Announcements

HW 2 will be posted tonight or tomorrow. **DUE 11/2**

Classification Logistic Regression

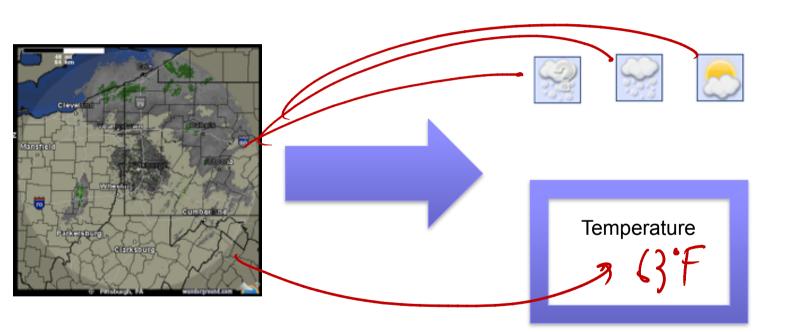
Machine Learning – CSE546 Kevin Jamieson University of Washington

October 16, 2016

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THUS FAR, REGRESSION: PREDICT A CONTINUOUS VALUE GIVEN SOME INPUTS

Weather prediction revisted



Reading Your Brain, Simple Example

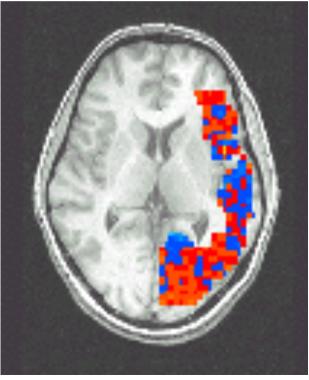
[Mitchell et al.]

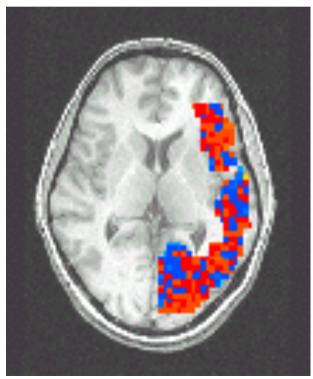
Pairwise classification accuracy: 85%

Person



Animal





Classification

- Learn: f:X —>Y
 - □ **X** features
 - □ Y target classes
- Conditional probability: P(Y|X)
- Suppose you know P(Y|X) exactly, how should you classify?
 - Bayes optimal classifier:

How do we estimate P(Y|X)?

Link Functions

Estimating P(Y|X): Why not use standard linear regression?

Combining regression and probability?
 Need a mapping from real values to [0,1]
 A link function!

Logistic Regression

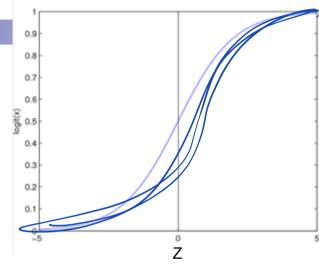
Logistic function (or Sigmoid): $1 + ext{ansatz}$

 $\frac{1}{1+exp(-z)}$

Learn P(Y|X) directly

- Assume a particular functional form for link function
- Sigmoid applied to a linear function of the input features:

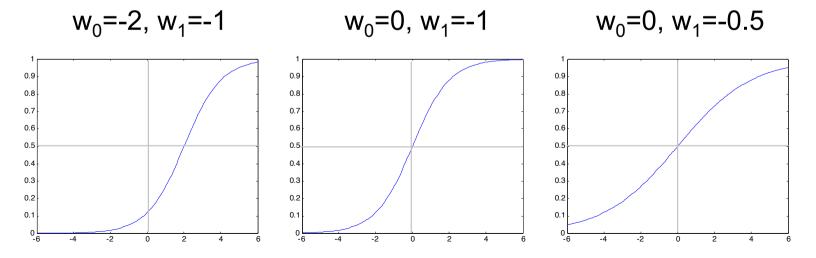
$$P(Y = 0|X, W) = \frac{1}{1 + exp(w_0 + \sum_i w_i X_i)}$$



Features can be discrete or continuous!

