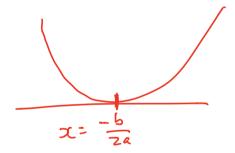
Warm up $\{(x_i, y_i)\}_{i=1}^n$

$$\mathbb{E}_{\mathbf{g}}[h(\mathbf{g})] = \int h(\mathbf{g}_{\mathbf{g}}\mathbf{g}_{\mathbf{g}_{\mathbf{r}}}^{n}) d\mathbf{g}(\mathbf{g}_{\mathbf{g}})$$

Fix any a, b, c > 0.

1. What is the $x \in \mathbb{R}$ that minimizes $ax^2 + bx + c$



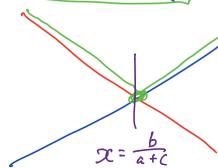


$$X = \frac{-b}{Z\alpha}$$

2. What is the $x \in \mathbb{R}$ that minimizes $\max\{-ax+b, cx\}$

$$-ax+b=cx$$

$$x=\frac{b}{a+c}$$



Fix some ZERd

Overfitting

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Oct 9, 2018

Bias-Variance Tradeoff

- Choice of hypothesis class introduces learning bias
 - □ More complex class → less bias
 - □ More complex class → more variance
- But in practice??
- Before we saw how increasing the feature space can increase the complexity of the learned estimator:

$$\mathcal{F}_1 \subset \mathcal{F}_2 \subset \mathcal{F}_3 \subset \dots$$

$$\widehat{f}_{\mathcal{D}}^{(k)} = \arg\min_{f \in \mathcal{F}_k} \frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - f(x_i))^2$$

Complexity grows as k grows

Training set error as a function of model complexity

$$\overline{\mathcal{F}}_1 \subset \mathcal{F}_2 \subset \mathcal{F}_3 \subset \dots \quad \mathcal{D} \stackrel{i.i.d.}{\sim} P_{XY}$$

$$\widehat{f}_{\mathcal{D}}^{(k)} = \arg \min_{f \in \mathcal{F}_k} \frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - f(x_i))^2$$

TRAIN error:

$$\frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - \widehat{f}_{\mathcal{D}}^{(k)}(x_i))^2$$

TRUE error:

$$\mathbb{E}_{XY}[(Y - \widehat{f}_{\mathcal{D}}^{(k)}(X))^2]$$

Training set error as a function of model complexity

$$\overline{\mathcal{F}}_1 \subset \mathcal{F}_2 \subset \mathcal{F}_3 \subset \dots \quad \mathcal{D} \stackrel{i.i.d.}{\sim} P_{XY}$$

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$$\overset{i.i.a.}{\sim} P_{XY}$$

$$= f(x_i))^2$$

$$\frac{1}{|\mathcal{D}|} \sum_{\substack{(x_i, y_i) \in \mathcal{D}}} (y_i - \widehat{f}_{\mathcal{D}}^{(k)}(x_i))^2$$

TRUE error:

$$\mathbb{E}_{XY}[(Y-\widehat{f}_{\mathcal{D}}^{(k)}(X))^2]$$

TEST error:

$$\mathcal{T} \overset{i.i.d.}{\sim} P_{XY}$$

$$\frac{1}{|\mathcal{T}|} \sum_{(x_i, y_i) \in \mathcal{T}} (y_i - \widehat{f}_{\mathcal{D}}^{(k)}(x_i))^2$$
Important: $\mathcal{D} \cap \mathcal{T} = \emptyset$

Complexity (k)

Training set error as a function of model complexity

Plot from Hastie et al

$$\widehat{\mathcal{F}}_1 \subset \mathcal{F}_2 \subset \mathcal{F}_3 \subset \dots \quad \mathcal{D} \overset{i.i.d.}{\sim} P_{XY}$$

$$\widehat{f}_{\mathcal{D}}^{(k)} = \arg\min_{f \in \mathcal{F}_k} \frac{1}{|\mathcal{D}|} \sum_{(x_i,y_i) \in \mathcal{D}} (y_i - f(x_i))^2$$

$$\lim_{\theta \to \infty} \lim_{\theta \to \infty} \lim_{\theta$$

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TRAIN error:

$$\frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - \widehat{f}_{\mathcal{D}}^{(k)}(x_i))^2$$

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Training set error as a function of model complexity

$$\overline{\mathcal{F}}_1 \subset \mathcal{F}_2 \subset \mathcal{F}_3 \subset \dots \quad \mathcal{D} \stackrel{i.i.d.}{\sim} P_{XY}$$

$$\widehat{f}_{\mathcal{D}}^{(k)} = \arg \min_{f \in \mathcal{F}_k} \frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - f(x_i))^2$$

TRAIN error is **optimistically biased** because it is evaluated on the data it trained on. **TEST error** is **unbiased** only if *T* is never used to train the model or even pick the complexity k.

