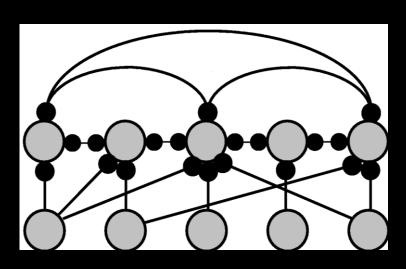
## **CSE/NB 528**

## Final Lecture: All Good Things Must...

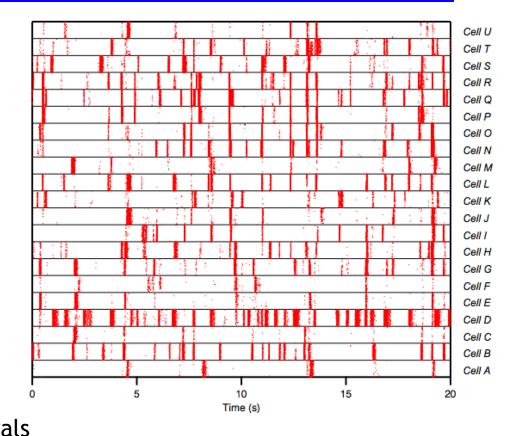




## Course Summary

- Where have we been?
  - Course Highlights
- Where do we go from here?
  - Challenges and Open Problems
- Further Reading

#### What is the neural code?



What is the nature of the code?
Representing the spiking output:
single cells vs populations
rates vs spike times vs intervals

What features of the stimulus does the neural system represent?

#### Encoding and decoding neural information

Encoding: building functional models of neurons/neural systems and predicting the spiking output given the stimulus

Decoding: what can we say about the stimulus given what we observe from the neuron or neural population?

