{x_i, pa_i} + M[x_i, pa_i]}{\alpha_{pa_i} + M[pa_i]}$$

Bayesian (Dirichlet)

pa	X	
	X ⁰	X ¹
p ⁰	$\theta_{x^0 pa^0}$	$\theta_{x^1 pa^0}$
p ¹	$\theta_{x^0 pa^1}$	$\theta_{x^1 pa^1}$

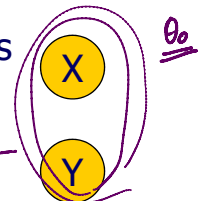
- Bayesian methods also require choice of **priors**
- MLE and Bayesian are asymptotically equivalent
- Both can be implemented in an **online** manner by accumulating sufficient statistics

Assessing Priors for BayesNets

- We need the $\alpha(x_i, pa_i)$ for each node x_i
- We can use initial parameters Θ_0 as prior information
 - Need also an **equivalent sample size** parameter M'
 - Then, we let $\alpha(x_i, pa_i) = M' P(x_i, pa_i | \Theta_0)$
- This allows to update a network using new data

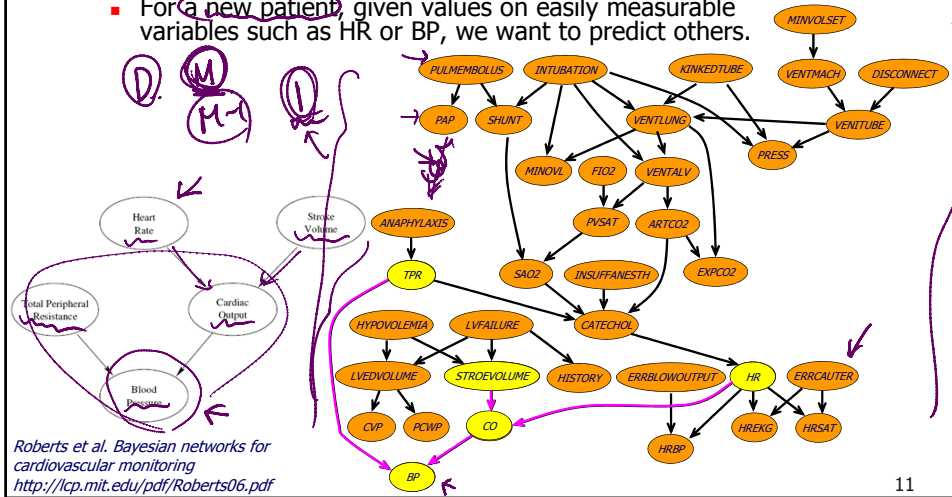
- Example network for priors

- $P(X=0) = P(X=1) = 0.5$
- $P(Y=0) = P(Y=1) = 0.5$
- $M' = 1$
- Note: $\alpha(x_0) = 0.5$ $\alpha(x_0, y_0) = 0.25$



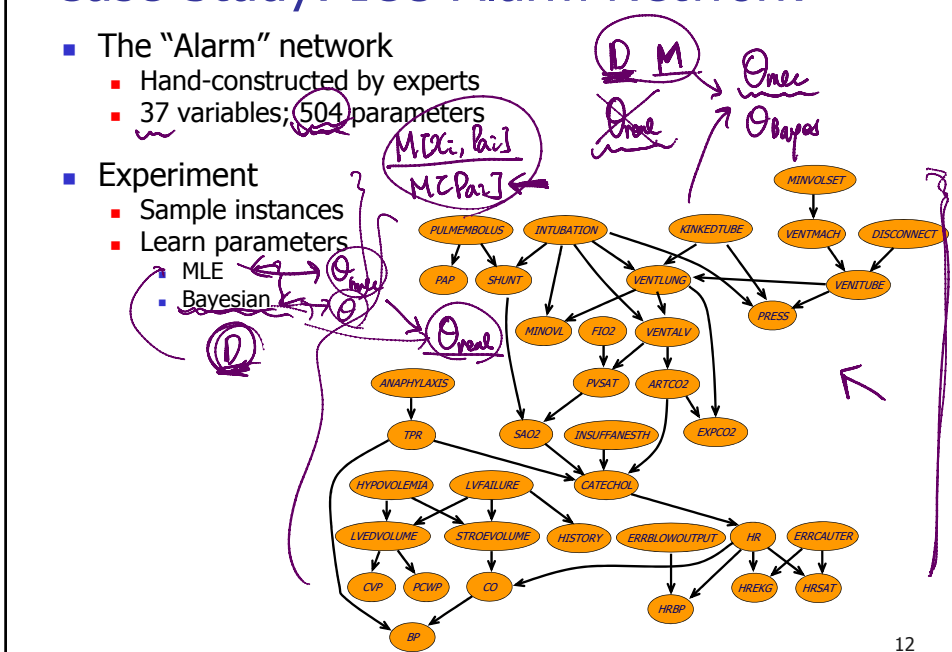
Case Study: ICU Alarm Network

- The "Alarm" network
 - Hand-constructed by experts: 37 variables; 504 parameters
- Predicting patient status in ICU
 - For a new patient, given values on easily measurable variables such as HR or BP, we want to predict others.

