

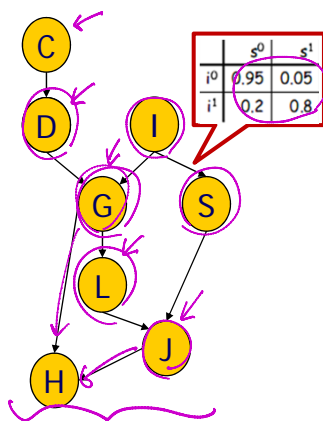


Exact Inference: Variable Elimination

Lecture 6-7 – Apr 13/18, 2011
CSE 515, Statistical Methods, Spring 2011

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University of Washington, Seattle

Let's revisit the *Student Network*

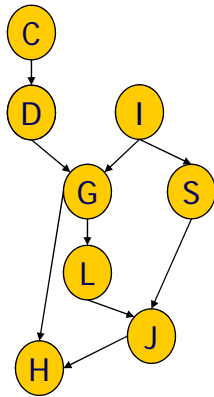


- Binary RVs
 - Coherence
 - Difficulty
 - Intelligence
 - Grade
 - SAT
 - Letter
 - Job
 - Happy

- Notations & abbreviations
 - J : a random variable ←
 - X : a set of random variables
 - $\text{Val}(J)$: a set of values on J
 - i : a value on J
 - $|J|$: size of $\text{Val}(J)$
 - $P(j)$: $P(J=j)$

- Assumptions
 - Local probabilistic models: table CPDs
 - Parameters and structure are given.

Inference Tasks in *Student Network*



- (Conditional) probability queries

- $P(I^1)$ or $P(L=I^1)$
 - $P(h^0)$ or $P(H=h^0)$
 - $P(j^1)$ or $P(J=j^1)$
 - $P(j^1|i^1, d^1)$ or $P(J=j^1|I=i^0, D=d^1)$
 - $P(j^1|h^0, i^1)$ or $P(J=j^1|H=h^0, I=i^1)$
 - $P(j^1, i^0|h^0)$
- Query RV(s) Evidence RV(s)

- How to compute the probabilities?

- Use joint distribution $P(C, D, I, G, S, L, J, H)$ ←

Naïve Approach

- Use full joint distribution $P(C, D, I, G, S, L, J, H)$

- Computing $P(J=j^1)$

$$\begin{aligned}
 P(j^1) = & P(c^0, d^0, i^0, g^0, s^0, l^0, j^1, h^0) \\
 & + P(c^0, d^0, i^0, g^0, s^0, l^0, j^1, h^1) \\
 & + P(c^0, d^0, i^0, g^0, s^0, l^1, j^1, h^0) \\
 & + P(c^0, d^0, i^0, g^0, s^0, l^1, j^1, h^1) \\
 & + P(c^0, d^0, i^0, g^0, s^1, l^0, j^1, h^0) \\
 & + P(c^0, d^0, i^0, g^0, s^1, l^0, j^1, h^1) \\
 & + P(c^0, d^0, i^0, g^0, s^1, l^1, j^1, h^0) \\
 & + P(c^0, d^0, i^0, g^0, s^1, l^1, j^1, h^1) \\
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 & + P(c^0, d^0, i^0, g^1, s^0, l^1, j^1, h^0) \\
 & + P(c^0, d^0, i^0, g^1, s^0, l^1, j^1, h^1) \\
 & + P(c^0, d^0, i^0, g^1, s^1, l^0, j^1, h^0) \\
 & + P(c^0, d^0, i^0, g^1, s^1, l^0, j^1, h^1) \\
 & + P(c^0, d^0, i^0, g^1, s^1, l^1, j^1, h^0) \\
 & + P(c^0, d^0, i^0, g^1, s^1, l^1, j^1, h^1) \\
 & + \dots
 \end{aligned}$$

- Computing $P(I=i^0, J=j^1)$

$$\begin{aligned}
 P(i^0, j^1) = & P(c^0, d^0, i^0, g^0, s^0, l^0, j^1, h^0) \\
 & + P(c^0, d^0, i^0, g^0, s^0, l^0, j^1, h^1) \\
 & + P(c^0, d^0, i^0, g^0, s^0, l^1, j^1, h^0) \\
 & + P(c^0, d^0, i^0, g^0, s^0, l^1, j^1, h^1) \\
 & + P(c^0, d^0, i^0, g^0, s^1, l^0, j^1, h^0) \\
 & + P(c^0, d^0, i^0, g^0, s^1, l^0, j^1, h^1) \\
 & + P(c^0, d^0, i^0, g^0, s^1, l^1, j^1, h^0) \\
 & + P(c^0, d^0, i^0, g^0, s^1, l^1, j^1, h^1) \\
 & + P(c^0, d^0, i^0, g^1, s^0, l^0, j^1, h^0) \\
 & + P(c^0, d^0, i^0, g^1, s^0, l^0, j^1, h^1) \\
 & + P(c^0, d^0, i^0, g^1, s^0, l^1, j^1, h^0) \\
 & + P(c^0, d^0, i^0, g^1, s^0, l^1, j^1, h^1) \\
 & + P(c^0, d^0, i^0, g^1, s^1, l^0, j^1, h^0) \\
 & + P(c^0, d^0, i^0, g^1, s^1, l^0, j^1, h^1) \\
 & + P(c^0, d^0, i^0, g^1, s^1, l^1, j^1, h^0) \\
 & + P(c^0, d^0, i^0, g^1, s^1, l^1, j^1, h^1) \\
 & + \dots
 \end{aligned}$$