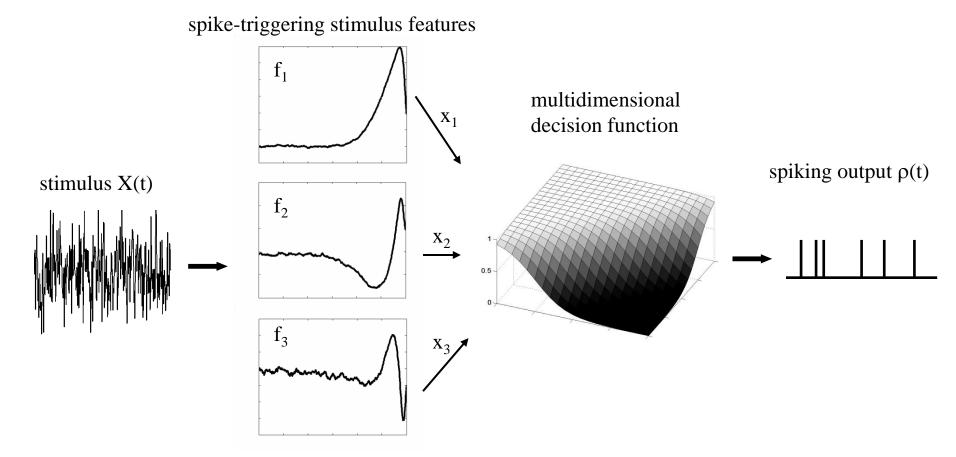
#### Key concepts: Poisson & Gaussian

Spike trains are variable

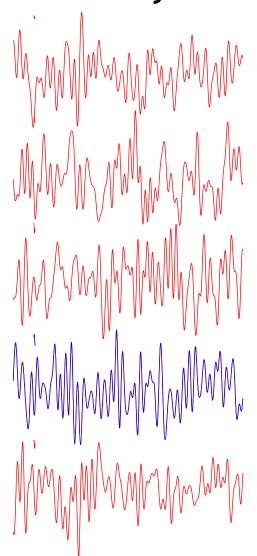
Models are probabilistic

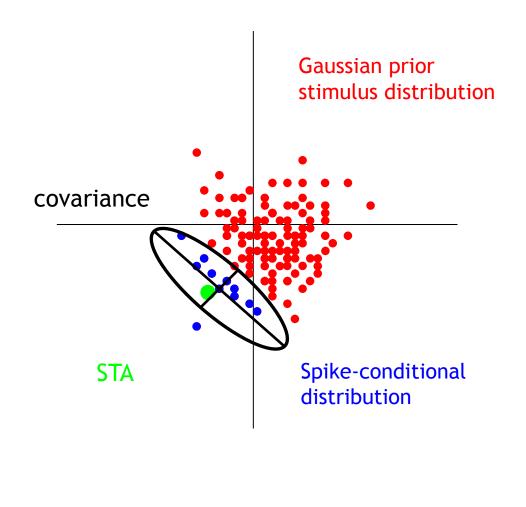
Deviations are close to independent

#### Highlights: Neural Encoding

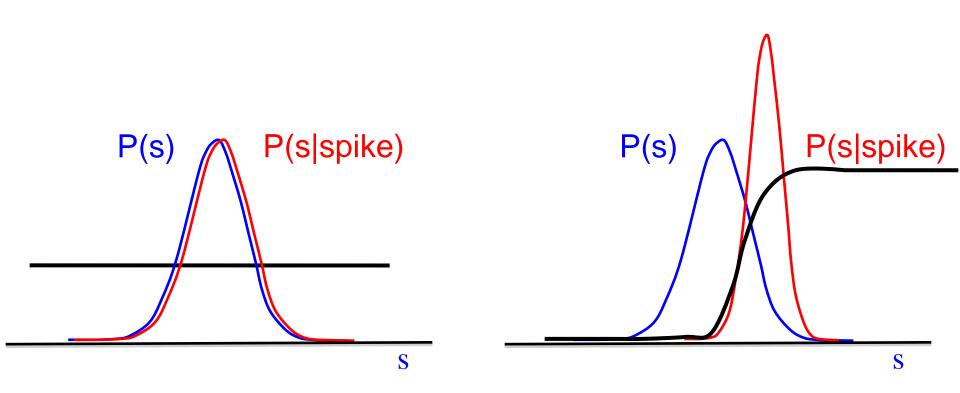


# Highlights: Finding the feature space of a neural system

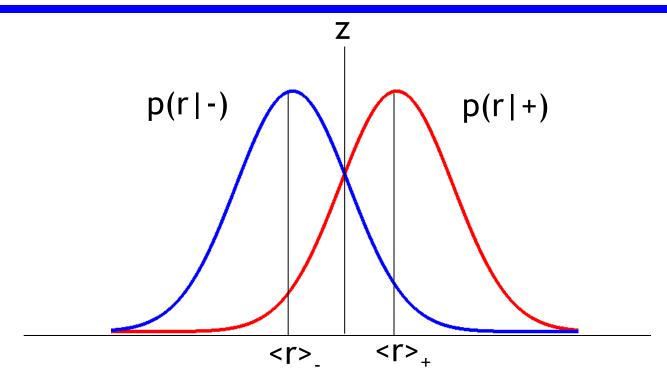




#### Highlights: Finding an interesting tuning curve



#### Decoding: Signal detection theory



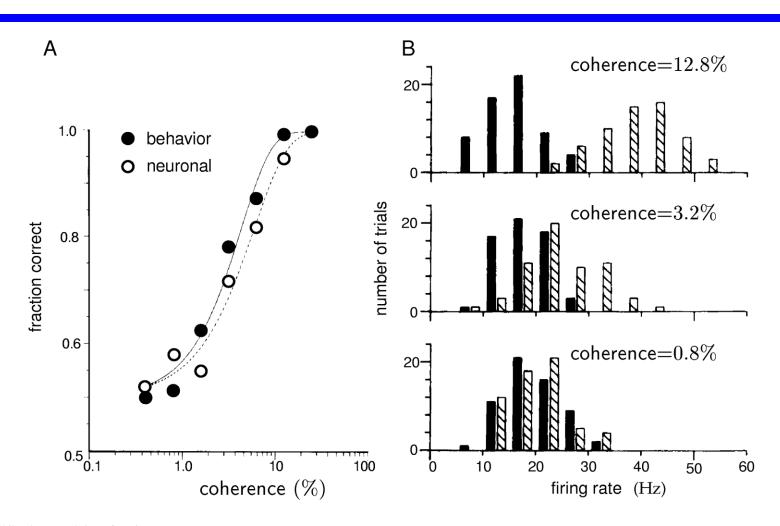
Decoding corresponds to comparing test to threshold.

