## Lecture 15

## Minimization of Submodular Functions in Polynomial Time; Edmond's Theorem

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## 15.1 Submodular function minimization

$$\begin{split} f: 2^U &\to \{i | i \text{ is a } k \text{-bit integer} \} \\ |U| &= n \\ \forall S, Tf(S) + f(T) \geq f(S \cap T) + f(S \cup T) \end{split}$$

A strongly polynomial algorithm would be polynomial in n. But instead we will have polynomial in (n, k).

Write integer program. S is represented by its characteristic 0-1 vector.  $f(x_1, x_2, \ldots, x_n)$ , where ever f is 1 compute f on that particular S.

$$\min \quad f(x_1, x_2, \dots, x_n)$$
$$x_i \in \{0, 1\}$$

Relax to:  $0 \le x_i \le 1$ . The minimum we'll give by another program because we don't know how to interpret  $x_i = 0.8$  for example.

$$\min \qquad \sum_{S} \lambda_{S} f(S) \\ \forall i \qquad \sum_{S:i \in S} \lambda_{S} = x_{i} \\ \sum_{S} \lambda_{S} = 1 \\ \lambda_{S} \ge 0$$

Write the x vector as a convex combination over integer vectors. I.e. (0.5, 0.5) becomes  $\frac{1}{2}(0,0) + \frac{1}{2}(1,1)$ . Think of the unit cube. This function is defined on all corner points of the cube initially. Any point inside can be written as a convex combination of the corner points. We try to minimize the convex combination.

**Claim 1.** The solution of this LP is optimized at integral  $x_i$ s.

In fact, this is true even if f is not submodular.

*Proof.* Suppose not, i.e., suppose it is minimized at some  $f(x_1, x_2, ..., x_n)$  and  $x_i$  is fractional. Then by definition  $f(x_1, x_2, ..., x_n) = \sum \lambda_S f(S)$ . One of the f(S)'s must be smaller than  $f(x_1, x_2, ..., x_n)$ , so f wasn't minimized.

Given any number  $b, f(x_1, x_2, \ldots, x_n) \le b. \ 0 \le x_i \le 1 \Rightarrow$  convex.

Since this is a convex program, we can run the ellipsoid algorithm. If we have a feasible solution for x, y, then we have a solution for (x + y)/2. The convex constraints are:

$$f(x_1, x_2, \dots, x_n) \leq b$$
  

$$f(y_1, y_2, \dots, y_n) \leq b$$
  

$$0 \leq x_i \leq 1$$
  

$$0 \leq y_i \leq 1$$

Then there exist  $\lambda_S$ 's satisfying

$$\sum_{S} \lambda_{S}^{x} f(S) = f(x_{1}, x_{2}, \dots, x_{n})$$
  
$$\forall i \sum_{S: i \in S} \lambda_{S}^{x} = x_{i}$$
  
$$\sum_{S} \lambda_{S}^{x} = 1$$
  
$$\lambda_{S}^{x} \ge 0$$

True for y as well. So:

$$\sum_{S} \lambda_{S}^{x} f(S) \leq b$$
$$\sum_{S} \lambda_{S}^{y} f(S) \leq b$$
$$\sum_{S:i \in S} \lambda_{S} = (x_{i} + y_{i})/2$$

The minimum  $(\lambda_S^x + \lambda_S^y)/2$  will be  $\leq b$ . So it is also convex.

**Claim 2.** There exists an optimal solution to this program such that  $\forall S, T : S \notin T$  and  $T \notin S$  then either  $\lambda_S = 0$  or  $\lambda_T = 0$ .

In other words, the only valid picture for S is concentric circles; you would never have two separate, non-overlapping circles, or two circles with an intersection.

*Proof.* Among all optimum solutions of this program, pick the one which maximizes  $\sum_{S} \lambda_{S} |S|^{2}$ .

$$|S|^{2} + |T|^{2} \le |S \cap T|^{2} + |S \cup T|^{2}$$

Always true. Take maximum, which separates S and T more extremely. We claim this particular optimum solution will satisfy property.

Suppose not. Then  $T_1 \not\subseteq T_2, T_2 \not\subseteq T_1$ , and  $\lambda_{T_1} > 0$  and  $\lambda_{T_2} > 0$ . Take  $\epsilon = \min(\lambda_{T_1}, \lambda_{T_2}) > 0$ .

$$\lambda'_{S} = \begin{cases} \lambda_{S} & S \neq T_{1}, S \neq T_{2}, S \neq T_{1} \cap T_{2}, S \neq T_{1} \cup T_{2} \\ \lambda_{S} - \epsilon & S = T_{1}, S = T_{2} \\ \lambda_{S} + \epsilon & S = T_{1} \cap T_{2}, S = T_{1} \cap T_{2} \end{cases}$$

Can check that all properties of the LP are still satisfied. The objective function is

$$\min \sum_{S} \lambda'_{S} f(S) = \min \sum_{S} \lambda_{S} f(S) - \epsilon (f(T_{1}) + f(T_{2})) + \epsilon (f(T_{1} \cap T_{2}) + f(T_{1} \cup T_{2}))$$

The loss must be negative because the objective function was minimal. In other words,  $f(T_1) + f(T_2) \ge f(T_1 \cap T_2) + f(T_1 \cup T_2)$ . By submodularity,  $f(T_1) + f(T_2) \le f(T_1 \cap T_2) + f(T_1 \cup T_2)$ . So they must be equal, so  $\lambda'$  also minimized the objective function.