Understanding the sigmoid

$$g(w_0 + \sum_i w_i x_i) = \frac{1}{1 + e^{w_0 + \sum_i w_i x_i}}$$



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Very convenient!

$$P(Y = 0 \mid |X = \langle X_1, ..., X_n \rangle) = \frac{1}{1 + exp(w_0 + \sum_i w_i X_i)}$$

implies

1

$$P(Y=1)|X = \langle X_1, ..., X_n \rangle = \frac{exp(w_0 + \sum_i w_i X_i)}{1 + exp(w_0 + \sum_i w_i X_i)}$$

Very convenient!

$$P(Y = 0 \mid |X = \langle X_1, ..., X_n \rangle) = \frac{1}{1 + exp(w_0 + \sum_i w_i X_i)}$$

implies

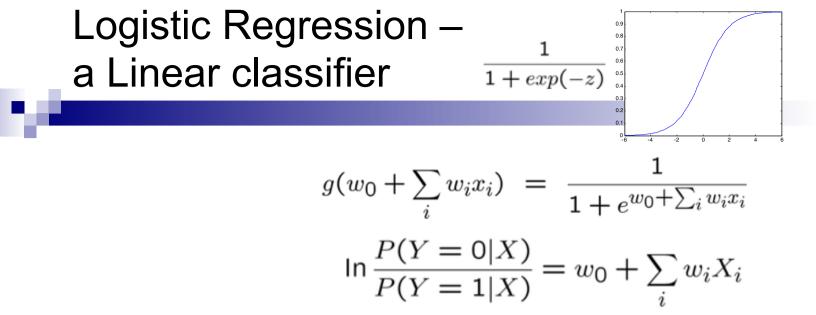
1

$$P(Y=1)|X = \langle X_1, ..., X_n \rangle = \frac{exp(w_0 + \sum_i w_i X_i)}{1 + exp(w_0 + \sum_i w_i X_i)}$$

implies

$$\frac{P(Y=1)|X)}{P(Y=0.|X)} = exp(w_0 + \sum_i w_i X_i)$$

implies
$$\ln \frac{P(Y=1)|X)}{P(Y=0L|X)} = w_0 + \sum_i w_i X_i$$



- Have a bunch of iid data of the form: $\{(x_i,y_i)\}_{i=1}^n$ $x_i\in\mathbb{R}^d, \;\;y_i\in\{-1,1\}$

$$P(Y = -1|x, w) = \frac{1}{1 + \exp(w^T x)}$$
$$P(Y = 1|x, w) = \frac{\exp(w^T x)}{1 + \exp(w^T x)}$$

This is equivalent to:

$$P(Y = y | x, w) = \frac{1}{1 + \exp(-y \, w^T x)}$$

• So we can compute the maximum likelihood estimator:

$$\widehat{w}_{MLE} = \arg\max_{w} \prod_{i=1}^{n} P(y_i | x_i, w)$$

• Have a bunch of iid data of the form: $\{(x_i, y_i)\}_{i=1}^n$ $x_i \in \mathbb{R}^d, y_i \in \{-1, 1\}$

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$$= \arg \min_{w} \sum_{i=1}^{n} \log(1 + \exp(-y_i \, x_i^T w))$$

