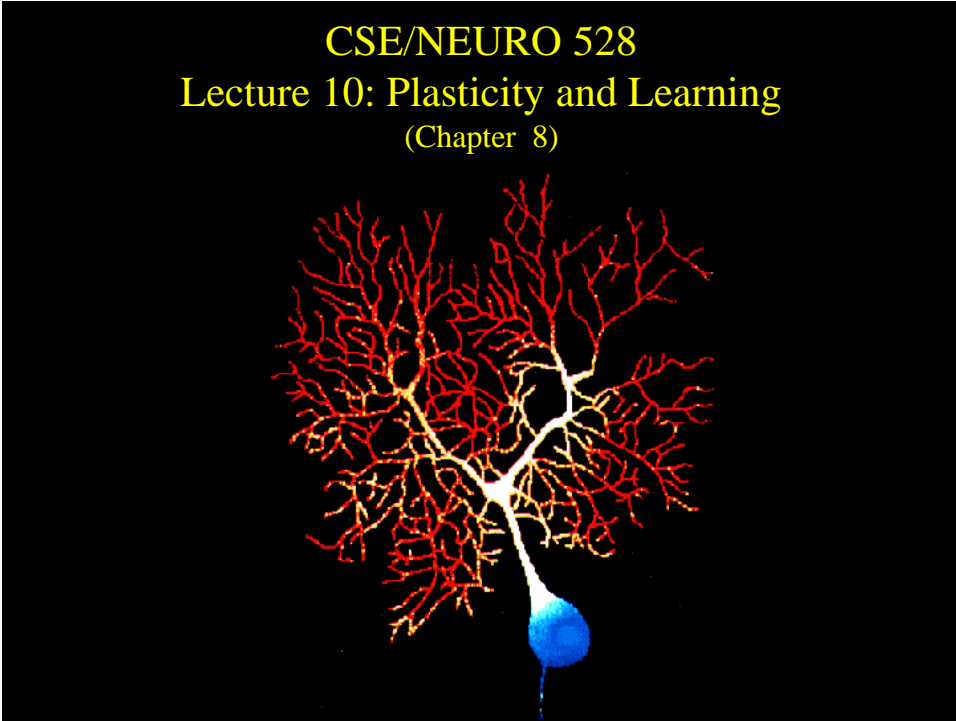


CSE/NEURO 528
Lecture 10: Plasticity and Learning
(Chapter 8)



Gameplan



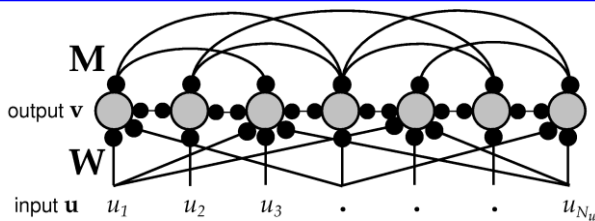
- ◆ Plasticity and Learning
 - ⇒ Types: Unsupervised, Supervised, and Reinforcement learning
- ◆ Today: Unsupervised Learning
 - ⇒ Hebb rule and its variants (Covariance, Oja rule)
 - ⇒ Mathematical formulation
 - ⇒ Stability analysis of learning rules

So far, we have been analyzing networks with *fixed* sets of synaptic weights W and M
(based on eigenvalues of M etc.)

Can synaptic weights be adapted in response to inputs?

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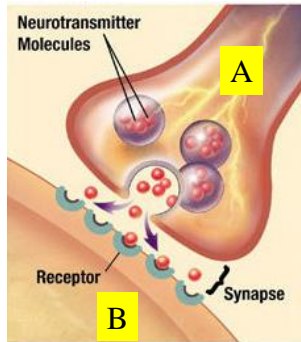
Plasticity and Learning: Adapting the Connections



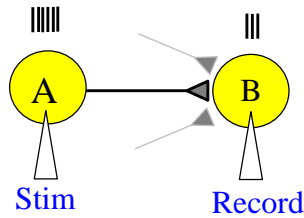
- ◆ **Question 1:** How do we adapt the synaptic weights W and M to solve useful tasks?
- ◆ **Question 2:** How does the brain do it?