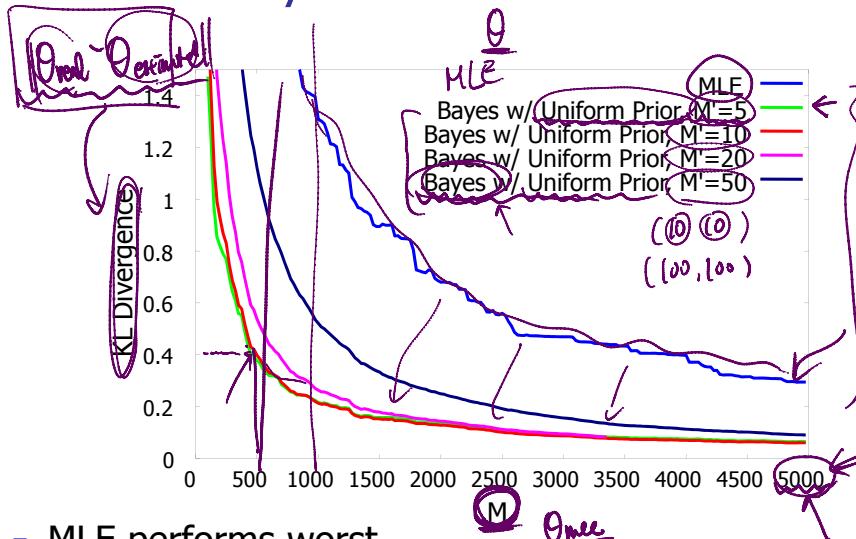


Case Study: ICU Alarm Network

- The "Alarm" network
 - Hand-constructed by experts
 - 37 variables; 504 parameters
- Experiment
 - Sample instances
 - Learn parameters
 - MLE
 - Bayesian



Case Study: ICU Alarm Network



- MLE performs worst
- Prior $M'=5$ provides best smoothing

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STRUCTURE LEARNING

Structure Learning Motivation

- Network structure is often unknown ←
- Purposes of structure learning ←
 - Discover the dependency structure of the domain ←
 - Goes beyond statistical correlations between individual variables and detects direct vs indirect correlations
 - Set expectations: at best, we can recover the structure up to the I-equivalence class
 - Density estimation ←
 - Estimate a statistical model of the underlying distribution and use it to reason with and predict new instances

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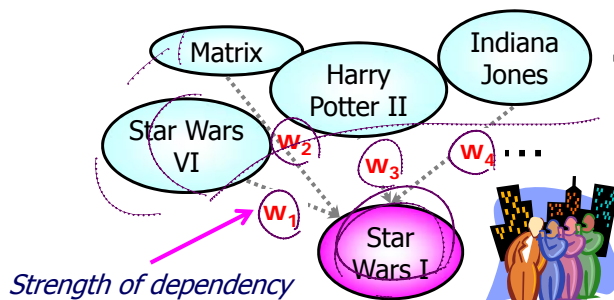
Application in Artificial Intelligence

- Collaborative filtering: Predicting a user's preference on a certain product based on his or her preference on other products
 - For example: Netflix competition (movie rating prediction), amazon recommendation system ...

Predict User rating of Star Wars I (task movie)

Given Ratings of other movies by the user (feature movies)