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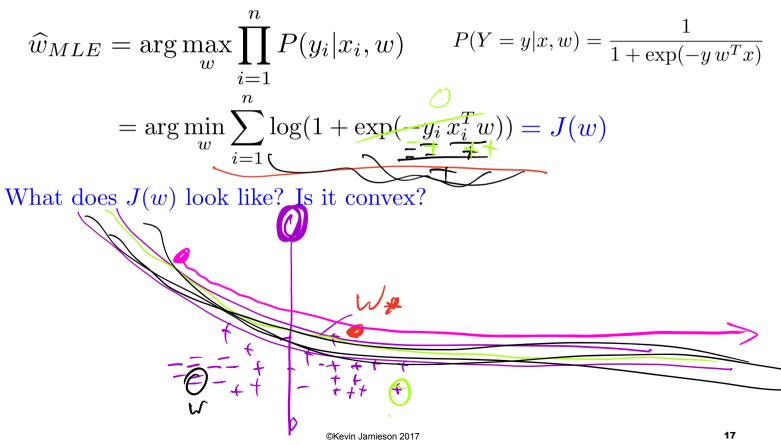
$$= \arg \min_{w} \sum_{i=1}^{n} \log(1 + \exp(-y_i x_i^T w))$$
Logistic Loss: $\ell_i(w) = \log(1 + \exp(-y_i x_i^T w))$

$$y_i / x_i$$
Squared error Loss: $\ell_i(w) = (y_i - x_i^T w)^2$ (MLE for Gaussian noise)
$$\log(1 + \exp(-y_i x_i^T w))$$

log(1+ exp(z)) ~ log(exp(z)) = 2 (evin Jamieson 2017

Z

- Have a bunch of iid data of the form: $\{(x_i,y_i)\}_{i=1}^n$ $x_i\in\mathbb{R}^d, \;\;y_i\in\{-1,1\}$

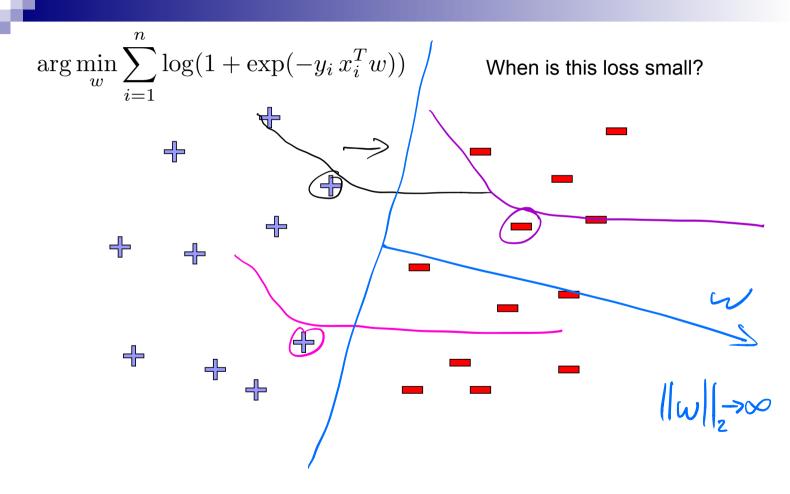


• Have a bunch of iid data of the form: $\{(x_i,y_i)\}_{i=1}^n$ $x_i\in\mathbb{R}^d, y_i\in\{-1,1\}$

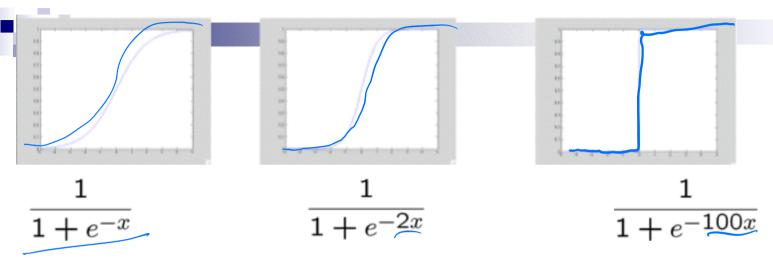
$$\widehat{w}_{MLE} = \arg \max_{w} \prod_{i=1}^{n} P(y_i | x_i, w) \qquad P(Y = y | x, w) = \frac{1}{1 + \exp(-y \, w^T x)}$$
$$= \arg \min_{w} \sum_{i=1}^{n} \log(1 + \exp(-y_i \, x_i^T w)) = J(w)$$

Good news: $J(\mathbf{w})$ is convex function of \mathbf{w} , no local optima problems Bad news: no closed-form solution to maximize $J(\mathbf{w})$ Good news: convex functions easy to optimize (next time)

Linear Separability



Large parameters → Overfitting



If data is linearly separable, weights go to infinity

In general, leads to overfitting:

Penalizing high weights can prevent overfitting...