$$\alpha(z) = P[r \ge z|-]$$

$$\beta(z) = P[r \ge z | +]$$

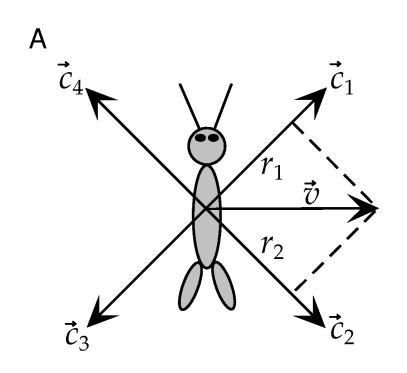
false alarm rate, "size" hit rate, "power"

#### Highlights: Neurometric curves

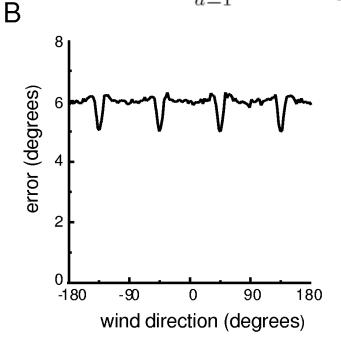


#### Decoding from a population

#### e.g. cosine tuning curves



$$\vec{v}_{\text{pop}} = \sum_{a=1}^{4} \left( \frac{r}{r_{\text{max}}} \right)_{a} \vec{c}_{a}$$



RMS error in estimate

Theunissen & Miller, 1991

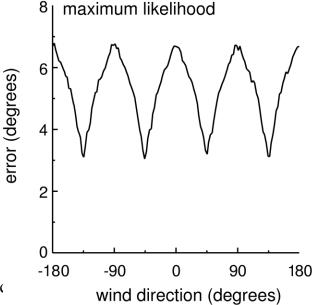
#### More general approaches: MAP and ML

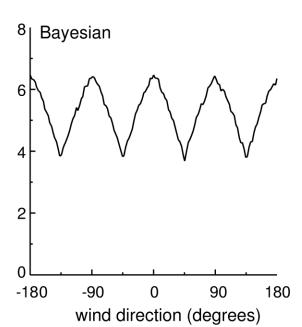
MAP: s\* which maximizes p[s|r]

ML: s\* which maximizes p[r|s]

Difference is the role of the prior: differ by factor p[s]/p[r]

For cercal data:

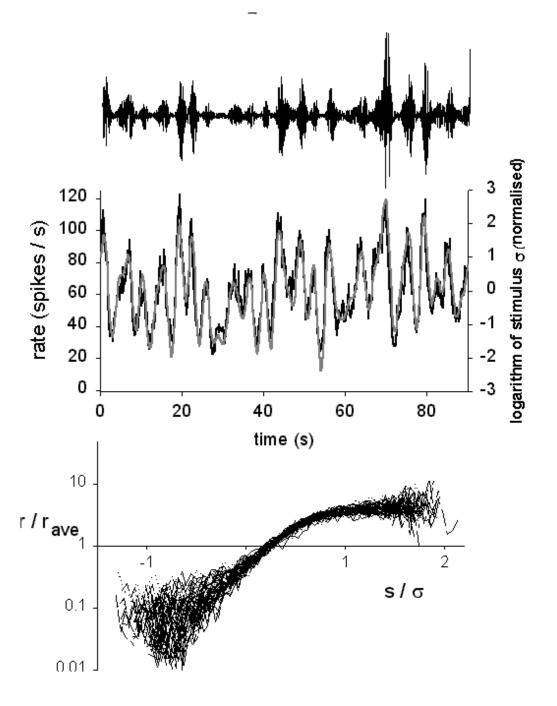




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CSE/NB 528: Final Lea

Highlights:
Information
maximization
as a design principle
of the nervous
system

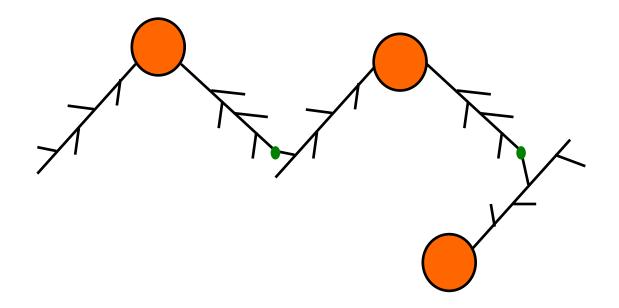


#### Encoding and decoding neural information

Encoding: building functional models of neurons/neural systems and predicting the spiking output given the stimulus

Decoding: what can we say about the stimulus given what we observe from the neuron or neural population?