Training instances Many users

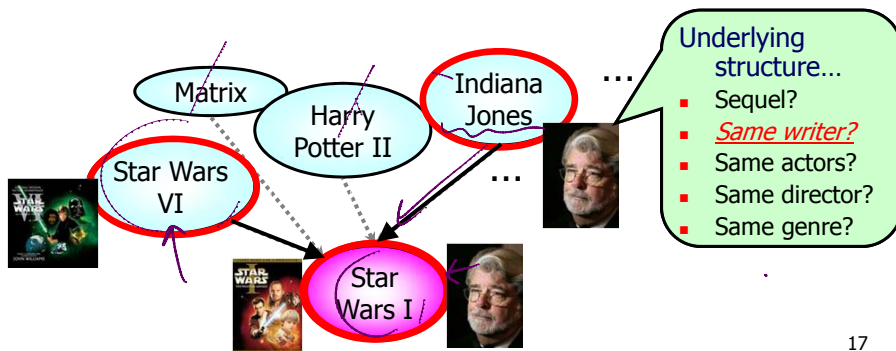


110,000 movies in IMDB* → Too many parameters in the CPD

*Internet Movie Database

BayesNet Learning in Netflix Challenge

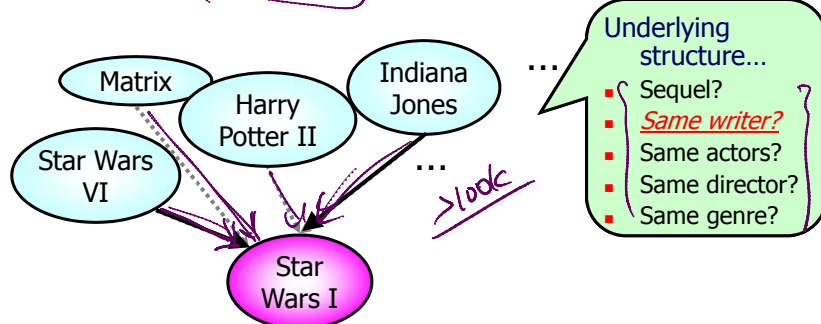
- Underlying structure should have a varying dependency between each feature movie and the task movie (Star Wars I)...



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BayesNet Learning in Netflix Challenge

- Underlying structure should have a varying dependency between each feature movie and the task movie (Star Wars I)...
- Bayesian network
 - Variables: ratings on movies (can be partially observed) ←
 - Structure: prediction model (directed) or affinity (undirected)
 - Training data $D = \langle \text{star_wars_I}[m], \text{matrix}[m], \text{harry_potter}[m], \dots \rangle$: ratings on movies from M users (complete or partially observed)
- Structure learning:
 - We don't want to fix the structure based on our prior knowledge, but learn from the training data
 - Too dense models are prone to overfitting. ←

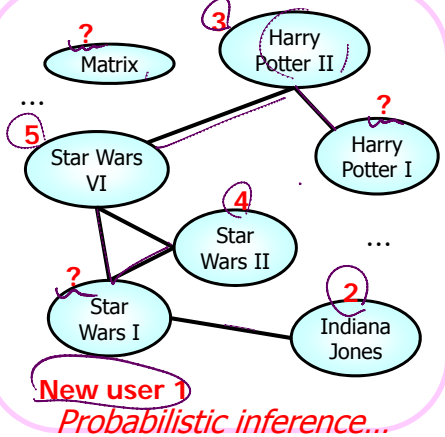


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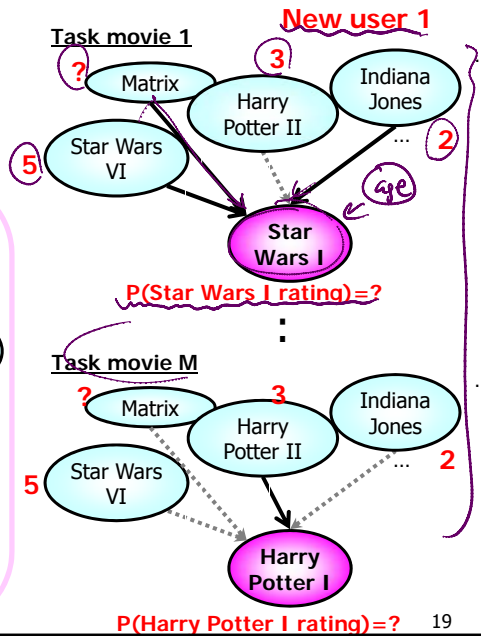
Predicting Ratings of New Users

- Given a new user's ratings, predict ratings on task movies
 - MLE
 - Bayesian approach

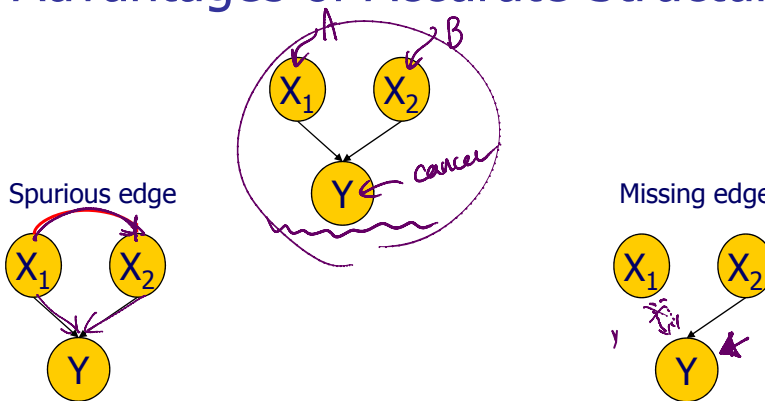
Markov network



Probabilistic inference...