- Computational complexity: exponential blowup

- Exploiting the independence properties? ←

Naïve Approach

- $P(C,D,I,G,S,L,J,H) = P(C)P(D|C)P(I)P(G|I,D)P(S|I)P(L|G)P(J|L,S)P(H|G,J)$

- **Computing $P(J)$**

$$P(J) = P(C^0)P(d^0|c^0) P(I^0) [P(g^0|i^0,d^0) P(s^0|i^0)P(l^0|g^0)P(j^1|i^0,s^0)P(h^0|g^0,j^1) \\ + P(g^0|i^0,d^0)P(s^0|i^0)P(l^0|g^0)P(j^1|i^0,s^0)P(h^1|g^0,j^1) \\ + P(g^0|i^0,d^0)P(s^0|i^0)P(l^1|g^0)P(j^1|i^1,s^0)P(h^0|g^0,j^1) \\ + P(g^0|i^0,d^0)P(s^1|i^0)P(l^0|g^0)P(j^1|i^0,s^1)P(h^0|g^0,j^1) \\ + P(g^0|i^0,d^0)P(s^1|i^0)P(l^0|g^0)P(j^1|i^0,s^1)P(h^1|g^0,j^1) \\ + P(g^0|i^0,d^0)P(s^1|i^0)P(l^1|g^0)P(j^1|i^1,s^1)P(h^0|g^0,j^1) \\ + P(g^0|i^0,d^0)P(s^1|i^0)P(l^1|g^0)P(j^1|i^1,s^1)P(h^1|g^0,j^1) \\ + P(g^1|i^0,d^0)P(s^0|i^0)P(l^0|g^1)P(j^1|i^0,s^0)P(h^0|g^1,j^1) \\ + P(g^1|i^0,d^0)P(s^0|i^0)P(l^1|g^1)P(j^1|i^1,s^0)P(h^0|g^1,j^1) \\ + P(g^1|i^0,d^0)P(s^0|i^0)P(l^1|g^1)P(j^1|i^1,s^0)P(h^1|g^1,j^1) \\ + P(g^1|i^0,d^0)P(s^1|i^0)P(l^0|g^1)P(j^1|i^0,s^1)P(h^0|g^1,j^1) \\ + P(g^1|i^0,d^0)P(s^1|i^0)P(l^0|g^1)P(j^1|i^0,s^1)P(h^1|g^1,j^1) \\ + P(g^1|i^0,d^0)P(s^1|i^0)P(l^1|g^1)P(j^1|i^1,s^1)P(h^0|g^1,j^1) \\ + P(g^1|i^0,d^0)P(s^1|i^0)P(l^1|g^1)P(j^1|i^1,s^1)P(h^1|g^1,j^1) \\ + \dots]$$

Certain terms are repeated several times

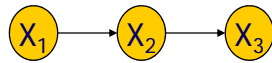
- Exploiting the structure can reduce computation.
- Let's systematically analyze computational complexity.

Let's start with the simplest network ...

Exact Inference Variable Elimination

- Inference in a simple chain

- Computing $P(X_2)$



$P(X_1), P(X_2|X_1), P(X_3|X_2)$

$$P(X_2) = \sum_{x_1} P(x_1, X_2)$$

The equation is annotated with pink circles around $P(X_2)$ and x_1 . A pink arrow points from the summation symbol to a pink oval. Another pink arrow points from the pink oval to a larger pink oval. A blue arrow points upwards from the text below towards the larger pink oval.

All the numbers for this computation are in the CPDs of the original Bayesian network

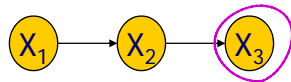
$O(\text{cardinality})$ operations

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Exact Inference Variable Elimination

- Inference in a simple chain

- Computing $P(X_2)$



- Computing $P(X_3)$

$$P(X_2) = \sum_{x_1} P(x_1, X_2) = \sum_{x_1} P(x_1)P(X_2 | x_1)$$

$$P(X_3) = \sum_{x_2} P(x_2, X_3)$$

The equations are annotated with pink circles around $P(X_2)$ and $P(X_3)$. A pink arrow points from the second equation to the first. A pink arrow points from the word 'CPD' to the second equation. A pink arrow points from the word 'CPD' to the second equation. A blue arrow points upwards from the text below towards the second equation.

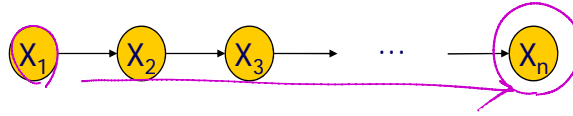
- $P(X_3|X_2)$ is a given CPD

- $P(X_2)$ was computed above

- $O(\text{cardinality})$ operations

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Exact Inference: Variable Elimination



■ Inference in a general chain

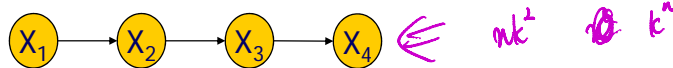
- Computing $P(X_n)$
 - Compute each $P(X_i)$ from $P(X_{i-1})$
 - k^2 operations for each computation for X_i (assuming $|X_i|=k$)
 - $O(nk^2)$ operations for the inference
 - Compare to k^n operations required in summing over all possible entries in the joint distribution over X_1, \dots, X_n
- Inference in a general chain can be done in linear time!

$P(X_n)$
 $O(nk^2)$

$O(nk^2)$

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Exact Inference: Variable Elimination



$$\begin{aligned}
 P(X_4) &= \sum_{X_1} \sum_{X_2} \sum_{X_3} P(X_1, X_2, X_3, X_4) \\
 &= \sum_{X_1} \sum_{X_2} \sum_{X_3} P(X_1)P(X_2 | X_1)P(X_3 | X_2)P(X_4 | X_3) \\
 &= \sum_{X_3} P(X_4 | X_3) \sum_{X_2} P(X_3 | X_2) \sum_{X_1} P(X_1)P(X_2 | X_1) \\
 &= \sum_{X_3} P(X_4 | X_3) \sum_{X_2} P(X_3 | X_2) \phi(X_2) \rightarrow P(X_2) \\
 &= \sum_{X_3} P(X_4 | X_3) \phi(X_3) \rightarrow P(X_3) \\
 &= \phi(X_4)
 \end{aligned}$$

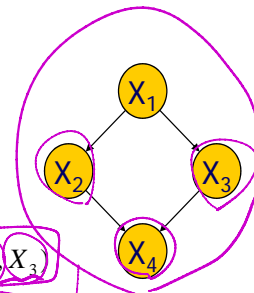
Pushing summations = Dynamic programming