## The biophysical basis of neural computation

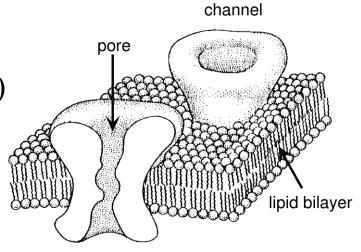


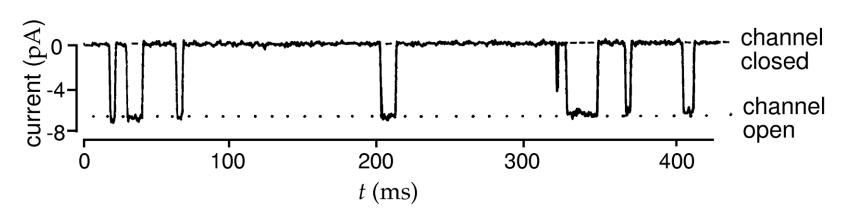
#### Excitability is due to the properties of ion channels

• Voltage dependent

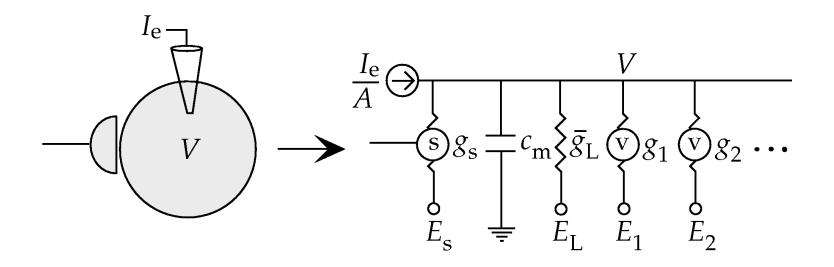
transmitter dependent (synaptic)

• Ca dependent





#### Highlights: The neural equivalent circuit



Ohm's law: V = IR and Kirchhoff's law

#### Simplified neural models

A sequence of neural models of increasing complexity that approach the behavior of real neurons

#### Integrate and fire neuron:

subthreshold, like a passive membrane spiking is due to an imposed threshold at  $V_T$ 

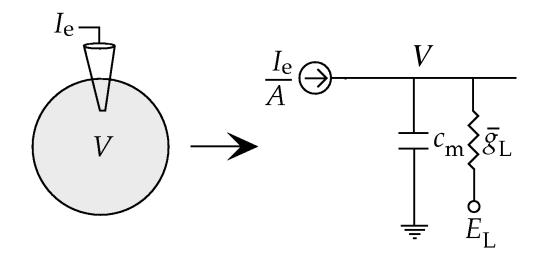
#### Spike response model:

subthreshold, arbitrary kernel spiking is due to an imposed threshold at  $V_T$  postspike, incorporates afterhyperpolarization

#### Simple model:

complete 2D dynamical system spiking threshold is intrinsic have to include a reset potential

## Simplified models: integrate-and-fire

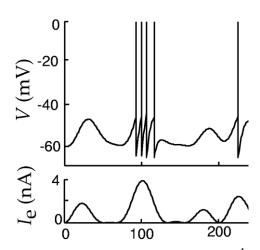


Integrate-and-Fire Model

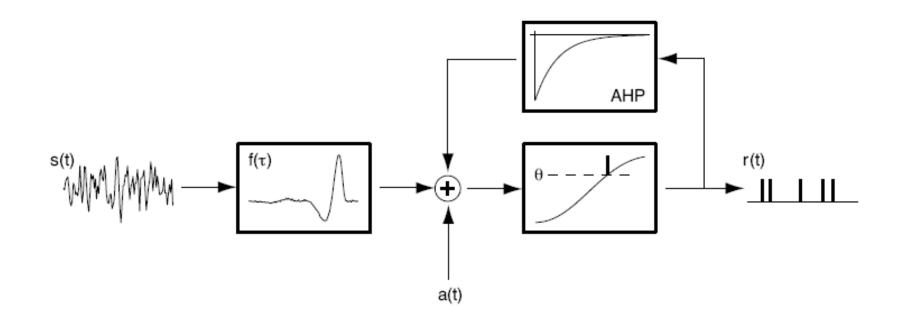
$$\tau_m \frac{dV}{dt} = -(V - E_L) + I_e R_m$$