Regularized Conditional Log Likelihood

 $\sum \log(1 + \exp(-y_i x_i^T w)) + \lambda ||w||_2^2$

Add regularization penalty, e.g., L₂:

Practical note about w₀:

n

arg min

w

$$W_{o}$$
 should not be regularized
arymin $\sum_{i=1}^{n} log(1 + exp(-y_{i}(x_{i}^{T}w + w_{o}))))$
 $w_{i}w_{o} \sum_{i=1}^{n} log(1 + exp(-y_{i}(x_{i}^{T}w + w_{o}))))$

λ>0

Gradient Descent

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Machine Learning Problems

Have a bunch of iid data of the form:

$$\{(x_i, y_i)\}_{i=1}^n \quad x_i \in \mathbb{R}^d \quad y_i \in \mathbb{R}$$

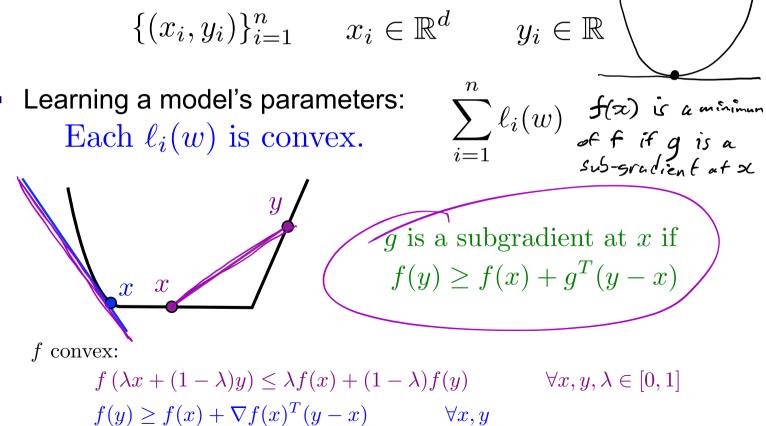
• Learning a model's parameters: Each $\ell_i(w)$ is convex.

$$\sum_{i=1}^{n} \ell_i(w)$$

 $LS \ l_i(\omega) = (\gamma_i - \gamma_i^{r_i}\omega)^2$

Machine Learning Problems

Have a bunch of iid data of the form:



Machine Learning Problems

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$$\{(x_i, y_i)\}_{i=1}^n \qquad x_i \in \mathbb{R}^d \qquad y_i \in \mathbb{R}$$

• Learning a model's parameters: Each $\ell_i(w)$ is convex.

$$\sum_{i=1}^{n} \ell_i(w)$$

Logistic Loss: $\ell_i(w) = \log(1 + \exp(-y_i x_i^T w))$ Squared error Loss: $\ell_i(w) = (y_i - x_i^T w)^2$

Least squares

Have a bunch of iid data of the form:

$$\{(x_i, y_i)\}_{i=1}^n \qquad x_i \in \mathbb{R}^d \qquad y_i \in \mathbb{R}$$

• Learning a model's parameters: Each $\ell_i(w)$ is convex. Squared error Loss: $\ell_i(w) = (y_i - x_i^T w)^2$ How does software solve: $\frac{1}{2} ||Xw - y||_2^2$

Least squares

Have a bunch of iid data of the form:

 $\{(x_i, y_i)\}_{i=1}^n \quad x_i \in \mathbb{R}^d \quad y_i \in \mathbb{R}$ • Learning a model's parameters: Each $\ell_i(w)$ is convex. Squared error Loss: $\ell_i(w) = (y_i - x_i^T w)^2$ How does software solve: $\frac{1}{2} ||Xw - y||_2^2$

> ...its complicated: (LAPACK, BLAS, MKL...)