TRAIN error:

$$\frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - \widehat{f}_{\mathcal{D}}^{(k)}(x_i))^2$$

TRUE error:

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$$\frac{1}{|\mathcal{T}|} \sum_{(x_i, y_i) \in \mathcal{T}} (y_i - \widehat{f}_{\mathcal{D}}^{(k)}(x_i))^2$$

Important: $\mathcal{D} \cap \mathcal{T} = \emptyset$

Test set error

- Given a dataset, randomly split it into two parts:
 - Training data:
 - □ Test data: *T*

Important:
$$\mathcal{D} \cap \mathcal{T} = \emptyset$$

- Use training data to learn predictor
 - e.g., $\frac{1}{|\mathcal{D}|} \sum_{(x_i,y_i) \in \mathcal{D}} (y_i \widehat{f}_{\mathcal{D}}^{(k)}(x_i))^2$
 - use training data to pick complexity k
- Use test data to report predicted performance

$$\frac{1}{|\mathcal{T}|} \sum_{(x_i, y_i) \in \mathcal{T}} (y_i - \widehat{f}_{\mathcal{D}}^{(k)}(x_i))^2$$

Regularization

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Regularization in Linear Regression

Recall Least Squares:
$$\widehat{w}_{LS} = \arg\min_{w} \sum_{i=1}^{N} (y_i - x_i^T w)^2$$

When $x_i \in \mathbb{R}^d$ and d > n the objective function is flat in some directions:

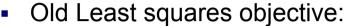
Implies optimal solution is *underconstrained* and unstable due to lack of curvature:

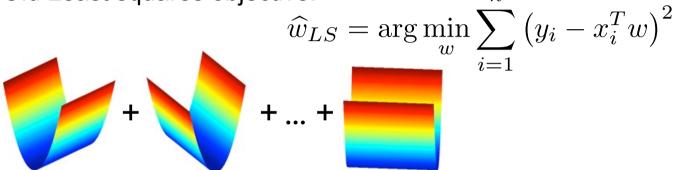
- small changes in training data result in large changes in solution
- often the *magnitudes* of *w* are "very large"



Regularization imposes "simpler" solutions by a "complexity" penalty

Ridge Regression





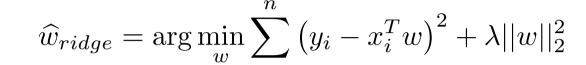
Ridge Regression objective:

$$\widehat{w}_{ridge} = \arg\min_{w} \sum_{i=1}^{n} (y_i - x_i^T w)^2 + \lambda ||w||_2^2$$

$$+ \dots + \dots + \lambda$$

Shrinkage Properties $\epsilon \sim \mathcal{N}(0, \sigma^2 I)$

$$\epsilon \sim \mathcal{N}(0,\sigma^2 I)$$



$$\widehat{w}_{ridge} = (\mathbf{X}^T \mathbf{X} + \lambda I)^{-1} \mathbf{X}^T \mathbf{y}$$

- Assume: $\mathbf{X}^T\mathbf{X}=nI$ and $\mathbf{y}=\mathbf{X}w+oldsymbol{\epsilon}$

$$\widehat{w}_{ridge} = (\mathbf{X}^T \mathbf{X} + \lambda I)^{-1} \mathbf{X}^T (\mathbf{X} w + \boldsymbol{\epsilon})$$
$$= \frac{n}{n+\lambda} w + \frac{1}{n+\lambda} \mathbf{X}^T \boldsymbol{\epsilon}$$

$$\mathbb{E}\|\widehat{w}_{ridge} - w\|^2 = \frac{\lambda^2}{(n+\lambda)^2} \|w\|^2 + \frac{dn\sigma^2}{(n+\lambda)^2}$$

$$\mathbb{E}\|\widehat{w}_{ridge} - w\|^2 = \frac{\lambda^2}{(n+\lambda)^2} \|w\|^2 + \frac{dn\sigma^2}{(n+\lambda)^2}$$

 $\lambda^* = \frac{d\sigma^2}{\|y\|^2}$

Ridge Regression: Effect of Regularization



$$\widehat{w}_{ridge} = \arg\min_{w} \sum_{i=1}^{n} (y_i - x_i^T w)^2 + \lambda ||w||_2^2$$

- Solution is indexed by the regularization parameter λ
- Larger λ
- Smaller λ
- As $\lambda \rightarrow 0$
- As λ →∞