But  $\sum_{S} \lambda_S |S|^2 \leq \sum_{S} \lambda'_S |S|^2$ , which contradicts the assumption that  $\lambda_S$  was the solution to the LP that maximized  $\sum_{S} \lambda_S |S|^2$ .

 $S: \lambda_S > 0$  are contained in each other. We can write this explicitly:

$$z_{1} = \min_{x_{i}>0} x_{i} \quad S_{1} = \{i | x_{i} \ge z_{1}\} \quad \lambda_{S_{1}} = z_{1}$$

$$z_{2} = \min_{x_{i}>z_{1}} x_{i} \quad S_{2} = \{i | x_{i} \ge z_{2}\} \quad \lambda_{S_{2}} = z_{2} - z_{1}$$

$$\vdots$$

$$z_{k} = \min_{x_{i}>z_{k-1}} x_{i} \quad S_{k} = \{i | x_{i} \ge z_{k}\} \quad \lambda_{S_{k}} = z_{k} - z_{k-1}$$

$$z_{k+1} = 1 \quad S_{k+1} = \{i | x_{i} \ge 1\} \quad \lambda_{S_{k+1}} = 1 - z_{k}$$

This is a unique solution. We can check the constraints easily.

The process is to choose a b and pick  $x_i$  to be all 0. If this is infeasible then can run ellipsoid again with smaller bounds (on the ellipsoid). Do a binary search and keep calling ellipsoid until you find a b such that the program is feasible at b but not at b - 1.

We have an oracle that answers at integer points. Put it inside another that answers for fractional values. If the minimization of the program happens at a fractional value, then it happens at an integral value. So if the ellipsoid algorithm returns a fractional value, we know there's an integral solution and can find it.

## **15.2 Edmond's theorem**

Given a directed graph G and a root r, an arborescence (branching, rooted directed spanning tree) is a spanning tree that has all edges pointing away from r. You might want an arborecense if you have information

at the root r and want to send it to all nodes on the graph. The capacity on all edges is one, and G is allowed to be a multigraph.

An arborescence packing is the maximum number of arborescences  $A_1, A_2, \ldots, A_k$  such that all are edge disjoint. They all share the same root.

Define  $\lambda_{r_u}$  to be the number of edge disjoint paths from r to u in G.  $k \leq \min_u(\lambda_{r_u})$ . Or, in other words, if  $\delta_{OUT}(S)$  is the number of outgoing edges of S, then  $k \leq \min_{r \in S, \exists u \notin S} |\delta_{OUT}(S)|$ .

**Theorem 15.1.** Edmond's Theorem: The maximum number of arborescences k is equal to the minimum cut.

$$k = \min_{u}(\lambda_{r_u}) = \min_{r \in S, \exists u \notin S} |\delta_{OUT}(S)|$$

*Proof.* (Lovasz) Assume  $\min_{r \in S, \exists u \notin S} |\delta_{OUT}(S)| = c$ . Initially take G. It has minimum cut  $c_G$ . Pick an arborescence  $A_1$  such that  $C(G - A_1) = c_G - 1$ . By induction we can keep going down, creating  $A_{C(G)}$  number of arborescences. Then k = C(G).

We need to prove the inductive step, that we can find  $A_1$  with this property. Initially  $A_1$  has a single vertex, root r. We create edges, maintaining the property that  $C(G - A) \ge C(G) - 1$ . We can keep picking edges and unless  $A_1$  becomes spanning, we can always maintain this property. Call vertices spanned by A V(A). Need to maintain

$$\forall S_{r \in SS \neq V(G)} \ |\delta_{OUT}^{G-A}(S)| \ge C(G) - 1$$

**Definition 15.1.** A critical set S satisfies

1.  $\delta_{OUT}^{G-A}(S) = C(G) - 1$ 2.  $V(G) - V(A) \nsubseteq S; \exists u | u \notin S \text{ but } u \in V(G) - V(A)$ 3.  $r \in S$ 

V(G) - V(A) are points outside the arborescence. We don't want to pick an edge for which  $d_{OUT}^{G-A}(S) = C(G) - 1$ , because then we'll have a problem.

Take any maximal critical set S. Can it contain all of A? No, because that would violate 1. It must leave some vertices outside.  $\exists$  point  $v, v \in V(A)$  and  $v \notin S$ . Because of 2,  $\exists$  point  $u, u \notin S, u \in V(G) - V(A)$ .

We will show something stronger:  $\exists u, u \notin S, u \in V(G) - V(A)$ , and v - u is an edge in G. This is the edge we will pick. We prove this existence using maximality.

$$\delta_{OUT}^{G-A}(S \cup \{v\}) = C(G)$$

Since S is maximal, it must violate one of 1, 2, 3; it still satisfies 2, 3 so it must violate 1. When we include v inside, there must be an edge in G - A that it goes to. If it doesn't go to G - A, throw it away. If it goes to G - A, then include it and the induction works.

This won't harm any other critical set T. Why? Suppose not. Assume T is hurt by removing v.  $|\delta_{OUT}(S)| + |\delta_{OUT}(T)| \ge |\delta_{OUT}(S \cap T)| + |\delta_{OUT}(S \cup T)|$  by submodularity.  $|\delta_{OUT}(S)| = C(G) - 1$  $|\delta_{OUT}(T)| = C(G) - 1$ 

The other ones must also be C(G)-1 because that's what we're maintaining inductively (can't be C(G)-2). So T cannot be violated, because  $S \cup T$  is also a critical set. But S was maximal, so can't hurt it.