Do you need high precision? Is X column/row sparse? Is \widehat{w}_{LS} sparse? Is $X^T X$ "well-conditioned"? Can $X^T X$ fit in cache/memory?

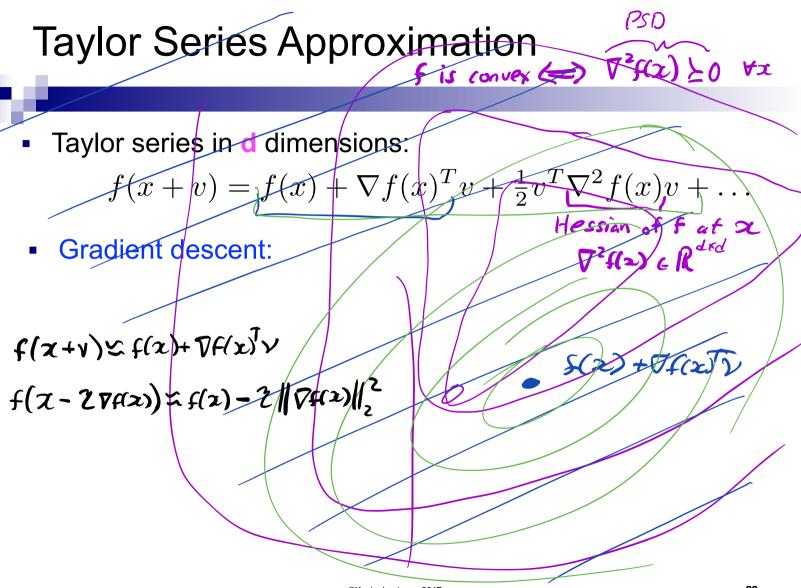
Taylor Series Approximation

Taylor series in one dimension:

$$f(x + \delta) = f(x) + f'(x)\delta + \frac{1}{2}f''(x)\delta^{2} + \dots$$

• Gradient descent:

$$\begin{aligned}
\chi_{next} = \chi_{trine_{t}} - \chi_{f}'(\chi_{turre_{t}}) \\
f(x + f) \approx f(x) + f'(x)\delta \\
f(x - \chi_{f}'(x)) \propto f(x) - \chi_{f}'(x)^{2} \\
f(x + \delta) \\$$



Gradient Descent $f(w) = \frac{1}{2} ||Xw - y||_2^2$

$$\begin{split} w_{t+1} &= w_t - \eta \nabla f(w_t) \\ \overline{\nabla f(w)} &= \mathbf{X}^T (\mathbf{X} \omega - \mathbf{y}) \\ \omega_{t+1} &= \omega_t - \mathcal{Z} (\mathbf{X}^T \mathbf{X} \omega_t - \mathbf{X}^T \mathbf{y}) \\ \omega_{t+1} &= \omega_t - \mathcal{Z} (\mathbf{X}^T \mathbf{X} \omega_t - \mathbf{X}^T \mathbf{y}) \\ \omega_{t+1} &= \omega_t - \mathcal{Z} (\mathbf{X}^T \mathbf{X} \omega_t - \mathbf{X}^T \mathbf{y}) \\ (\omega_{t+1} - \omega_{\mathbf{x}})^{-1} (\omega_t - \omega_{\mathbf{x}}) - \mathcal{Z} (\mathbf{X}^T \mathbf{X} \omega_t - \mathbf{X}^T \mathbf{y}) \\ &= (\omega_t - \omega_{\mathbf{x}}) - \mathcal{Z} (\mathbf{X}^T \mathbf{X} \omega_t - \mathbf{X}^T \mathbf{X} \omega_{\mathbf{x}}) \\ = (\omega_t - \omega_{\mathbf{x}}) - \mathcal{Z} (\mathbf{X}^T \mathbf{X} \omega_t - \mathbf{X}^T \mathbf{X} \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) - \mathcal{Z} (\mathbf{X}^T \mathbf{X} \mathbf{x} - \mathbf{X}^T \mathbf{X} \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) - \mathcal{Z} (\mathbf{X}^T \mathbf{X}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) (\omega_t - \omega_{\mathbf{x}}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{x}) \\ &= (\mathbf{X} - \mathbf{X} \mathbf{$$