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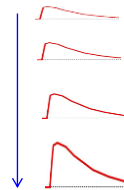
Synaptic Plasticity in the Brain



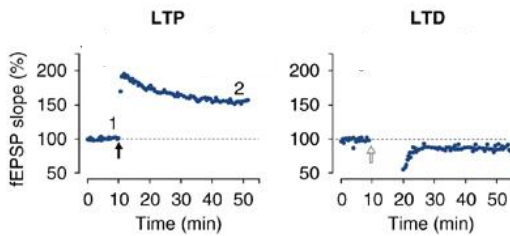
How can we measure plasticity using electrodes?



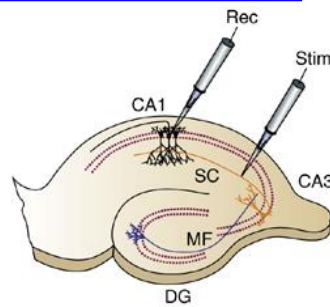
Increase in EPSP size for same input over time



Data from an Experiment



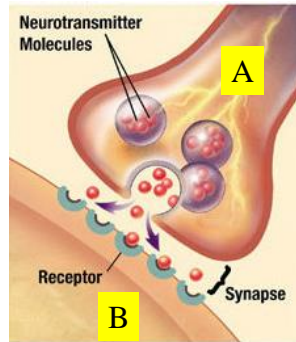
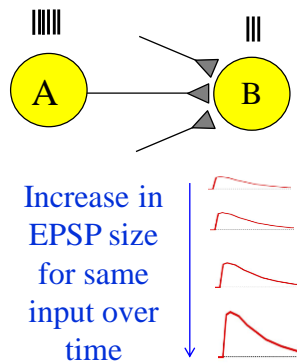
LTP = Long Term Potentiation
LTD = Long Term Depression



Hippocampus

Long Term Potentiation (LTP)

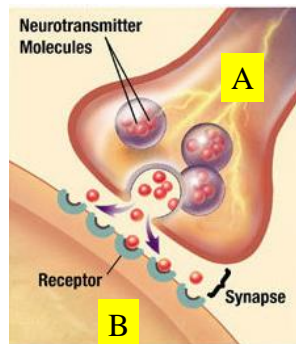
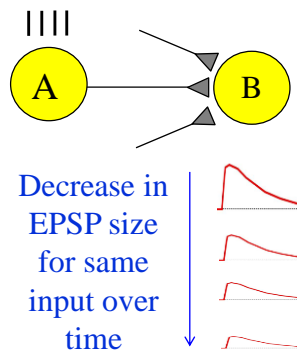
LTP = Experimentally observed *increase* in synaptic strength that lasts for hours or days



7
Image Source: Wikimedia Commons

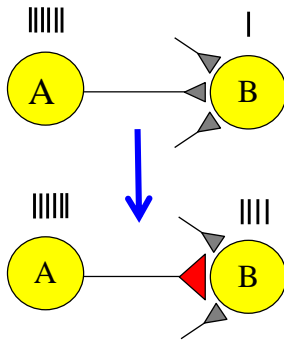
Long Term Depression (LTD)

LTD = Experimentally observed *decrease* in synaptic strength that lasts for hours or days



8
Image Source: Wikimedia Commons

Hebb's Learning Rule



If neuron A repeatedly takes part in firing neuron B, then the synapse from A to B is strengthened



“Neurons that fire together wire together!”

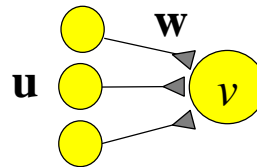
9

Image Source: Wikimedia Commons

Formalizing Hebb's Rule

- Consider a single linear neuron with steady state output:

$$v = \mathbf{w} \cdot \mathbf{u} = \mathbf{w}^T \mathbf{u} = \mathbf{u}^T \mathbf{w}$$



- Basic Hebb Rule: $\tau_w \frac{d\mathbf{w}}{dt} = \mathbf{u}v$

Discrete Implementation:

$$\tau_w \frac{\mathbf{w}(t + \Delta t) - \mathbf{w}(t)}{\Delta t} = \mathbf{u}v \quad (\text{or } \mathbf{w}(t + \Delta t) = \mathbf{w}(t) + \frac{\Delta t}{\tau_w} \mathbf{u}v)$$

$$\mathbf{w}_{i+1} = \mathbf{w}_i + \varepsilon \cdot \mathbf{u}v \quad (\text{or } \Delta \mathbf{w} = \varepsilon \cdot \mathbf{u}v)$$

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What is the average effect of the Hebb rule?