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Inference With a Loop

- Computing $P(X_4)$

$$\begin{aligned}
 P(X_4) &= \sum_{X_1} \sum_{X_2} \sum_{X_3} P(X_1, X_2, X_3, X_4) \\
 &= \sum_{X_1} \sum_{X_2} \sum_{X_3} P(X_1)P(X_2 | X_1)P(X_3 | X_1)P(X_4 | X_2, X_3) \\
 &= \sum_{X_2} \sum_{X_3} P(X_4 | X_2, X_3) \sum_{X_1} P(X_1)P(X_2 | X_1)P(X_3 | X_1) \\
 &= \sum_{X_2} \sum_{X_3} P(X_4 | X_2, X_3) \phi(X_{2,3}) \\
 &= \sum_{X_2} \phi(X_2, X_4) \\
 &= \phi(X_4)
 \end{aligned}$$



- Differences
 - Summations are not "pushed in" as far as before.
 - The scope of ϕ includes two variables, not one.
- Depends on network structure

Efficient Inference in Bayesnets

- Properties that allow us to **avoid exponential blowup** in the joint distribution
 - Bayesian network structure – some subexpressions depend on a small number of variables
 - Computing these subexpressions and caching the results avoids generating them exponentially many times

Variable Elimination: Factors

- Inference algorithm defined in terms of factors
- Factors generalize the notion of CPDs
- A factor ϕ is a function from value assignments of a set of random variables \mathbf{D} to real positive numbers \mathfrak{R}^+
 - The set of variables \mathbf{D} is the scope of the factor
- Thus, the algorithm we describe applies both to Bayesian networks and Markov networks

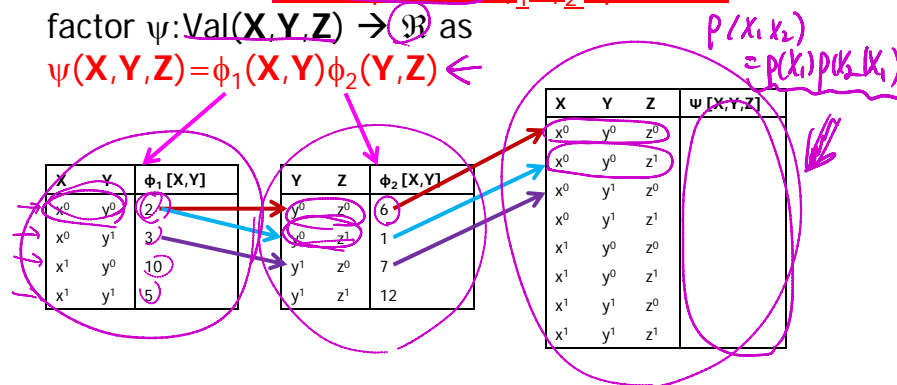
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Operations on Factors I: Product

- Let $\mathbf{X}, \mathbf{Y}, \mathbf{Z}$ be three sets of disjoint sets of RVs, and let $\phi_1(\mathbf{X}, \mathbf{Y})$ and $\phi_2(\mathbf{Y}, \mathbf{Z})$ be two factors

- We define the factor product $\phi_1 \times \phi_2$ operation to be a factor $\psi: \text{Val}(\mathbf{X}, \mathbf{Y}, \mathbf{Z}) \rightarrow \mathfrak{R}$ as

$$\psi(\mathbf{X}, \mathbf{Y}, \mathbf{Z}) = \phi_1(\mathbf{X}, \mathbf{Y}) \phi_2(\mathbf{Y}, \mathbf{Z}) \leftarrow$$



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Operations on Factors II: Marginalization

- Let \mathbf{X} be a set of RVs, $Y \notin \mathbf{X}$ a RV, and $\phi(\mathbf{X}, Y)$ a factor
- We define the **factor marginalization of Y in \mathbf{X}** to be a factor $\psi: \text{Val}(\mathbf{X}) \rightarrow \mathfrak{R}$ as $\psi(\mathbf{X}) = \sum_Y \phi(\mathbf{X}, Y)$
- Also called **summing out** ← $p(x_2) = \sum_{x_1} p(x_1) p(x_2 | x_1)$
- In a Bayesian network, summing out all variables =
- In a Markov network, summing out all variables is the

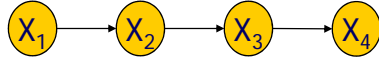
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More on Factors

- For factors ϕ_1 and ϕ_2 :
- Factors are **commutative**
 - $\phi_1 \times \phi_2 = \phi_2 \times \phi_1$
 - $\sum_X \sum_Y \phi(\mathbf{X}, \mathbf{Y}) = \sum_Y \sum_X \phi(\mathbf{X}, \mathbf{Y})$
- Products are **associative**
 - $(\phi_1 \times \phi_2) \times \phi_3 = \phi_1 \times (\phi_2 \times \phi_3)$
- If $\mathbf{X} \notin \text{Scope}[\phi_1]$ (we used this in elimination above)
 - $\sum_X \phi_1 \times \phi_2 = \phi_1 \times \sum_X \phi_2$ ←

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Inference in Chain by Factors



$$\begin{aligned}
 P(X_4) &= \sum_{X_1} \sum_{X_2} \sum_{X_3} P(X_1, X_2, X_3, X_4) \\
 &= \sum_{X_1} \sum_{X_2} \sum_{X_3} \phi_{X_1} \times \phi_{X_2} \times \phi_{X_3} \times \phi_{X_4} \\
 &= \sum_{X_3} \sum_{X_2} \phi_{X_4} \times \phi_{X_3} \times \left(\sum_{X_1} \phi_{X_1} \times \phi_{X_2} \right) \\
 &= \sum_{X_3} \phi_{X_4} \times \left(\sum_{X_2} \phi_{X_3} \times \left(\sum_{X_1} \phi_{X_1} \times \phi_{X_2} \right) \right)
 \end{aligned}$$

Scope of ϕ_{X_3} and ϕ_{X_4} does not contain X_1
 Scope of ϕ_{X_4} does not contain X_2

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Sum-Product Inference

- Let **Y** be the query RVs and **Z** be all other RVs
- We can generalize this task as that of computing the value of an expression of the form:

$$\phi(Y) = \sum_{Z} \prod_{\phi' \in F} \phi'$$

- Call it sum-product inference task.
- Effective computation
 - The scope of the factors is limited. ←
 - → "Push in" some of the summations, performing them over the product of only a subset of factors

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Sum-Product Variable Elimination

