

# EM Algorithm and its Applications

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## Outline

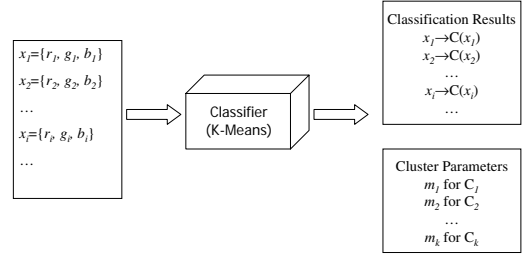
- Introduction of EM
  - K-Means → EM
- EM Applications
  - Image Segmentation using EM
  - Object Class Recognition in CBIR

## Color Clustering by K-means Algorithm

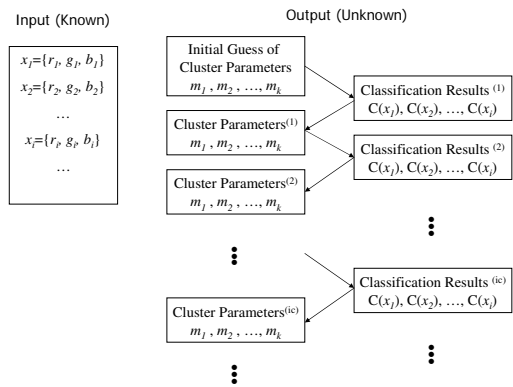
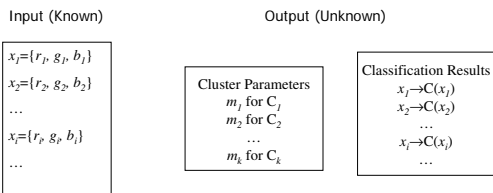
Form K-means clusters from a set of  $n$ -dimensional vectors

1. Set  $ic$  (iteration count) to 1
2. Choose randomly a set of  $K$  means  $m_1(I), \dots, m_k(I)$ .
3. For each vector  $x_i$ , compute  $D(x_i, m_k(ic)), k=1, \dots, K$  and assign  $x_i$  to the cluster  $C_j$  with nearest mean.
4. Increment  $ic$  by 1, update the means to get  $m_1(ic), \dots, m_k(ic)$ .
5. Repeat steps 3 and 4 until  $C_k(ic) = C_k(ic+1)$  for all  $k$ .

## K-Means Classifier



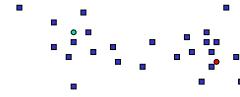
## K-Means Classifier (Cont.)



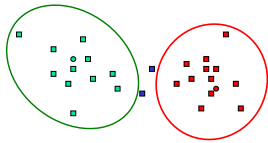
## K-Means (Cont.)

- **Boot Step:**
  - Initialize  $K$  clusters:  $C_1, \dots, C_K$   
Each Cluster is represented by its mean  $m_j$
- **Iteration Step:**
  - Estimate the cluster of each data  
 $x_i \Rightarrow C(x_i)$
  - Re-estimate the cluster parameters  
 $m_j = \text{mean}\{x_i \mid x_i \in C_j\}$

## K-Means Example



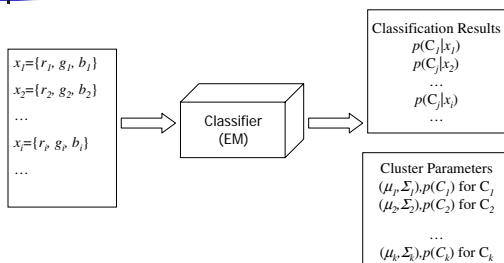
## K-Means Example



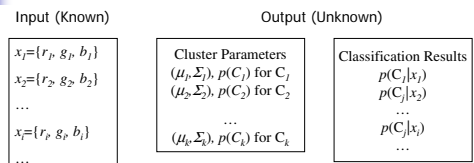
## K-Means $\rightarrow$ EM

- **Boot Step:**
  - Initialize  $K$  clusters:  $C_1, \dots, C_K$   
 $(\mu_j, \Sigma_j)$  and  $P(C_j)$  for each cluster  $j$ .
- **Iteration Step:**
  - Estimate the cluster of each data  $\rightarrow$  **Expectation**  
 $p(C_j \mid x_i)$
  - Re-estimate the cluster parameters  $\rightarrow$  **Maximization**  
 $(\mu_j, \Sigma_j), p(C_j)$  For each cluster  $j$