If  $V > V_{threshold} \rightarrow Spike$ 

Then reset:  $V = V_{reset}$ 



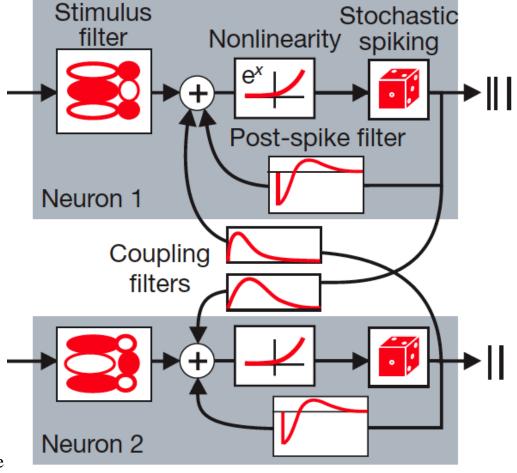
## Simplified models: spike response model



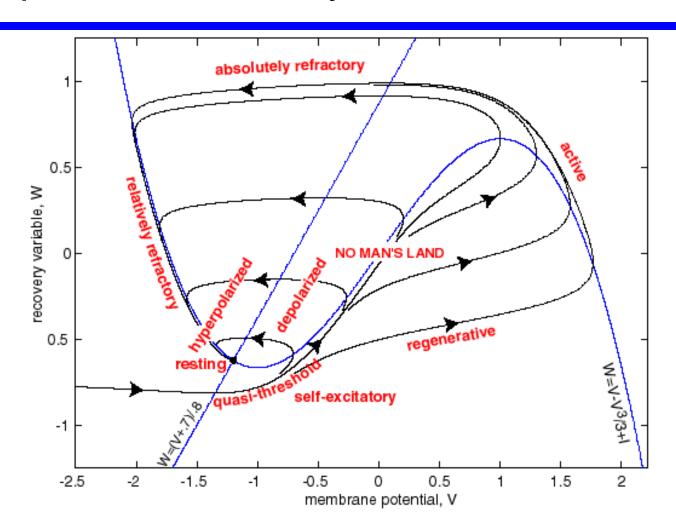
Gerstner; Keat et al. 2001

## Simplified models: spike response model

## Coupled spiking model

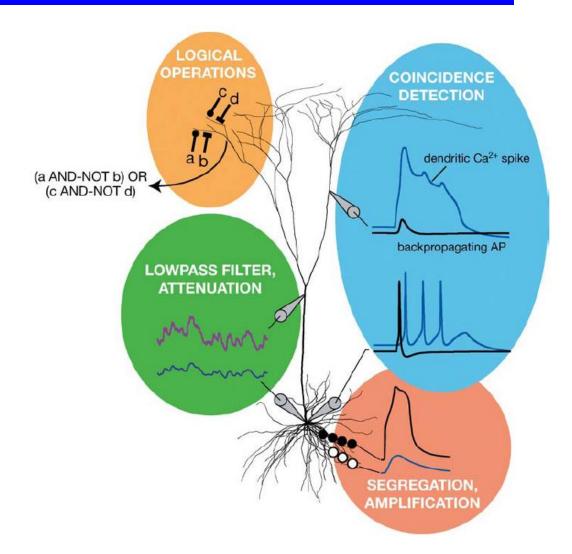


## Simplified models: dynamical models



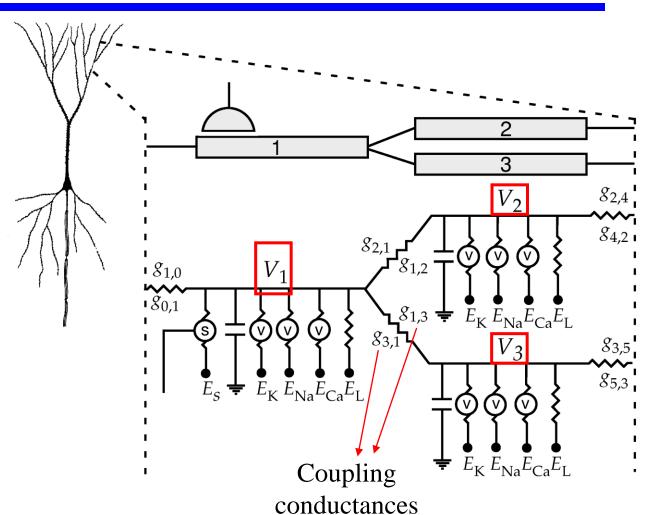
#### Highlights: Dendritic computation

Filtering
Shunting
Delay lines
Information segregation
Synaptic scaling
Direction selectivity



## Highlights: Compartmental models

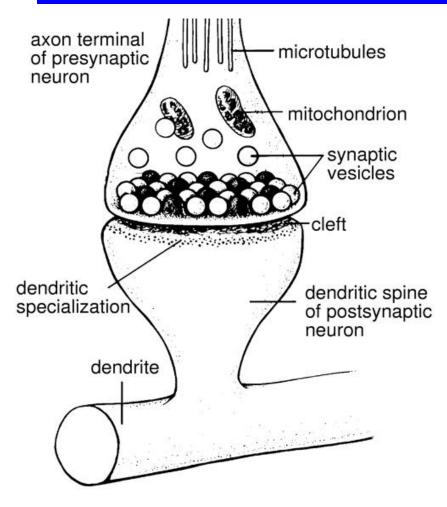
