




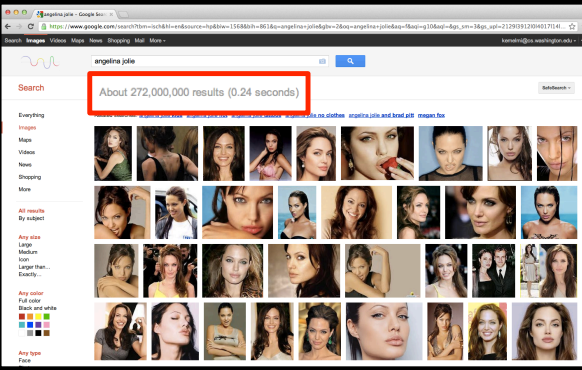
Computer Vision and Graphics In the Wild

Personal collections:  **> Trillion**

Online collections:  **250 Billion**
250 million/day

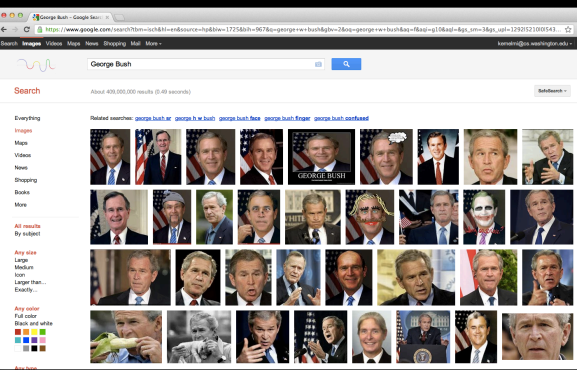
Videos:  **48 hours/minute**

Variation in faces captured in Internet photos



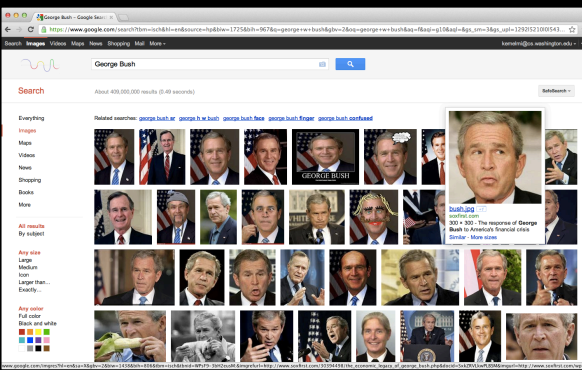
Search: **angelina jolie**
About 272,000,000 results (0.24 seconds)

Variation in faces captured in Internet photos

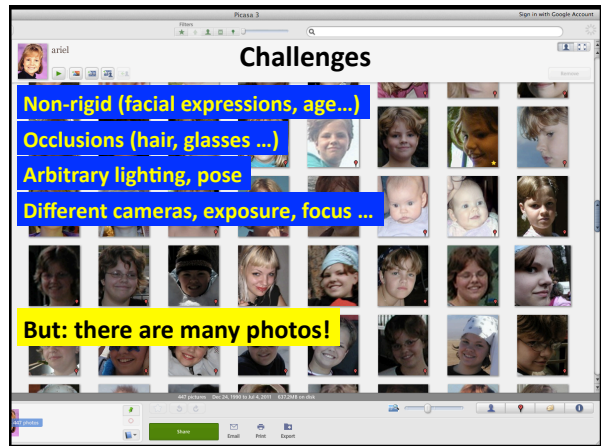
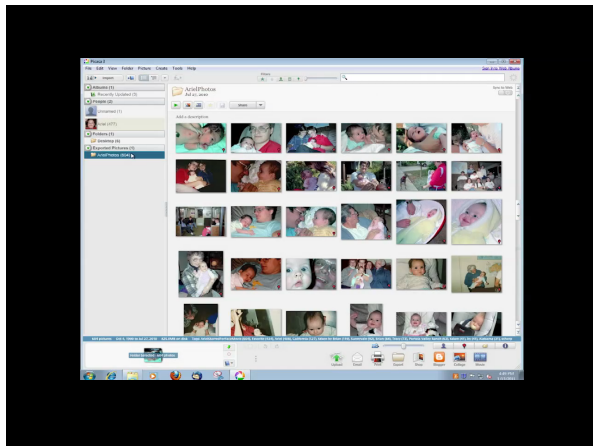
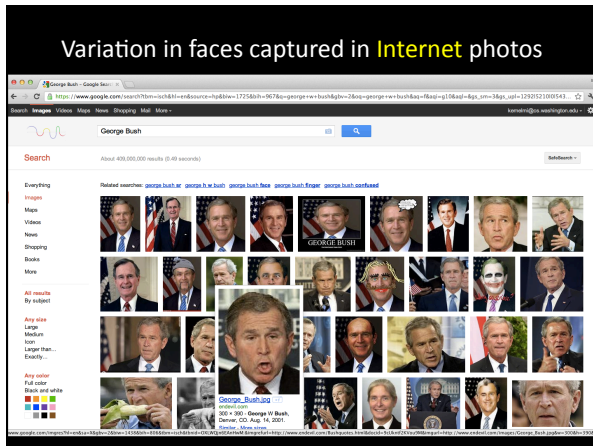