## EM Classifier



## EM Classifier (Cont.)



## Expectation Step

Input (Known)	Input (Estimation)	Output
$x_1 = \{r_1, g_1, b_1\}$ $x_2 = \{r_2, g_2, b_2\}$ ... $x_r = \{r_r, g_r, b_r\}$ ...	Cluster Parameters $(\mu_j, \Sigma_j), p(C_j)$ for $C_j$ $(\mu_2, \Sigma_2), p(C_2)$ for $C_2$ ... $(\mu_k, \Sigma_k), p(C_k)$ for $C_k$	Classification Results $p(C_j   x_1)$ $p(C_j   x_2)$ ... $p(C_j   x_r)$ ...

$$p(C_j | x_i) = \frac{p(x_i | C_j) \cdot p(C_j)}{p(x_i)} = \frac{p(x_i | C_j) \cdot p(C_j)}{\sum_j p(x_i | C_j) \cdot p(C_j)}$$

## Maximization Step

Input (Known)	Input (Estimation)	Output
$x_1 = \{r_1, g_1, b_1\}$ $x_2 = \{r_2, g_2, b_2\}$ ... $x_r = \{r_r, g_r, b_r\}$ ...	Classification Results $p(C_j   x_1)$ $p(C_j   x_2)$ ... $p(C_j   x_r)$ ...	Cluster Parameters $(\mu_j, \Sigma_j), p(C_j)$ for $C_j$ $(\mu_2, \Sigma_2), p(C_2)$ for $C_2$ ... $(\mu_k, \Sigma_k), p(C_k)$ for $C_k$

$$\mu_j = \frac{\sum_i p(C_j | x_i) \cdot x_i}{\sum_i p(C_j | x_i)} \quad \Sigma_j = \frac{\sum_i p(C_j | x_i) \cdot (x_i - \mu_j) \cdot (x_i - \mu_j)^T}{\sum_i p(C_j | x_i)} \quad p(C_j) = \frac{\sum_i p(C_j | x_i)}{N}$$

## EM Algorithm

- Boot Step:**
  - Initialize  $K$  clusters:  $C_1, \dots, C_K$   
 $(\mu_j, \Sigma_j)$  and  $p(C_j)$  for each cluster  $j$ .
- Iteration Step:**
  - Expectation Step  

$$p(C_j | x_i) = \frac{p(x_i | C_j) \cdot p(C_j)}{p(x_i)} = \frac{p(x_i | C_j) \cdot p(C_j)}{\sum_j p(x_i | C_j) \cdot p(C_j)}$$
  - Maximization Step  

$$\mu_j = \frac{\sum_i p(C_j | x_i) \cdot x_i}{\sum_i p(C_j | x_i)} \quad \Sigma_j = \frac{\sum_i p(C_j | x_i) \cdot (x_i - \mu_j) \cdot (x_i - \mu_j)^T}{\sum_i p(C_j | x_i)} \quad p(C_j) = \frac{\sum_i p(C_j | x_i)}{N}$$

## EM Demo

- Demo**  
<http://www.neurosci.aist.go.jp/~akaho/MixtureEM.html>
- Example**  
<http://www-2.cs.cmu.edu/~awm/tutorials/gmm13.pdf>

## EM Applications

- Blobworld: Image Segmentation Using Expectation-Maximization and its Application to Image Querying**

## Image Segmentation using EM

- Step 1: Feature Extraction**
- Step 2: Image Segmentation using EM**

## Symbols

- The feature vector for pixel  $i$  is called  $x_i$ .
- There are going to be  $K$  segments;  $K$  is given.
- The  $j$ -th segment has a Gaussian distribution with parameters  $\theta_j = (\mu_j, \Sigma_j)$ .
- $\alpha_j$ 's are the weights (which sum to 1) of Gaussians.  $\Theta$  is the collection of parameters:  $\Theta = (\alpha_1, \dots, \alpha_k, \theta_1, \dots, \theta_k)$

## Initialization

- Each of the  $K$  Gaussians will have parameters  $\theta_j = (\mu_j, \Sigma_j)$ , where
  - $\mu_j$  is the mean of the  $j$ -th Gaussian.
  - $\Sigma_j$  is the covariance matrix of the  $j$ -th Gaussian.
- The covariance matrices are initiated to be the identity matrix.
- The means can be initialized by finding the average feature vectors in each of  $K$  windows in the image; this is data-driven initialization.