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30

Gradient Descent
$$f(w) = \frac{1}{2} ||Xw - y||_{2}^{2}$$
$$w_{t+1} = w_{t} - \eta \nabla f(w_{t})$$
$$(w_{t+1} - w_{*}) = (I - \eta X^{T} X)(w_{t} - w_{*})$$
$$= (I - \eta X^{T} X)^{t+1}(w_{0} - w_{*})$$
Example:
$$X = \begin{bmatrix} 10^{-3} & 0 \\ 0 & 1 \end{bmatrix} \quad y = \begin{bmatrix} 10^{-3} \\ 1 \end{bmatrix} \quad w_{0} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad w_{*} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
$$\sqrt{Y} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad y = \begin{bmatrix} 10^{-3} \\ 1 \end{bmatrix} \quad w_{0} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad w_{*} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Taylor Series Approximation

Taylor series in one dimension:

$$f(x+\delta) = f(x) + f'(x)\delta + \frac{1}{2}f''(x)\delta^{2} + \dots$$

• Newton's method: f(2+s) = f(x)+f'(x) + f''(2) + f''(2

Taylor Series Approximation

Taylor series in d dimensions:

$$f(x+v) = f(x) + \nabla f(x)^T v + \frac{1}{2} v^T \nabla^2 f(x) v + \dots$$

Newton's method:

Newton's Method $f(w) = \frac{1}{2} ||Xw - y||_2^2$

$$\nabla f(w) = \mathbf{X}^{\mathsf{T}} (\mathbf{X}_{\mathsf{w}} - \mathbf{Y})$$

$$\nabla^{2} f(w) = \mathbf{X}^{\mathsf{T}} \mathbf{X}$$

$$v_{t} \text{ is solution to } : \nabla^{2} f(w_{t}) v_{t} = -\nabla f(w_{t})$$

$$w_{t+1} = w_{t} + \eta v_{t}$$

Newton's Method $f(w) = \frac{1}{2} ||Xw - y||_2^2$

$$\nabla f(w) = \mathbf{X}^{T} (\mathbf{X}w - \mathbf{y})$$

$$\nabla^{2} f(w) = \mathbf{X}^{T} \mathbf{X}$$

$$v_{t} \text{ is solution to } : \nabla^{2} f(w_{t}) v_{t} = -\nabla f(w_{t})$$

$$w_{t+1} = w_{t} + \eta v_{t}$$

$$V_{t} : (\mathbf{x}' \mathbf{x})^{*} \mathbf{x}' \mathbf{y}$$

For quadratics, Newton's method converges in one step! (Not a surprise, why?)

$$w_1 = w_0 - \eta (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T (\mathbf{X} w_0 - y) = w_*$$

$$(\mathbf{X}^{\uparrow} \mathbf{Y})^{\uparrow} \mathbf{V}^{\uparrow} \mathbf{y}$$

General case

In general for Newton's method to achieve $f(w_t) - f(w_*) \le \epsilon$:

$$t \simeq O(log(log(l(e))))$$

So why are ML problems overwhelmingly solved by gradient methods?