Ridge Regression: Effect of Regularization



$$\mathcal{D} \overset{i.i.d.}{\sim} P_{XY}$$

$$\widehat{w}_{\mathcal{D},ridge}^{(\lambda)} = \arg\min_{w} \frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - x_i^T w)^2 + \lambda ||w||_2^2$$

TRAIN error:

$$\widehat{w}_{\mathcal{D},ridge}^{(\lambda)} = \arg\min_{w} \frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - x_i^T w)^2 + \lambda ||w||_2^2 \qquad \frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - x_i^T \widehat{w}_{\mathcal{D},ridge}^{(\lambda)})^2$$

TRUE error:

$$\mathbb{E}[(Y - X^T \widehat{w}_{\mathcal{D},ridge}^{(\lambda)})^2]$$

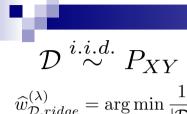
TEST error:

$$\mathcal{T} \overset{i.i.d.}{\sim} P_{XY}$$

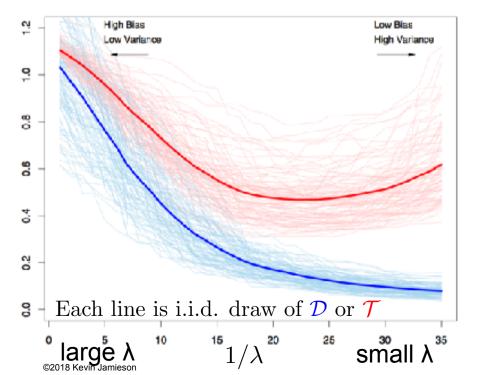
$$\frac{1}{|\mathcal{T}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - x_i^T \widehat{w}_{\mathcal{D}, ridge}^{(\lambda)})^2$$

Important: $\mathcal{D} \cap \mathcal{T} = \emptyset$

Ridge Regression: Effect of Regularization



$$\widehat{w}_{\mathcal{D},ridge}^{(\lambda)} = \arg\min_{w} \frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - x_i^T w)^2 + \lambda ||w||_2^2$$



TRAIN error:

$$\frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - x_i^T \widehat{w}_{\mathcal{D}, ridge}^{(\lambda)})^2$$

TRUE error:

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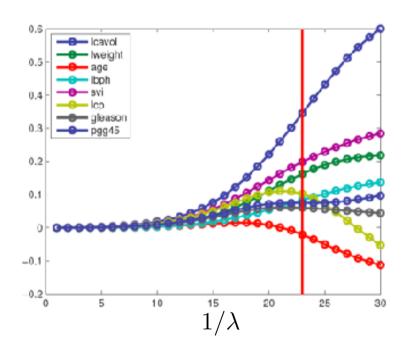
TEST error:

$$\mathcal{T} \overset{i.i.d.}{\sim} P_{XY}$$

$$\frac{1}{|\mathcal{T}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - x_i^T \widehat{w}_{\mathcal{D}, ridge}^{(\lambda)})^2$$

Important: $\mathcal{D} \cap \mathcal{T} = \emptyset$

Ridge Coefficient Path



From Kevin Murphy textbook

Typical approach: select λ using cross validation, up next

What you need to know...

- Regularization
 - Penalizes for complex models
- Ridge regression
 - L₂ penalized least-squares regression
 - Regularization parameter trades off model complexity with training error

Cross-Validation

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How... How... How???????

- How do we pick the regularization constant λ...
- How do we pick the number of basis functions...

We could use the test data, but...

How... How... How???????

- How do we pick the regularization constant λ...
- How do we pick the number of basis functions...
- We could use the test data, but...

(LOO) Leave-one-out cross validation

- Consider a validation set with 1 example:
 - D training data
 - $D \setminus j$ –)training data with j th data point $(\mathbf{x}_j, \mathbf{y}_j)$ moved to validation set
- Learn classifier $f_{D \setminus i}$ with $D \setminus j$ dataset
- Estimate true error as squared error on predicting y_i:
 - Unbiased estimate of error_{true}(f_{D\i})!

(LOO) Leave-one-out cross validation



- □ D training data
- □ $D \setminus j$ training data with j th data point $(\mathbf{x}_i, \mathbf{y}_i)$ moved to validation set
- Learn classifier f_{D\i} with D\j dataset
- Estimate true error as squared error on predicting y_i:
 - □ Unbiased estimate of $error_{true}(\mathbf{f}_{D\setminus i})!$

- LOO cross validation: Average over all data points j:

 - Estimate error as:

$$\operatorname{error}_{LOO} = \frac{1}{n} \sum_{j=1}^{n} (y_j - f_{\mathcal{D}\setminus j}(x_j))^2$$

LOO cross validation is (almost) unbiased estimate of true error of h_D !