## E-Step

$$p(j | x_i, \Theta) = \frac{\alpha_j f_j(x_i | \theta_j)}{\sum_{k=1}^K \alpha_k f_k(x_i | \theta_k)}$$

$$f_j(x | \theta_j) = \frac{1}{(2\pi)^{d/2} |\Sigma_j|^{1/2}} e^{-\frac{1}{2}(x-\mu_j)^T \Sigma_j^{-1} (x-\mu_j)}$$

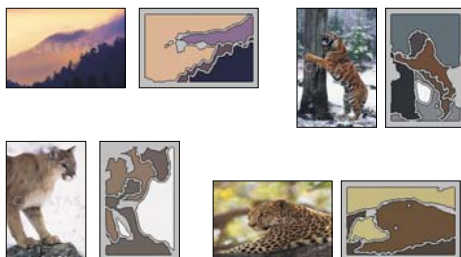
## M-Step

$$\mu_j^{new} = \frac{\sum_{i=1}^N x_i p(j | x_i, \Theta^{old})}{\sum_{i=1}^N p(j | x_i, \Theta^{old})}$$

$$\Sigma_j^{new} = \frac{\sum_{i=1}^N p(j | x_i, \Theta^{old}) (x_i - \mu_j^{new})(x_i - \mu_j^{new})^T}{\sum_{i=1}^N p(j | x_i, \Theta^{old})}$$

$$\alpha_j^{new} = \frac{1}{N} \sum_{i=1}^N p(j | x_i, \Theta^{old})$$

## Sample Results



## Object Class Recognition in CBIR

- The Goal: Automatic image labeling (annotation) to enable object-based image retrieval

## Problem Statement

**Known:** Some images and their corresponding descriptions

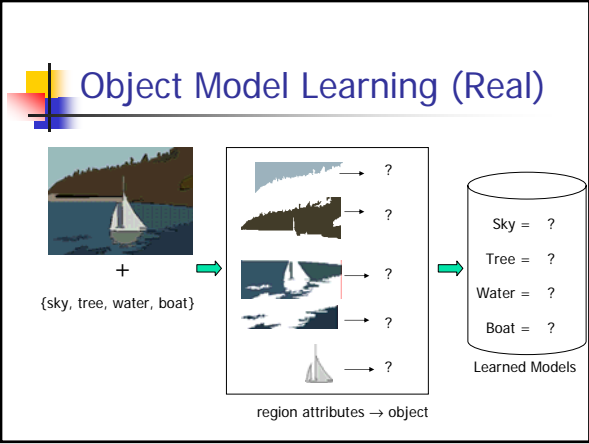
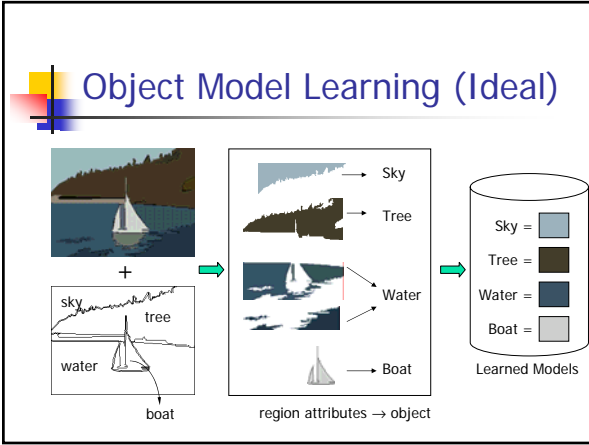
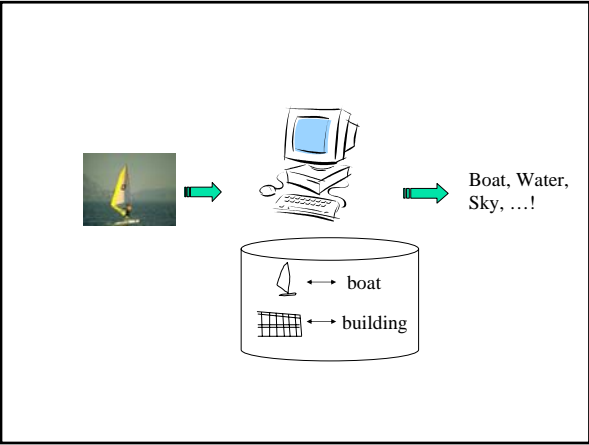
{trees, grass, cherry trees} {cheetah, trunk} {mountains, sky} {beach, sky, trees, water} ...