◆ Hebb Rule: $\tau_w \frac{d\mathbf{w}}{dt} = \mathbf{u}v$

◆ Average effect of the rule:

$$\tau_w \frac{d\mathbf{w}}{dt} = \langle \mathbf{u}v \rangle_{\mathbf{u}} = \langle \mathbf{u}\mathbf{u}^T \mathbf{w} \rangle_{\mathbf{u}} = \langle \mathbf{u}\mathbf{u}^T \rangle_{\mathbf{u}} \mathbf{w} = \mathbf{Q}\mathbf{w}$$

◆ Q is the input correlation matrix: $\mathbf{Q} = \langle \mathbf{u}\mathbf{u}^T \rangle_{\mathbf{u}}$

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Covariance Rule

◆ Hebb rule only increases synaptic weights (LTP)

⇒ What about LTD?

◆ Covariance rule:

$$\tau_w \frac{d\mathbf{w}}{dt} = \mathbf{u}(v - \langle v \rangle) \quad (\text{Note: LTD for low or no output given some input})$$

◆ Average effect of the rule:

$$\begin{aligned} \tau_w \frac{d\mathbf{w}}{dt} &= \langle \mathbf{u}(v - \langle v \rangle) \rangle_{\mathbf{u}} = \langle \mathbf{u}(\mathbf{u}^T - \langle \mathbf{u} \rangle^T) \mathbf{w} \rangle_{\mathbf{u}} = (\langle \mathbf{u}\mathbf{u}^T \rangle - \langle \mathbf{u} \rangle \langle \mathbf{u} \rangle^T) \mathbf{w} \\ &= \mathbf{C}\mathbf{w} \quad (\mathbf{C} \text{ is the input covariance matrix } \langle \mathbf{u}\mathbf{u}^T \rangle - \langle \mathbf{u} \rangle \langle \mathbf{u} \rangle^T) \end{aligned}$$

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Are these learning rules stable?

- ◆ Does \mathbf{w} converge to a stable value or explode?

⇨ Look at what happens to the length of \mathbf{w} over time

- ◆ Hebb rule: $\tau_w \frac{d\mathbf{w}}{dt} = \mathbf{u}v$

$$\frac{d\|\mathbf{w}\|^2}{dt} = 2\mathbf{w}^T \frac{d\mathbf{w}}{dt} = 2\mathbf{w}^T (\mathbf{u}v / \tau_w) = \frac{2}{\tau_w} v^2 > 0 \quad \mathbf{w} \text{ grows without bound!}$$

- ◆ Covariance rule: $\tau_w \frac{d\mathbf{w}}{dt} = \mathbf{u}(v - \langle v \rangle)$

$$\frac{d\|\mathbf{w}\|^2}{dt} = 2\mathbf{w}^T \frac{d\mathbf{w}}{dt} = 2\mathbf{w}^T (\mathbf{u}(v - \langle v \rangle) / \tau_w) = \frac{2}{\tau_w} (v^2 - v\langle v \rangle)$$

$$\text{Averaging RHS, } \frac{d\|\mathbf{w}\|^2}{dt} = \frac{2}{\tau_w} (\langle v^2 \rangle - \langle v \rangle^2) = \frac{2}{\tau_w} \sigma_v^2 > 0 \quad \mathbf{w} \text{ grows without bound!}$$

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Oja's Rule for Hebbian Learning

- ◆ Oja's rule: $\tau_w \frac{d\mathbf{w}}{dt} = \mathbf{u}v - \alpha v^2 \mathbf{w} \quad (\alpha > 0)$

- ◆ Stable?

$$\frac{d\|\mathbf{w}\|^2}{dt} = 2\mathbf{w}^T \frac{d\mathbf{w}}{dt} = \frac{2}{\tau_w} \mathbf{w}^T (\mathbf{u}v - \alpha v^2 \mathbf{w}) = \frac{2}{\tau_w} (v^2 - \alpha v^2 \mathbf{w}^T \mathbf{w})$$

$$\text{i.e., } \tau_w \frac{d\|\mathbf{w}\|^2}{dt} = 2v^2(1 - \alpha\|\mathbf{w}\|^2)$$

$$\text{At steady state: } \|\mathbf{w}\|^2 = \frac{1}{\alpha} \text{ i.e., } \|\mathbf{w}\| = \frac{1}{\sqrt{\alpha}}$$

\mathbf{w} does not grow without bound, i.e.,
Oja's rule is stable!