- When computing LOOCV error, we only use N-1 data points
 - So it's not estimate of true error of learning with N data points
 - Usually pessimistic, though learning with less data typically gives worse answer
- LOO is almost unbiased! Use LOO error for model selection!!!
 - E.g., picking λ

Computational cost of LOO

- Suppose you have 100,000 data points
- You implemented a great version of your learning algorithm
 - Learns in only 1 second
- Computing LOO will take about 1 day!!!

Use k-fold cross validation



- Randomly divide training data into k equal parts
 - D_1, \ldots, D_k
- For each i
 - Learn classifier $f_{D \setminus D_i}$ using data point not in D_i
 - Estimate error of f_{D\Di} on validation set D_i:



$\operatorname{error}_{\mathcal{D}_{\cdot}} =$	1	$\overline{}$	(21	$-f_{\mathcal{D}\setminus\mathcal{D}_i}$	$(x_{\cdot})^2$
error_i –	$\overline{ \mathcal{D}_i }$			$-J\mathcal{D}\backslash\mathcal{D}_i$	(x_j)
	1 - i (a	$(x_j,y_j)\in\mathcal{I}$	\mathcal{O}_i		

Use k-fold cross validation



- Randomly divide training data into k equal parts
 - \square $D_1,...,D_k$
- For each i
 - □ Learn classifier $f_{D \setminus Di}$ using data point not in D_i
 - Estimate error of $f_{D \setminus Di}$ on validation set D_i :



$$\operatorname{error}_{\mathcal{D}_i} = \frac{1}{|\mathcal{D}_i|} \sum_{(x_j, y_j) \in \mathcal{D}_i} (y_j - f_{\mathcal{D} \setminus \mathcal{D}_i}(x_j))^2$$

k-fold cross validation error is average over data splits:

$$error_{k-fold} = \frac{1}{k} \sum_{i=1}^{k} error_{\mathcal{D}_i}$$

- *k*-fold cross validation properties:
 - Much faster to compute than LOO
 - **More (pessimistically) biased** using much less data, only n(k-1)/k
 - Usually, k = 10

Recap

Given a dataset, begin by splitting into

TRAIN TEST

 Model selection: Use k-fold cross-validation on TRAIN to train predictor and choose magic parameters such as λ

TRA!N TRA

TRAIN-2 VAL-2 TRAIN-2

VAL-3 TRAIN-3

- Model assessment: Use TEST to assess the accuracy of the model you output
 - Never ever ever ever train or choose parameters based on the test data

Example

1) Make CV splits 2) Then pick 50 and perform (Von A

 Given 10,000-dimensional data and n examples, we pick a subset of 50 dimensions that have the highest correlation with labels in the training set:

50 indices j that have largest
$$\frac{|\sum_{i=1}^n x_{i,j}y_i|}{\sqrt{\sum_{i=1}^n x_{i,j}^2}}$$

- After picking our 50 features, we then use CV to train ridge regression with regularization λ
- What's wrong with this procedure?

Recap

- Learning is...
 - Collect some data
 - E.g., housing info and sale price
 - Randomly split dataset into TRAIN, VAL, and TEST
 - E.g., 80%, 10%, and 10%, respectively
 - Choose a hypothesis class or model
 - E.g., linear with non-linear transformations
 - Choose a loss function
 - E.g., least squares with ridge regression penalty on TRAIN
 - Choose an optimization procedure
 - E.g., set derivative to zero to obtain estimator, cross-validation on VAL to pick num. features and amount of regularization
 - Justifying the accuracy of the estimate
 - E.g., report TEST error

Simple Variable Selection LASSO: Sparse Regression

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Sparsity

$$\widehat{w}_{LS} = \arg\min_{w} \sum_{i=1}^{n} (y_i - x_i^T w)^2$$

- Vector w is sparse, if many entries are zero
- Very useful for many tasks, e.g.,
 - Efficiency: If size(w) = 100 Billion, each prediction is expensive:
 - If part of an online system, too slow
 - If w is sparse, prediction computation only depends on number of non-zeros

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 - Interpretability: What are the relevant dimension to make a prediction?
 - E.g., what are the parts of the brain associated with particular words?