Advantages of Accurate Structure



- Increases number of fitted parameters → *overfitting*
- Wrong causality and domain structure assumptions

- Cannot be compensated by parameter estimation
- Wrong causality and domain structure assumptions

Structure Learning Approaches

- **Constraint based methods**

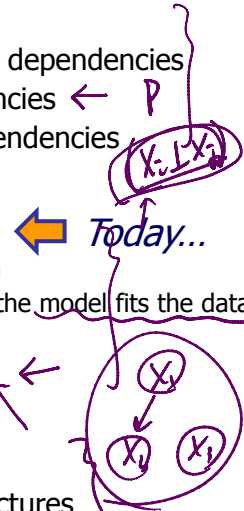
- View the Bayesian network as representing dependencies
- Find a network that best explains dependencies $\leftarrow P$
- **Limitation:** sensitive to errors in single dependencies

- **Score based approaches**

- View learning as a model selection problem
 - Define a scoring function specifying how well the model fits the data
 - Search for a high-scoring network structure
- **Limitation:** super-exponential search space

- **Bayesian model averaging methods**

- Average predictions across all possible structures
- Can be done exactly (some cases) or approximately



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Score Based Approaches

- **Strategy**

- Define a scoring function for each candidate structure
- Search for a high scoring structure

- **Key: choice of scoring function** }

- Likelihood based scores }
- Bayesian based scores }

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Likelihood Scores

- Goal: find (G, θ) that maximize the likelihood
 - Score_L(G:D) = log P(D | G, θ_G) where θ_G is MLE for G
 - Find G that maximizes Score_L(G:D)

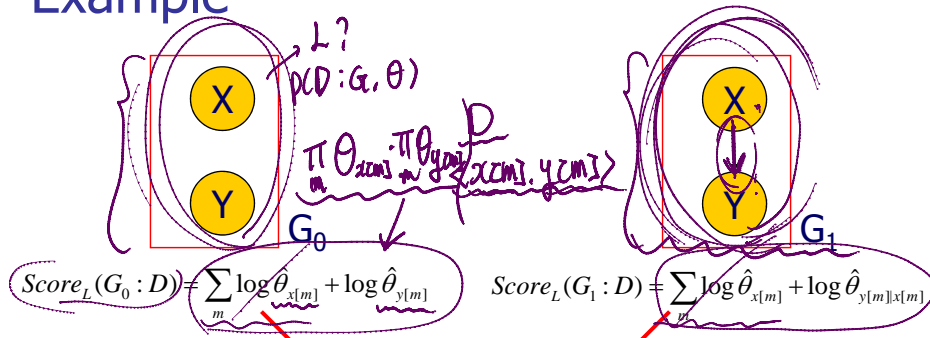
$$\hat{\theta} = \underset{\theta}{\operatorname{argmax}} P(D|\theta)$$

$$\underset{G, \theta}{\operatorname{argmax}} P(D|G, \theta) -$$

$$\max_{G, \theta} P(D|G, \theta) = \max_G \left[\max_{\theta_G} P(D|G, \theta_G) \right]$$

$$\text{Score}_L(G:D) = \log P(D|G, \hat{\theta}_G)$$

Example



$$\begin{aligned} \text{Score}_L(G_1:D) - \text{Score}_L(G_0:D) &= \sum_m \log \hat{\theta}_{y[m]|x[m]} - \log \hat{\theta}_{y[m]} \\ &= \sum_{x,y} M[x,y] \log \hat{\theta}_{y|x} - \sum_y M[y] \log \hat{\theta}_y \\ &= M \sum_{x,y} \hat{P}(x,y) \log \hat{P}(y|x) - M \sum_y \hat{P}(y) \log \hat{P}(y) \\ &= M \sum_{x,y} \hat{P}(x,y) \log \hat{P}(y|x) - M \sum_{x,y} \hat{P}(x,y) \log \hat{P}(y) \\ &= M \sum_{x,y} \hat{P}(x,y) \log \frac{\hat{P}(y|x)}{\hat{P}(y)} \geq 0. \end{aligned}$$

Information-theoretic interpretation:
 High mutual information implies stronger dependency.
 Stronger dependency implies stronger preference for the model where X and Y depend on each other.