**To solve:** What object classes are present in new images

? ? ? ? ...

## Abstract Regions

Original Images	Color Regions	Texture Regions	Line Clusters

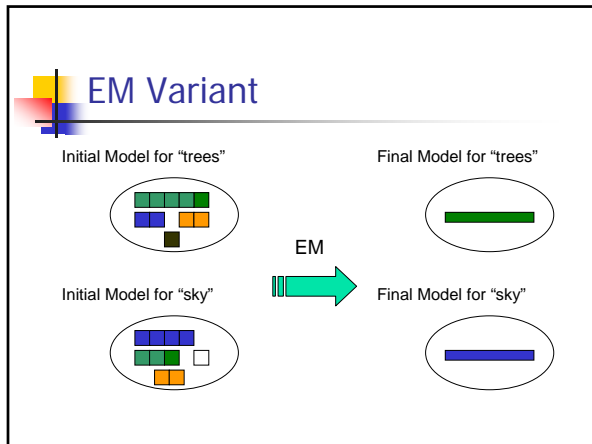


## Model Initial Estimation

- Estimate the initial model of an object using all the region features from all images that contain the object

Tree

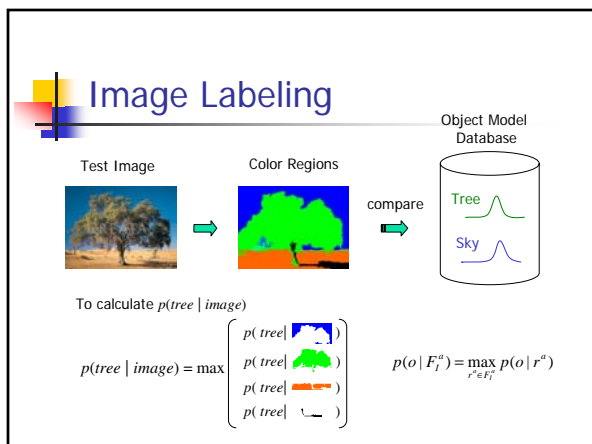
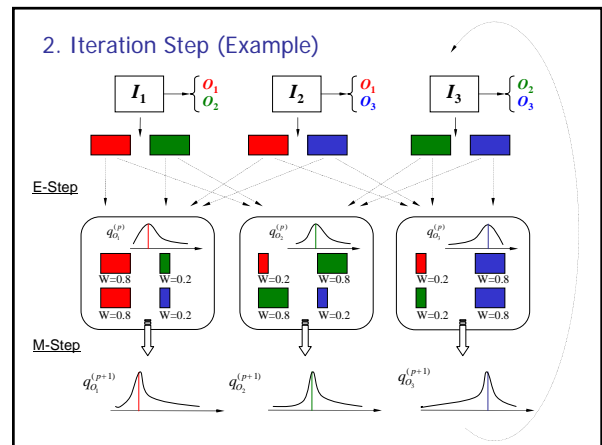
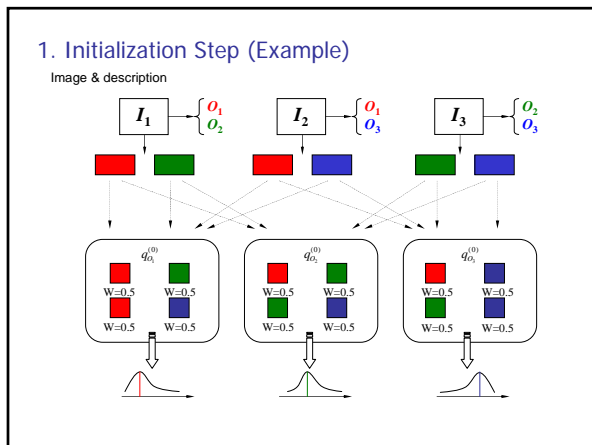
Sky



## Object Model Learning

### Assumptions

- The feature distribution of each object within a region is a Gaussian;
- Each image is a set of regions, each of which can be modeled as a mixture of multivariate Gaussian distributions.



## Experiments

- 860 images
- 18 keywords: mountains (30), orangutan (37), track (40), tree trunk (43), football field (43), beach (45), prairie grass (53), cherry tree (53), snow (54), zebra (56), polar bear (56), lion (71), water (76), chimpanzee (79), cheetah (112), sky (259), grass (272), tree (361).
- A set of cross-validation experiments (80% as the training set and the other 20% as the test set)