Neuronal structure can be modeled using electrically coupled compartments



CSE/NB 528: Final Lecture

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## Connecting neurons: Synapses



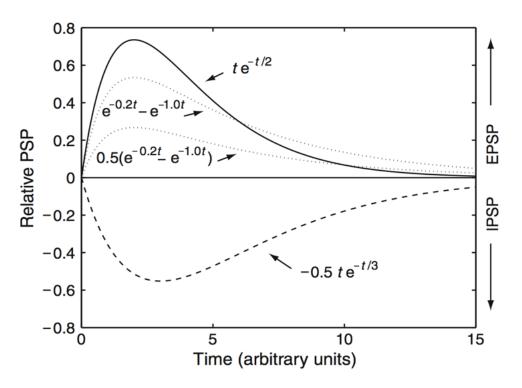
Presynaptic voltage spikes cause neurotransmitter to cross the cleft, triggering postsynaptic receptors allowing ions to flow in, changing postsynaptic potential

Glutamate: excitatory

GABA<sub>A</sub>: inhibitory

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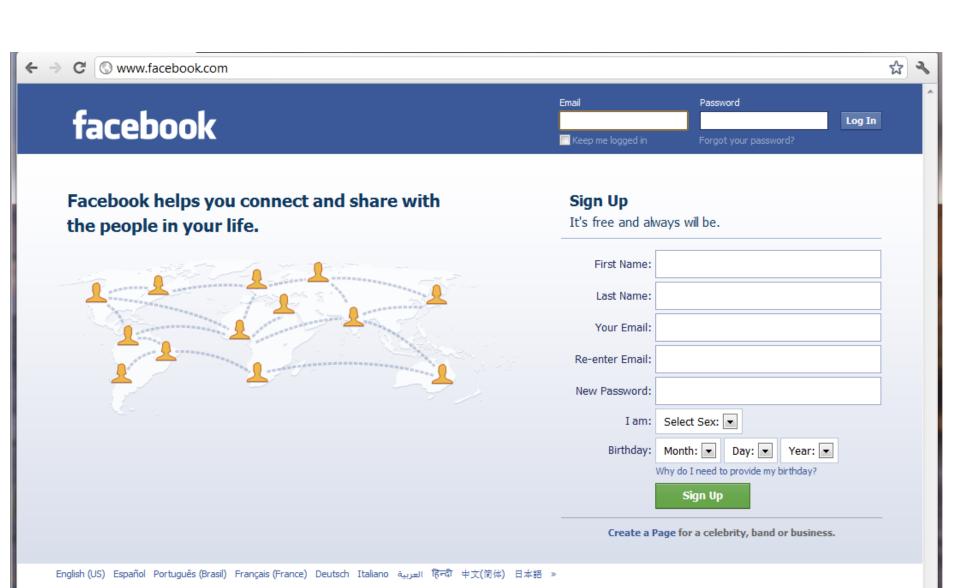
## Synaptic voltage changes