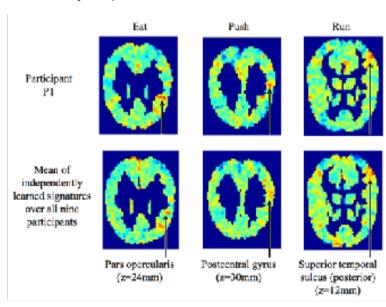


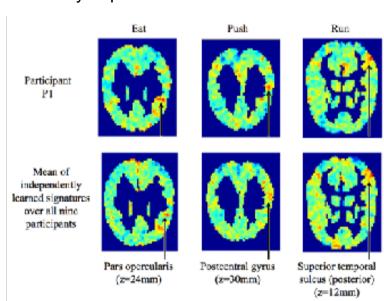
Figure from Tom Mitchell

Sparsity

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How do we find "best" subset among all possible?



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Figure from Tom Mitchel

Greedy model selection algorithm

- Pick a dictionary of features
 - □ e.g., cosines of random inner products
- Greedy heuristic:
 - □ Start from empty (or simple) set of features $F_0 = \emptyset$
 - \square Run learning algorithm for current set of features F_t
 - Obtain weights for these features
 - □ Select next best feature h_i(x)*
 - e.g., $h_j(x)$ that results in lowest training error learner when using $F_t + \{h_i(x)^*\}$
 - $\Box F_{t+1} \leftarrow F_t + \{h_i(x)^*\}$
 - Recurse

Greedy model selection

- Applicable in many other settings:
 - Considered later in the course:
 - Logistic regression: Selecting features (basis functions)
 - Naïve Bayes: Selecting (independent) features P(X_i|Y)
 - Decision trees: Selecting leaves to expand
- Only a heuristic!
 - Finding the best set of k features is computationally intractable!
 - □ Sometimes you can prove something strong about it...

When do we stop???

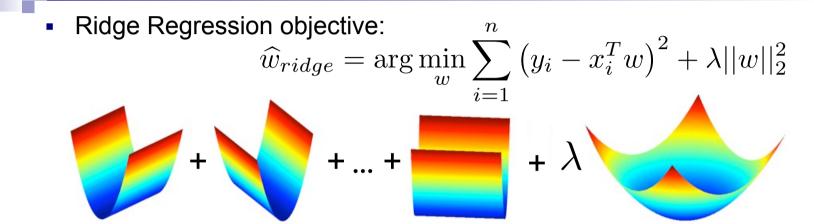
- Greedy heuristic:
 - _____
 - Select next best feature X_i*
 - E.g. $h_j(x)$ that results in lowest training error learner when using $F_t + \{h_i(x)^*\}$
 - Recurse

When do you stop???

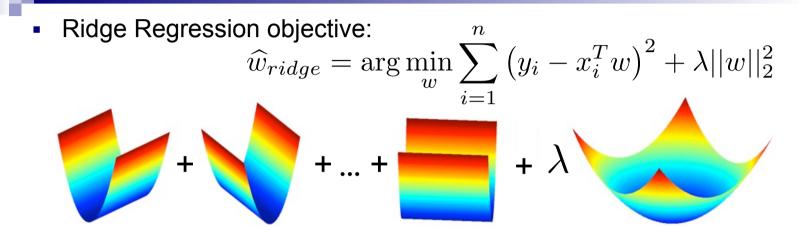
- When training error is low enough?
- When test set error is low enough?
- Using cross validation?

Is there a more principled approach?

Recall Ridge Regression



Ridge vs. Lasso Regression



Lasso objective:

asso objective:
$$\widehat{w}_{lasso} = \arg\min_{w} \sum_{i=1}^{n} \left(y_i - x_i^T w\right)^2 + \lambda ||w||_1$$

Penalized Least Squares

Ridge:
$$r(w) = ||w||_2^2$$
 Lasso: $r(w) = ||w||_1$

$$\widehat{w}_r = \arg\min_{w} \sum_{i=1}^n (y_i - x_i^T w)^2 + \lambda r(w)$$

Penalized Least Squares



Ridge:
$$r(w) = ||w||_2^2$$
 Lasso: $r(w) = ||w||_1$

$$\widehat{w}_r = \arg\min_{w} \sum_{i=1}^{n} (y_i - x_i^T w)^2 + \lambda r(w)$$

For any $\lambda \geq 0$ for which \widehat{w}_r achieves the minimum, there exists a $\nu \geq 0$ such that

$$\widehat{w}_r = \arg\min_{w} \sum_{i=1}^{n} (y_i - x_i^T w)^2$$
 subject to $r(w) \le \nu$

Penalized Least Squares



$$\widehat{w}_r = \arg\min_{w} \sum_{i=1}^n (y_i - x_i^T w)^2 + \lambda r(w)$$

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