Algorithm

- Given an ordering of variables Z_1, \dots, Z_n $X_1 \dots X_m$
- **Sum out** the variables one at a time
- When summing out each variable Z_i
 - Multiply all the factors ϕ 's that mention the variable Z_i generating a product factor ψ
 - **Sum out** the variable from the combined factor ψ , generating a new factor f without the variable Z_i

Sum out

- Let \mathbf{X} be a set of RVs, $Y \notin \mathbf{X}$ a RV, and $\phi(\mathbf{X}, Y)$ a factor
- We define the **factor marginalization** of Y in \mathbf{X} to be a factor $\psi: \text{Val}(\mathbf{X}) \rightarrow \mathbb{R}$ as $\psi(\mathbf{X}) = \sum_Y \phi(\mathbf{X}, Y)$
- Also called **summing out**

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Sum-Product Variable Elimination

Theorem

- Let \mathbf{X} be a set of RVs
- Let $\mathbf{Y} \subseteq \mathbf{X}$ be a set of query RVs
- Let $\mathbf{Z} = \mathbf{X} - \mathbf{Y}$
- \rightarrow For any ordering α over \mathbf{Z} , the above algorithm returns a factor $\phi(\mathbf{Y})$ such that

$$\phi(\mathbf{Y}) = \sum_{\mathbf{Z}} \prod_{\phi' \in F} \phi'$$

Bayesian network query $P_G(\mathbf{Y})$

- F consists of all CPDs in G $F = \{\phi_{X_i}\}_{i=1}^n$
- Each $\phi_{X_i} = P(X_i | \text{Pa}(X_i))$
- Apply **variable elimination** for $\mathbf{Z} = \mathbf{X} - \mathbf{Y}$ (summing out \mathbf{Z})

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Example – Let's consider a little more complex network...

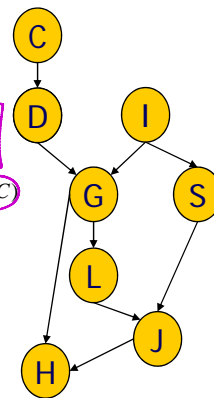
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A More Complex Network

- Goal: $P(J)$
- Eliminate: C, D, I, H, G, S, L ←

$$P(J) = \sum_{L,S,G,H,I,D,C} P(J|L,S)P(L|G)P(S|I)P(G|I,D)P(H|G,J)P(I)P(C|D)P(C)$$

$$P(J) = \sum_{L,S,G,H,I,D,C} \phi_J(J,L,S)\phi_L(L,G)\phi_S(S,I)\phi_G(G,I,D)\phi_H(H,G,J)\phi_I(I)\phi_D(C,D)\phi_C(C)$$



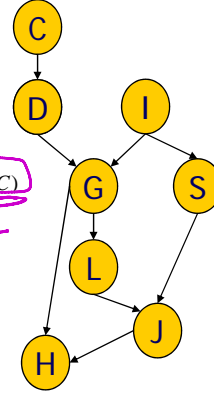
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A More Complex Network

- Goal: $P(J)$
- Eliminate: C, D, I, H, G, S, L
- Compute: $f_1(D) = \sum_C \phi_C(C) \phi_D(C, D)$

$$P(J) = \sum_{L,S,G,H,I,D,C} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_G(G,I,D) \phi_H(H,G,J) \phi_I(I) \phi_D(C,D) \phi_C(C)$$

$$= \sum_{L,S,G,H,I,D} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_G(G,I,D) \phi_H(H,G,J) \phi_I(I) f_1(D)$$



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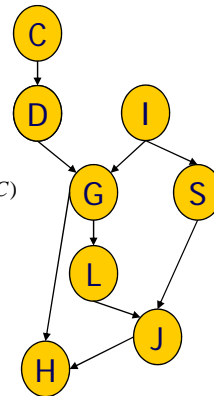
A More Complex Network

- Goal: $P(J)$
- Eliminate: C, D, I, H, G, S, L
- Compute: $f_2(G,I) = \sum_D \phi_G(G,I,D) f_1(D)$

$$P(J) = \sum_{L,S,G,H,I,D,C} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_G(G,I,D) \phi_H(H,G,J) \phi_I(I) \phi_D(C,D) \phi_C(C)$$

$$= \sum_{L,S,G,H,I,D} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_G(G,I,D) \phi_H(H,G,J) \phi_I(I) f_1(D)$$

$$= \sum_{L,S,G,H,I} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_H(H,G,J) \phi_I(I) f_2(G,I)$$

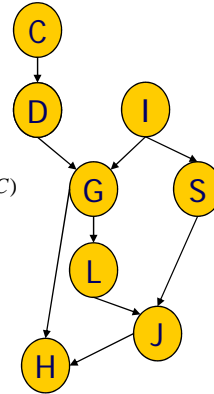


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A More Complex Network

- Goal: $P(J)$
- Eliminate: C, D, I, H, G, S, L
- Compute: $f_3(G, S) = \sum_I \phi_I(I) \phi_S(S, I) f_2(G, I)$

$$\begin{aligned}
 P(J) &= \sum_{L,S,G,H,I,D,C} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) \phi_D(C, D) \phi_C(C) \\
 &= \sum_{L,S,G,H,I,D} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) f_1(D) \\
 &= \sum_{L,S,G,H,I} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_H(H, G, J) \phi_I(I) f_2(G, I) \\
 &= \sum_{L,S,G,H} \phi_J(J, L, S) \phi_L(L, G) \phi_H(H, G, J) f_3(G, S)
 \end{aligned}$$

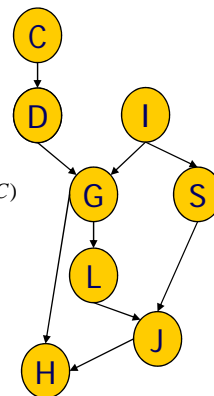


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A More Complex Network

- Goal: $P(J)$
- Eliminate: C, D, I, H, G, S, L
- Compute: $f_4(G, J) = \sum_H \phi_H(H, G, J)$

$$\begin{aligned}
 P(J) &= \sum_{L,S,G,H,I,D,C} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) \phi_D(C, D) \phi_C(C) \\
 &= \sum_{L,S,G,H,I,D} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) f_1(D) \\
 &= \sum_{L,S,G,H,I} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_H(H, G, J) \phi_I(I) f_2(G, I) \\
 &= \sum_{L,S,G,H} \phi_J(J, L, S) \phi_L(L, G) \phi_H(H, G, J) f_3(G, S) \\
 &= \sum_{L,S,G} \phi_J(J, L, S) \phi_L(L, G) f_3(G, S) f_4(G, J)
 \end{aligned}$$