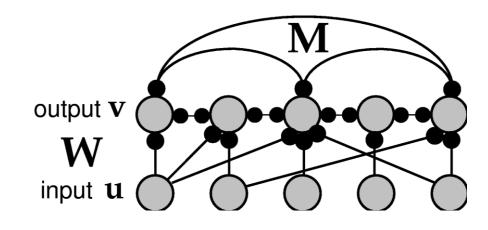
Size of the PSP is a measure of synaptic strength.

Can vary on the short term due to input history on the long term due to synaptic plasticity .. one way to build circuits that learn

## Networks



#### Modeling Networks of Neurons



$$\tau \frac{d\mathbf{v}}{dt} = -\mathbf{v} + F(\mathbf{W}\mathbf{u} + \mathbf{M}\mathbf{v})$$

Output

Decay

Input Feedback

## Highlights: Unsupervised Learning

- For linear neuron: $v = \mathbf{w}^T \mathbf{u} = \mathbf{u}^T \mathbf{w}$
- Basic Hebb Rule:  $\tau_w \frac{d\mathbf{w}}{dt} = \mathbf{u}v$



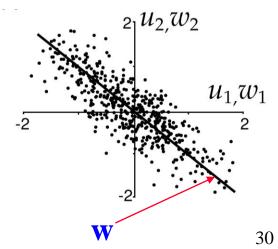
Average effect over many inputs:

$$\tau_{w} \frac{d\mathbf{w}}{dt} = \langle \mathbf{u} v \rangle = Q\mathbf{w}$$

Q is the input correlation matrix:

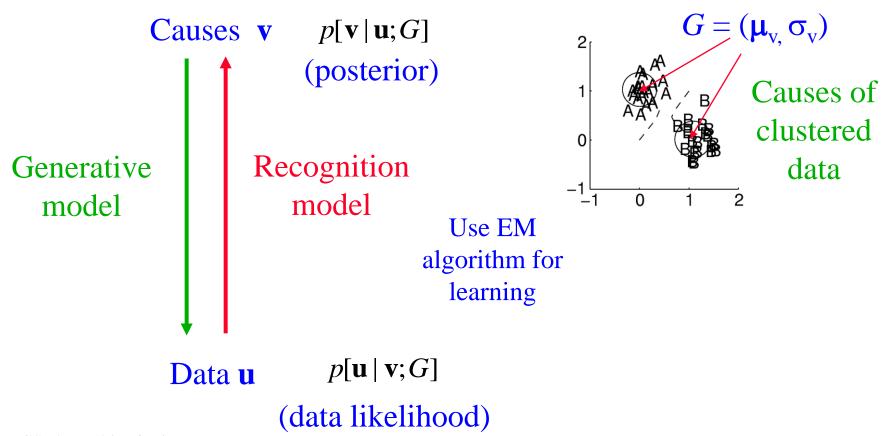
$$Q = \langle \mathbf{u}\mathbf{u}^T \rangle$$

Hebb rule performs principal component analysis (PCA)