Hint: v_t is solution to : $\nabla^2 f(w_t)v_t = -\nabla f(w_t)$

General Convex case $f(w_t) - f(w_*) \le \epsilon$

Newton's method:

 $t\approx \log(\log(1/\epsilon))$

Gradient descent:

- f is smooth and strongly convex: $aI \preceq \nabla^2 f(w) \preceq bI$
- f is smooth: $\nabla^2 f(w) \preceq bI$
- f is potentially non-differentiable: $||\nabla f(w)||_2 \leq c$

Nocedal +Wright, Bubeck

Clean converge nce proofs: Bubeck

Other: BFGS, Heavy-ball, BCD, SVRG, ADAM, Adagrad,...

Revisiting... Logistic Regression

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• Have a bunch of iid data of the form: $\{(x_i,y_i)\}_{i=1}^n$ $x_i\in\mathbb{R}^d, y_i\in\{-1,1\}$

$$\widehat{w}_{MLE} = \arg \max_{w} \prod_{i=1}^{n} P(y_i | x_i, w) \qquad P(Y = y | x, w) = \frac{1}{1 + \exp(-y \, w^T x)}$$
$$f(w) = \arg \min_{w} \sum_{i=1}^{n} \log(1 + \exp(-y_i \, x_i^T w))$$

 $\nabla f(w) =$

Stochastic Gradient Descent: A Learning perspective

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Learning Problems as Expectations

Minimizing loss in training data:

- Given dataset:
 - Sampled iid from some distribution p(x) on features:
- Loss function, e.g., hinge loss, logistic loss,...
- We often minimize loss in training data:

$$\ell_{\mathcal{D}}(\mathbf{w}) = \frac{1}{N} \sum_{j=1}^{N} \ell(\mathbf{w}, \mathbf{x}^j)$$

- However, we should really minimize expected loss on all data:

$$\ell(\mathbf{w}) = E_{\mathbf{x}} \left[\ell(\mathbf{w}, \mathbf{x})\right] = \int p(\mathbf{x})\ell(\mathbf{w}, \mathbf{x})d\mathbf{x}$$

• So, we are approximating the integral by the average on the training data

Gradient ascent in Terms of Expectations

• "True" objective function:

$$\ell(\mathbf{w}) = E_{\mathbf{x}} \left[\ell(\mathbf{w}, \mathbf{x}) \right] = \int p(\mathbf{x}) \ell(\mathbf{w}, \mathbf{x}) d\mathbf{x}$$

• Taking the gradient:

١

• "True" gradient ascent rule:

How do we estimate expected gradient?

SGD: Stochastic Gradient Ascent (or Descent)

"True" gradient:

$$\nabla \ell(\mathbf{w}) = E_{\mathbf{x}} \left[\nabla \ell(\mathbf{w}, \mathbf{x}) \right]$$

• Sample based approximation:

- What if we estimate gradient with just one sample???
 - Unbiased estimate of gradient
 - Very noisy!
 - Called stochastic gradient ascent (or descent)
 - Among many other names
 - VERY useful in practice!!!

Stochastic Gradient Ascent for Logistic Regression

Logistic loss as a stochastic function:

$$E_{\mathbf{x}}\left[\ell(\mathbf{w}, \mathbf{x})\right] = E_{\mathbf{x}}\left[\ln P(y|\mathbf{x}, \mathbf{w}) - \lambda ||\mathbf{w}||_{2}^{2}\right]$$

Batch gradient ascent updates:

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \left\{ -\lambda w_i^{(t)} + \frac{1}{N} \sum_{j=1}^N x_i^{(j)} [y^{(j)} - P(Y = 1 | \mathbf{x}^{(j)}, \mathbf{w}^{(t)})] \right\}$$

- Stochastic gradient ascent updates:
 - Online setting:

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta_t \left\{ -\lambda w_i^{(t)} + x_i^{(t)} [y^{(t)} - P(Y = 1 | \mathbf{x}^{(t)}, \mathbf{w}^{(t)})] \right\}$$