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Summary: Hebbian Learning

- ◆ Hebb rule:

$$\tau_w \frac{d\mathbf{w}}{dt} = \mathbf{u}\mathbf{v} \quad \text{Unstable} \quad (\text{unless constraint on } \|\mathbf{w}\| \text{ is imposed})$$

- ◆ Covariance rule:

$$\tau_w \frac{d\mathbf{w}}{dt} = \mathbf{u}(v - \langle v \rangle) \quad \text{Unstable} \quad (\text{unless constraint on } \|\mathbf{w}\| \text{ is imposed})$$

- ◆ Oja's rule:

$$\tau_w \frac{d\mathbf{w}}{dt} = \mathbf{u}\mathbf{v} - \alpha v^2 \mathbf{w} \quad \text{Stable} \quad \|\mathbf{w}\| \rightarrow \frac{1}{\sqrt{\alpha}}$$

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What does Hebbian Learning do anyway?

- ◆ Start with the averaged Hebb rule: $\tau_w \frac{d\mathbf{w}}{dt} = Q\mathbf{w}$
- ◆ How do we solve this equation to find $\mathbf{w}(t)$?
 ⇒ **Eigenvectors** to the rescue (again)!
- ◆ Write $\mathbf{w}(t)$ in terms of *eigenvectors* of Q : $\mathbf{w}(t) = \sum_i c_i(t) \mathbf{e}_i$
- ◆ Substitute in Hebb rule diff. eq. and simplify as before:

$$\tau_w \frac{dc_i}{dt} = \lambda_i c_i \quad \text{i.e., } c_i(t) = c_i(0) \exp(\lambda_i t / \tau_w)$$

$$\mathbf{w}(t) = \sum_i c_i(t) \mathbf{e}_i = \sum_i c_i(0) \exp(\lambda_i t / \tau_w) \mathbf{e}_i$$

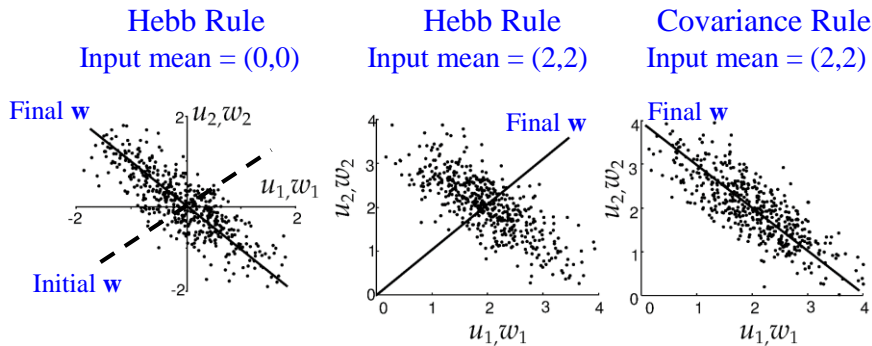
For large t , largest eigenvalue term dominates: $\mathbf{w}(t) \propto \mathbf{e}_1$

(For Oja's rule: $\mathbf{w}(t) = \frac{\mathbf{e}_1}{\sqrt{\alpha}}$)

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The Brain can do Statistics!*

Hebbian Learning implements *Principal Component Analysis* (PCA)



Hebbian learning learns a weight vector aligned with the principal eigenvector of input correlation/covariance matrix (i.e., direction of maximum variance)

*See a previous lecture for “The Brain can do Calculus!”

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Image Source: Dayan & Abbott textbook

Next Class: Unsupervised to Supervised Learning

◆ Things to do:

- ⇒ Finish Chapter 8 and Start Chapter 10
- ⇒ Homework 3 due on Sunday, February 19
- ⇒ Start mini-project