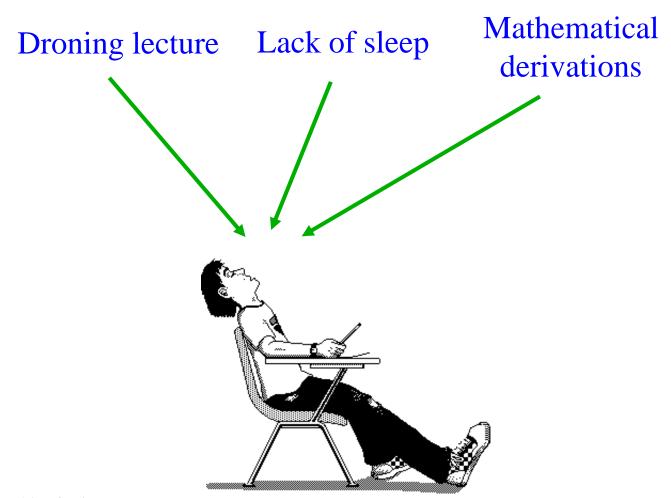


#### Highlights: The Connection to Statistics

<u>Unsupervised learning</u> = learning the *hidden causes* of input data

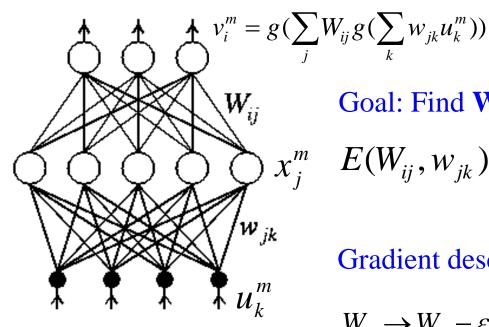


## Highlights: Generative Models



## Highlights: Supervised Learning

#### **Backpropagation for Multilayered Networks**



Goal: Find W and w that minimize errors:

$$\chi_j^m \quad E(W_{ij}, w_{jk}) = \frac{1}{2} \sum_{m,i} (d_i^m - v_i^m)^2$$
Desired output

Gradient descent learning rules:

$$W_{ij} \to W_{ij} - \varepsilon \frac{\partial E}{\partial W_{ij}}$$
 (Delta rule)

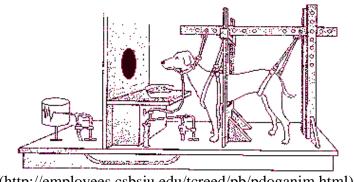
$$w_{jk} \to w_{jk} - \varepsilon \frac{\partial E}{\partial w_{jk}} = w_{jk} - \varepsilon \frac{\partial E}{\partial x_j^m} \cdot \frac{\partial x_j^m}{\partial w_{jk}}$$
 (Chain rule)

## Highlights: Reinforcement Learning

Learning to predict rewards:

$$w \rightarrow w + \varepsilon (r - v)u$$

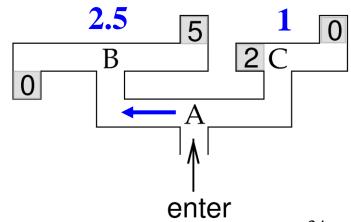
 Learning to predict delayed rewards (TD learning):



(http://employees.csbsju.edu/tcreed/pb/pdoganim.html)

$$w(\tau) \rightarrow w(\tau) + \varepsilon [r(t) + v(t+1) - v(t)] u(t-\tau)$$

- Actor-Critic Learning:
  - Critic learns value of each state using TD learning
  - Actor learns best actions based on value of next state (using the TD error)



#### The Future: Challenges and Open Problems

- How do neurons encode information?
  - Topics: Synchrony, Spike-timing based learning, Dynamic synapses
- Does a neuron's structure confer computational advantages?
  - Topics: Role of channel dynamics, dendrites, plasticity in channels and their density
- How do networks implement computational principles such as efficient coding and Bayesian inference?
- How do networks learn "optimal" representations of their environment and engage in purposeful behavior?
  - Topics: Unsupervised/reinforcement/imitation learning

# Further Reading (for the summer and beyond)

- Spikes: Exploring the Neural Code, F. Rieke et al., MIT Press, 1997
- The Biophysics of Computation, C. Koch, Oxford University Press, 1999
- Large-Scale Neuronal Theories of the Brain,
   C. Koch and J. L. Davis, MIT Press, 1994
- Probabilistic Models of the Brain, R. Rao et al., MIT Press, 2002
- Bayesian Brain, K. Doya et al., MIT Press, 2007
- Reinforcement Learning: An Introduction, R. Sutton and A. Barto, MIT Press, 1998



## Next meeting: Project presentations!

- Project presentations will be on Thursday, June 9
   (10:30am-12:20pm) in the same classroom
- Keep your presentation short: ~6-8 slides, 8 mins/group
- Slides:
  - Bring your slides on a USB stick to use the class laptop (Apple)

#### OR

- Bring your own laptop if you have videos etc.
- Projects reports (10-15 pages total) due June 9 (by email to both Adrienne and Raj before midnight)