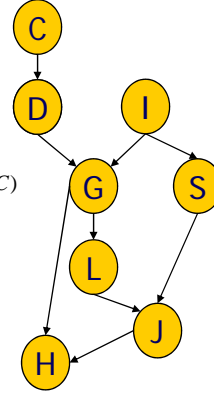


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A More Complex Network

- Goal: $P(J)$
- Eliminate: C, D, I, H, G , S, L
- Compute: $f_5(J, L, S) = \sum_G \phi_L(L, G) f_3(G, S) f_4(G, J)$

$$\begin{aligned}
 P(J) &= \sum_{L,S,G,H,I,D,C} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) \phi_D(C, D) \phi_C(C) \\
 &= \sum_{L,S,G,H,I,D} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) f_1(D) \\
 &= \sum_{L,S,G,H,I} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_H(H, G, J) \phi_I(I) f_2(G, I) \\
 &= \sum_{L,S,G,H} \phi_J(J, L, S) \phi_L(L, G) \phi_H(H, G, J) f_3(G, S) \\
 &= \sum_{L,S,G} \phi_J(J, L, S) \phi_L(L, G) f_3(G, S) f_4(G, J) \\
 &= \sum_{L,S} \phi(J, L, S) f_5(J, L, S)
 \end{aligned}$$

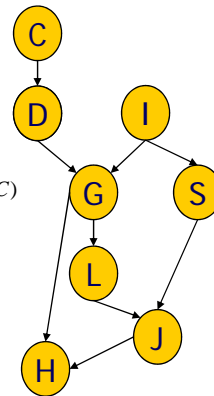


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A More Complex Network

- Goal: $P(J)$
- Eliminate: C, D, I, H, G, S, L
- Compute: $f_6(J, L) = \sum_S \phi(J, L, S) f_5(J, L, S)$

$$\begin{aligned}
 P(J) &= \sum_{L,S,G,H,I,D,C} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) \phi_D(C, D) \phi_C(C) \\
 &= \sum_{L,S,G,H,I,D} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) f_1(D) \\
 &= \sum_{L,S,G,H,I} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_H(H, G, J) \phi_I(I) f_2(G, I) \\
 &= \sum_{L,S,G,H} \phi_J(J, L, S) \phi_L(L, G) \phi_H(H, G, J) f_3(G, S) \\
 &= \sum_{L,S,G} \phi_J(J, L, S) \phi_L(L, G) f_3(G, S) f_4(G, J) \\
 &= \sum_{L,S} \phi(J, L, S) f_5(J, L, S) \\
 &= \sum_L f_6(J, L)
 \end{aligned}$$

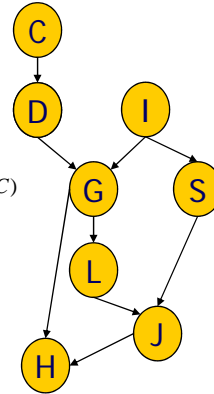


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A More Complex Network

- Goal: $P(J)$
- Eliminate: C,D,I,H,G,S,L
- Compute: $f_7(J) = \sum_L f_6(J,L)$

$$\begin{aligned}
 P(J) &= \sum_{L,S,G,H,I,D,C} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_G(G,I,D) \phi_H(H,G,J) \phi_I(I) \phi_D(C,D) \phi_C(C) \\
 &= \sum_{L,S,G,H,I,D} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_G(G,I,D) \phi_H(H,G,J) \phi_I(I) f_1(D) \\
 &= \sum_{L,S,G,H,I} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_H(H,G,J) \phi_I(I) f_2(G,I) \\
 &= \sum_{L,S,G,H} \phi_J(J,L,S) \phi_L(L,G) \phi_H(H,G,J) f_3(G,S) \\
 &= \sum_{L,S,G} \phi_J(J,L,S) \phi_L(L,G) f_3(G,S) f_4(G,J) \\
 &= \sum_{L,S} \phi(J,L,S) f_5(J,L,S) \\
 &= \sum_L f_6(J,L) \\
 &= f_7(J)
 \end{aligned}$$

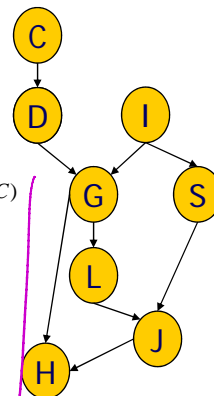


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A More Complex Network

- Goal: $P(J)$
- Eliminate: G,I,S,L,H,C,D (different ordering)

$$\begin{aligned}
 P(J) &= \sum_{G,I,S,L,H,C,D} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_G(G,I,D) \phi_H(H,G,J) \phi_I(I) \phi_D(C,D) \phi_C(C) \\
 &= \sum_{I,S,L,H,C,D} \phi_J(J,L,S) \phi_S(S,I) \phi_I(I) \phi_D(C,D) \phi_C(C) f_1(I,D,L,J,H) \\
 &= \sum_{S,L,H,C,D} \phi_J(J,L,S) \phi_D(C,D) \phi_C(C) f_2(D,L,S,J,H) \\
 &= \sum_{L,H,C,D} \phi_D(C,D) \phi_C(C) f_3(D,L,J,H) \\
 &= \sum_{H,C,D} \phi_D(C,D) \phi_C(C) f_4(D,J,H) \\
 &= \sum_{C,D} \phi_D(C,D) \phi_C(C) f_5(D,J) \\
 &= \sum_D f_5(D,J) f_6(D,J) \\
 &= f_7(J)
 \end{aligned}$$



■ Note: intermediate factors tend to be large $f_1(I,D,L,J,H)$ → ordering matters ←