General Decomposition

- The Likelihood score decomposes as:

$$Score_L(G : D) = M \sum_{i=1}^n \mathbf{I}_{\hat{p}}(X_i, Pa_{X_i}^G) - M \sum_{i=1}^n \mathbf{H}_{\hat{p}}(X_i)$$



- Proof:

$$Score_L(G : D) = \sum_{i=1}^n \left[\sum_{u_i \in Val(Pa_{X_i}^G)} \sum_{x_i} M[x_i, u_i] \log \hat{\theta}_{x_i|u_i} \right]$$

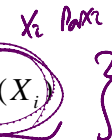
$$\begin{aligned} \frac{1}{M} \sum_{u_i} \sum_{x_i} M[x_i, u_i] \log \hat{\theta}_{x_i|u_i} &= \sum_{u_i} \sum_{x_i} \hat{P}(x_i, u_i) \log \hat{P}(x_i | u_i) \\ &= \sum_{u_i} \sum_{x_i} \hat{P}(x_i, u_i) \log \left(\frac{\hat{P}(x_i, u_i) \hat{P}(x_i)}{\hat{P}(u_i) \hat{P}(x_i)} \right) \\ &= \sum_{u_i} \sum_{x_i} \hat{P}(x_i, u_i) \log \left(\frac{\hat{P}(x_i, u_i)}{\hat{P}(u_i) \hat{P}(x_i)} \right) + \sum_{x_i} \left(\sum_{u_i} \hat{P}(x_i, u_i) \right) \log \hat{P}(x_i) \\ &= \mathbf{I}_{\hat{p}}(X_i, U_i) + \sum_{x_i} \hat{P}(x_i) \log \hat{P}(x_i) \\ &= \mathbf{I}_{\hat{p}}(X_i, U_i) - \mathbf{H}_{\hat{p}}(X_i) \end{aligned}$$

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- Second term does not depend on network structure and thus is irrelevant for selecting between two structures
- Score increases as mutual information, or strength of dependence between connected variable increases

- After some manipulation can show:

$$Score_L(G : D) = \mathbf{H}_{\hat{p}}(X_1, \dots, X_n) - \sum_{i=1}^n \mathbf{I}_{\hat{p}}(X_i, \{X_1, \dots, X_{i-1}\} - Pa_{X_i}^G | Pa_{X_i}^G)$$

- These two interpretations are complementary, one is measuring the strength of dependence between X and its parents, and the other is measuring the extent of the independence of X, from its predecessors given its parents.

Limitations of Likelihood Score



$$\text{Score}_L(G_1 : D) - \text{Score}_L(G_0 : D) = M \cdot \mathbf{I}_p(X, Y)$$

- Since $\mathbf{I}_p(X, Y) \geq 0 \rightarrow \text{Score}_L(G_1 : D) \geq \text{Score}_L(G_0 : D)$
- Adding arcs always helps ←
- Maximal scores attained for fully connected network ↘
- Such networks **overfit** the data (i.e., fit the noise in the data)

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Avoiding Overfitting

- Classical problem in machine learning
- Solutions
 - **Restricting the hypotheses space**
 - Limits the overfitting capability of the learner
 - Example: restrict # of parents or # of parameters
 - **Minimum description length**
 - Description length measures complexity
 - Prefer models that compactly describes the training data
 - **Bayesian methods**
 - Average over all possible parameter values
 - Use prior knowledge

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Bayesian Score }

- Main principle of the Bayesian approach
 - Whenever we have uncertainty over anything, we should place a distribution over it. What uncertainty? (G, Θ_G)

Marginal likelihood

Prior over structures

$$P(G | D) = \frac{P(D | G)P(G)}{P(D)}$$

Marginal probability of Data

$P(D)$ does not depend on the network

Bayesian Score: $Score_B(G : D) = \log P(D | G) + \log P(G)$

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Marginal Likelihood of Data Given G

Bayesian Score: $Score_B(G : D) = \log P(D | G) + \log P(G)$

Likelihood

Prior over parameters

Marginal likelihood

$$P(D | G) = \int_{\theta_G} P(D | G, \theta_G) P(\theta_G | G) d\theta_G$$

Note similarity to maximum likelihood score, but with the key difference that **ML finds maximum of likelihood** and here we compute average of the terms over parameter space

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