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Inference With Evidence

- Computing $P(\mathbf{Y} | \mathbf{E} = \mathbf{e})$ ← $\frac{p(\mathbf{Y}, \mathbf{E} = \mathbf{e})}{P(\mathbf{E} = \mathbf{e})}$
- Let \mathbf{Y} be the query RVs
- Let \mathbf{E} be the evidence RVs and \mathbf{e} their assignment
- Let \mathbf{Z} be all other RVs ($U - \mathbf{Y} - \mathbf{E}$)
- The general inference task is

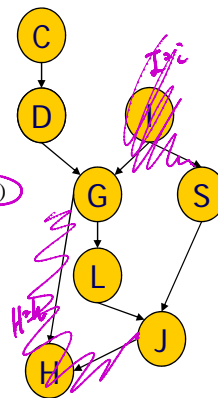
$$\frac{\phi(\mathbf{Y}, \mathbf{e})}{\phi(\mathbf{e})} = \frac{\sum_{\mathbf{Z}} \prod_{X \in U} \phi_{X|E=\mathbf{e}}}{\sum_{\mathbf{Z}} \prod_{X \in U} \phi_{X|E=\mathbf{e}}} \quad E = \mathbf{e}$$

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Inference With Evidence

- Goal: $P(J | H=h, I=i)$ ←
- Eliminate: C, D, G, S, I
- Below, compute $f(J, H=h, I=i)$

$$\begin{aligned} P(J, h, i) &= \sum_{L, S, G, D, C} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, i) \phi_G(G, i, D) \phi_H(h, G, J) \phi_I(i) \phi_D(C, D) \phi_C(C) \\ &= \sum_{L, S, G, D} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, i) \phi_G(G, i, D) \phi_H(h, G, J) \phi_I(i) f_1(D) \\ &= \sum_{L, S, G} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, i) \phi_H(h, G, J) \phi_I(i) f_2(G, i) \\ &= \sum_{L, S} \phi_J(J, L, S) \phi_S(S, i) f_3(L, J) \\ &= \sum_L f_4(L, J) \\ &= f_5(J) \end{aligned}$$



- Differences
 - Less number of variables to be eliminated (H and I are excluded)
 - Scope of factors tend to be smaller.

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What's the complexity of variable elimination?

Complexity of Variable Elimination

- Variable elimination complexity

- Generating the factors f_i
- Summing out

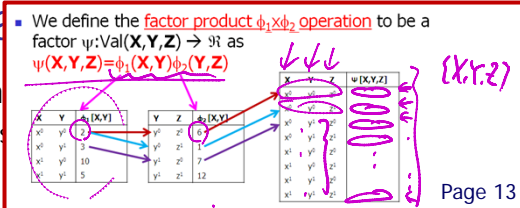
- Generating the factor $f_i = \phi_1(x_1, \dots, x_k)$ through factor product operation

- Let X_i be the scope of f_i
- Each entry requires k_i multiplications to generate
- Generating factor f_i is

- Summing out

- Addition operations, at most $|\text{Val}(X_i)|$

- Per factor: $O(kN)$ where $N = \max_i |\text{Val}(X_i)|$, $k = \max_i k_i$



Complexity of Variable Elimination

- Start with n factors ($n = \text{number of variables}$)
- Generate exactly one factor at each iteration } $\sum_{i=1}^n PCH(G, J) = 1$
 → there are at most $2n$ factors
- Generating factors (Say $N = \max_i |\text{Val}(X_i)|$)
 - At most $\sum_i |\text{Val}(X_i)| k_i \leq N \sum_i k_i \leq N \cdot 2n$ (since each factor is multiplied in exactly once and there are $2n$ factors)
- Summing out
 - $\sum_i |\text{Val}(X_i)| \leq N \cdot n$ (since we have n summing outs to do)
- Total work is linear in N and n , where $N = \max_i |\text{Val}(X_i)|$ $O(Nn)$
- Exponential blowup can be in N_i which for factor i can be v^m if factor i has m variables with v values each
- Interpretation: **maximum scope size** is important. ↖

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Factors and Undirected Graphs

- The algorithm does not care whether the graph that generated the factors is directed or undirected.
 - The algorithm's input is a set of factors, and the only relevant aspect to the computational is **the scope of the factors**.
- Let's view the algorithm as operating on an undirected graph H .
 - For Bayesian networks, we consider the **moralized Markov network** of the original BNs.
- How does the network structure change in each variable elimination step?

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VE as Graph Transformation

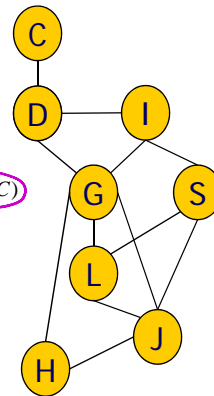
- At each step we are computing $f_i = \sum_{x_i} \prod_j f_j(z_j)$
- Plot a graph where there is an undirected edge $X-Y$ if variables X and Y appear in the same factor
- Note:** this is the Markov network of the probability on the variables that were not eliminated yet

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VE as Graph Transformation

- Goal:** $P(J)$
- Eliminate:** C, D, I, H, G, S, L

$$P(J) = \sum_{L,S,G,H,I,D,C} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_G(G,I,D) \phi_H(H,G,J) \phi_I(I) \phi_D(C,D) \phi_C(C)$$



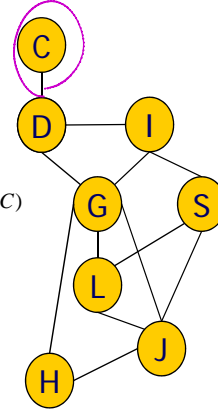
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VE as Graph Transformation

- Goal: P(J)
- Eliminate: C, D, I, H, G, S, L
- Compute: $f_1(D) = \sum_C \phi_C(C) \phi_D(C, D)$

$$P(J) = \sum_{L,S,G,H,I,D,C} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_G(G,I,D) \phi_H(H,G,J) \phi_I(I) \phi_D(C,D) \phi_C(C)$$

$$= \sum_{L,S,G,H,I,D} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_G(G,I,D) \phi_H(H,G,J) \phi_I(I) f_1(D) \leftarrow$$



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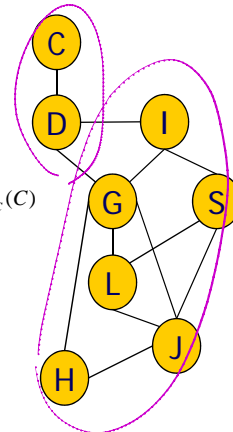
VE as Graph Transformation

- Goal: P(J)
- Eliminate: C, D, I, H, G, S, L
- Compute: $f_2(G,I) = \sum_D \phi_G(G,I,D) f_1(D)$

$$P(J) = \sum_{L,S,G,H,I,D,C} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_G(G,I,D) \phi_H(H,G,J) \phi_I(I) \phi_D(C,D) \phi_C(C)$$

$$= \sum_{L,S,G,H,I,D} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_G(G,I,D) \phi_H(H,G,J) \phi_I(I) f_1(D)$$

$$= \sum_{L,S,G,H,I} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_H(H,G,J) \phi_I(I) f_2(G,I) \leftarrow$$

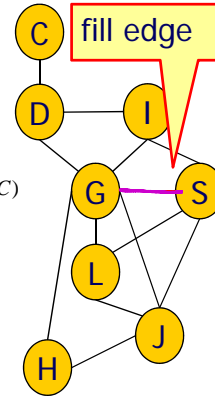


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VE as Graph Transformation

- Goal: $P(J)$
- Eliminate: C, D, I, H, G, S, L
- Compute: $f_3(G, S) = \sum_I \phi_I(I) \phi_S(S, I) f_2(G, I)$

$$\begin{aligned}
 P(J) &= \sum_{L,S,G,H,I,D,C} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) \phi_D(C, D) \phi_C(C) \\
 &= \sum_{L,S,G,H,I,D} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) f_1(D) \\
 &= \sum_{L,S,G,H,I} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_H(H, G, J) \phi_I(I) f_2(G, I) \\
 &= \sum_{L,S,G,H} \phi_J(J, L, S) \phi_L(L, G) \phi_H(H, G, J) \boxed{f_3(G, S)} \leftarrow
 \end{aligned}$$

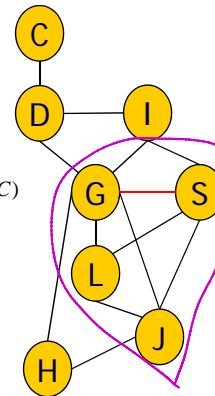


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VE as Graph Transformation

- Goal: $P(J)$
- Eliminate: C, D, I, H, G, S, L
- Compute: $f_4(G, J) = \sum_H \phi_H(H, G, J)$

$$\begin{aligned}
 P(J) &= \sum_{L,S,G,H,I,D,C} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) \phi_D(C, D) \phi_C(C) \\
 &= \sum_{L,S,G,H,I,D} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) f_1(D) \\
 &= \sum_{L,S,G,H,I} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_H(H, G, J) \phi_I(I) f_2(G, I) \\
 &= \sum_{L,S,G,H} \phi_J(J, L, S) \phi_L(L, G) \phi_H(H, G, J) \boxed{f_3(G, S)} \leftarrow \\
 &= \sum_{L,S,G} \phi_J(J, L, S) \phi_L(L, G) f_3(G, S) f_4(G, J)
 \end{aligned}$$

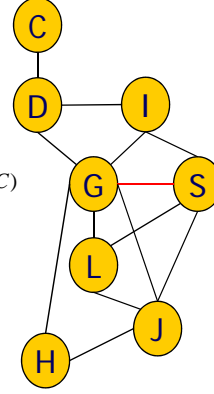


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VE as Graph Transformation

- Goal: P(J)
- Eliminate: C,D,I,H,G,S,L
- Compute: $f_5(J, L, S) = \sum_G \phi_L(L, G) f_3(G, S) f_4(G, J)$

$$\begin{aligned}
 P(J) &= \sum_{L,S,G,H,I,D,C} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) \phi_D(C, D) \phi_C(C) \\
 &= \sum_{L,S,G,H,I,D} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) f_1(D) \\
 &= \sum_{L,S,G,H,I} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_H(H, G, J) \phi_I(I) f_2(G, I) \\
 &= \sum_{L,S,G,H} \phi_J(J, L, S) \phi_L(L, G) \phi_H(H, G, J) f_3(G, S) \\
 &= \sum_{L,S,G} \phi_J(J, L, S) \phi_L(L, G) f_3(G, S) f_4(G, J) \\
 &= \sum_{L,S} \phi(J, L, S) f_5(J, L, S)
 \end{aligned}$$

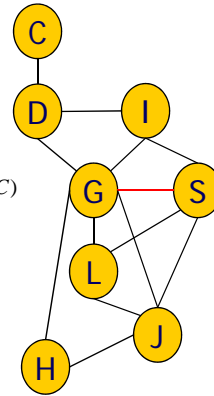


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VE as Graph Transformation

- Goal: P(J)
- Eliminate: C,D,I,H,G,S,L
- Compute: $f_6(J, L) = \sum_S \phi(J, L, S) f_5(J, L, S)$

$$\begin{aligned}
 P(J) &= \sum_{L,S,G,H,I,D,C} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) \phi_D(C, D) \phi_C(C) \\
 &= \sum_{L,S,G,H,I,D} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_G(G, I, D) \phi_H(H, G, J) \phi_I(I) f_1(D) \\
 &= \sum_{L,S,G,H,I} \phi_J(J, L, S) \phi_L(L, G) \phi_S(S, I) \phi_H(H, G, J) \phi_I(I) f_2(G, I) \\
 &= \sum_{L,S,G,H} \phi_J(J, L, S) \phi_L(L, G) \phi_H(H, G, J) f_3(G, S) \\
 &= \sum_{L,S,G} \phi_J(J, L, S) \phi_L(L, G) f_3(G, S) f_4(G, J) \\
 &= \sum_{L,S} \phi(J, L, S) f_5(J, L, S) \\
 &= \sum_L f_6(J, L)
 \end{aligned}$$

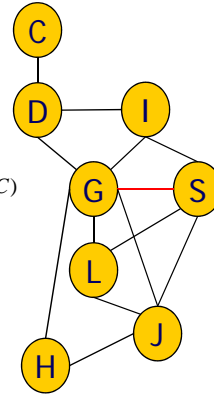


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VE as Graph Transformation

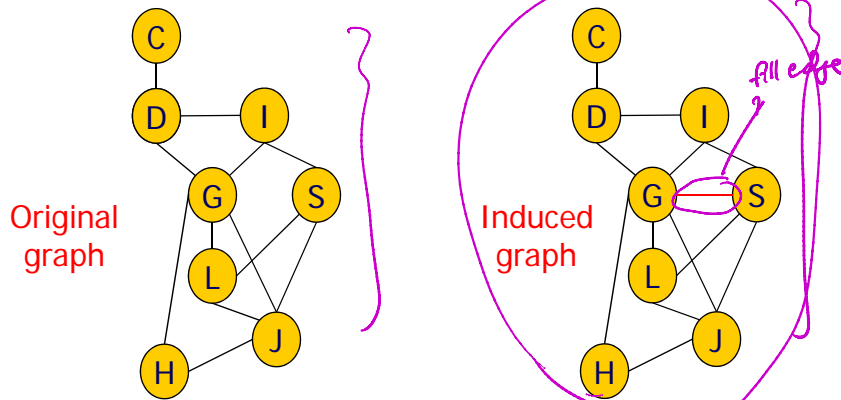
- Goal: $P(J)$
- Eliminate: C,D,I,H,G,S,L
- Compute: $f_7(J) = \sum_L f_6(J,L)$

$$\begin{aligned}
 P(J) &= \sum_{L,S,G,H,I,D,C} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_G(G,I,D) \phi_H(H,G,J) \phi_I(I) \phi_D(C,D) \phi_C(C) \\
 &= \sum_{L,S,G,H,I,D} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_G(G,I,D) \phi_H(H,G,J) \phi_I(I) f_1(D) \\
 &= \sum_{L,S,G,H,I} \phi_J(J,L,S) \phi_L(L,G) \phi_S(S,I) \phi_H(H,G,J) \phi_I(I) f_2(G,I) \\
 &= \sum_{L,S,G,H} \phi_J(J,L,S) \phi_L(L,G) \phi_H(H,G,J) f_3(G,S) \\
 &= \sum_{L,S,G} \phi_J(J,L,S) \phi_L(L,G) f_3(G,S) f_4(G,J) \\
 &= \sum_{L,S} \phi(J,L,S) f_5(J,L,S) \\
 &= \sum_L f_6(J,L) \\
 &= f_7(J)
 \end{aligned}$$



The Induced Graph

- The induced graph $I_{F,\alpha}$ over factors F and ordering α :
 - Union of all of the graphs resulting from the different steps of the variable elimination algorithm.
 - X_i and X_j are connected if they appeared in the same factor throughout the VE algorithm using α as the ordering



The Induced Graph

- The **induced graph** $I_{F,\alpha}$ over factors F and ordering α :
 - Undirected
 - X_i and X_j are connected if they appeared in the same factor throughout the VE algorithm using α as the ordering
- The **width of an induced graph** $w(I_K)$ is the number of nodes in the largest clique in the graph minus 1
 - **Minimal induced width** of a graph K is $\min_{\alpha} w(I_{K,\alpha})$
 - Minimal induced width provides a **lower bound on best performance** by applying VE to a model that factorized on K
- How can we compute the minimal induced width of the graph, and the elimination ordering achieving that width?
 - No easy way to answer this question.

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The Induced Graph

- Finding the optimal ordering is NP-hard
- Hopeless? No, **heuristic techniques** can find good elimination orderings
- **Greedy search using heuristic cost function**
 - We eliminate variables one at a time in a **greedy way**, so that each step tends to lead to a small blowup in size.
 - At each point, find the node with smallest **cost**
 - Possible costs: **number of neighbors in current graph**, **neighbors of neighbors**, **number of filling edges**

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Inference should be efficient for certain kinds of graphs ...

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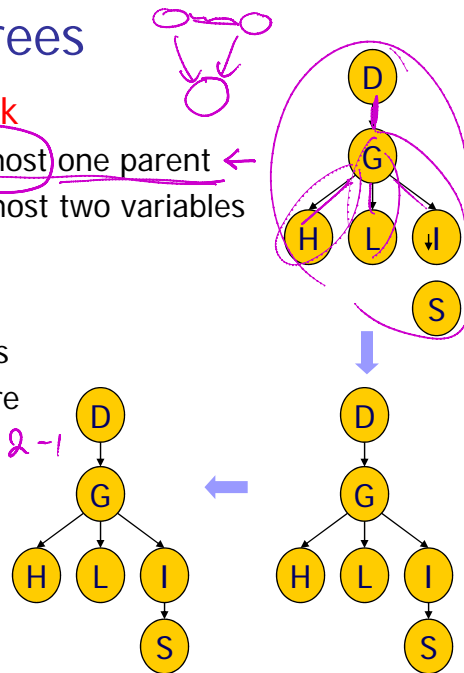
Elimination On Trees

- **Tree Bayesian network**

- Each variable has at most one parent
- All factors involve at most two variables

- **Elimination**

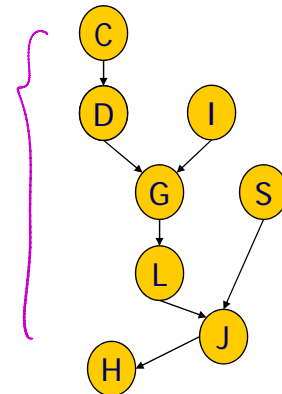
- Eliminate leaf variables
- Maintains tree structure
- Induced width = 1



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Elimination on PolyTrees

- PolyTree Bayesian network ←
 - At most one path between any two variables
- Theorem: inference is linear in the network representation size



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For a fixed graph structure,
is there any way to reduce
the induced width?

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Inference By Conditioning

- General idea

- Enumerate the possible values of a variable
- Apply Variable Elimination in a simplified network
- Aggregate the results

$$p(J) = \sum_{I \text{ all values}} p(C, D, Z, \dots)$$

$$= \sum_{I=i^0} q(I=i^0) p(I=i^0) + \sum_{I=i^1} q(I=i^1) p(I=i^1)$$

Transform CPDs of G and S to eliminate I as parent