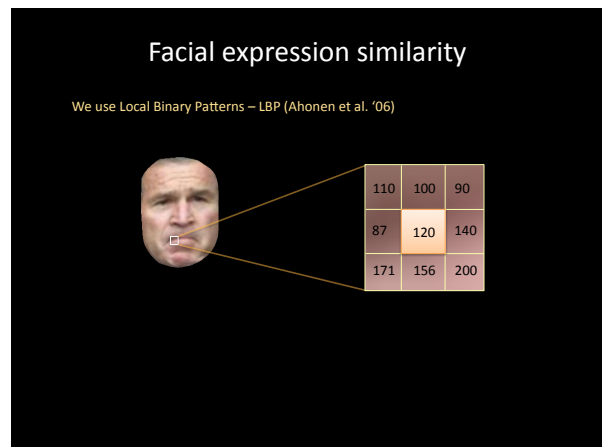
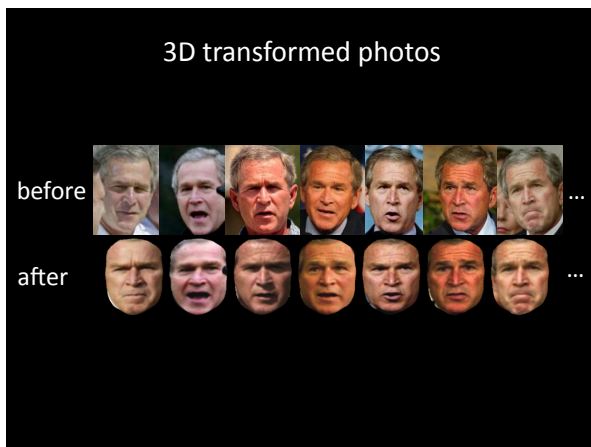
Search: **George Bush**
About 418,000,000 results (0.49 seconds)

Variation in faces captured in Internet photos



Search: **George Bush**
About 418,000,000 results (0.49 seconds)





Facial expression similarity

We use Local Binary Patterns – LBP (Ahonen et al. '06)

0 0 0
0 1 1
1 1 1

→ **01111000** = **30**
Binary code Integer

Facial expression similarity

Eyes Mouth Hair

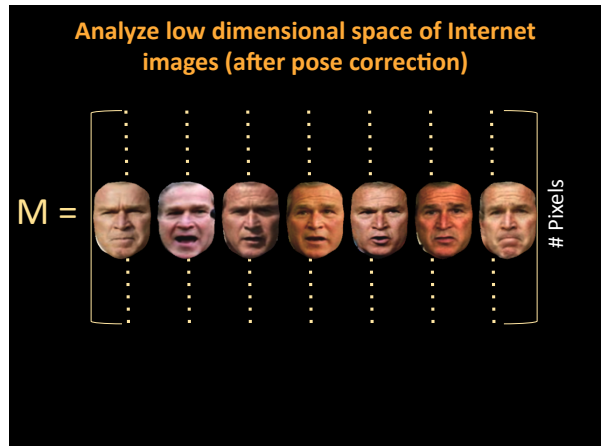
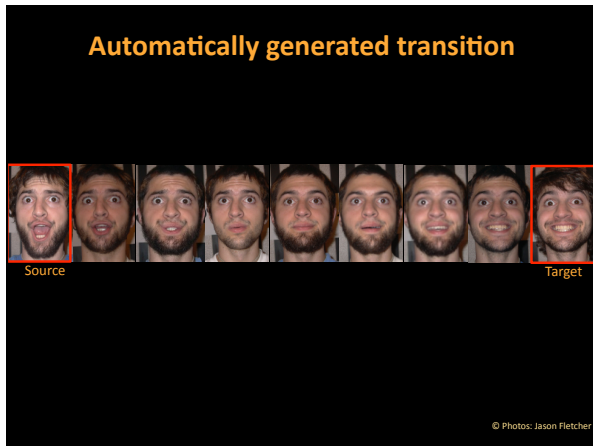
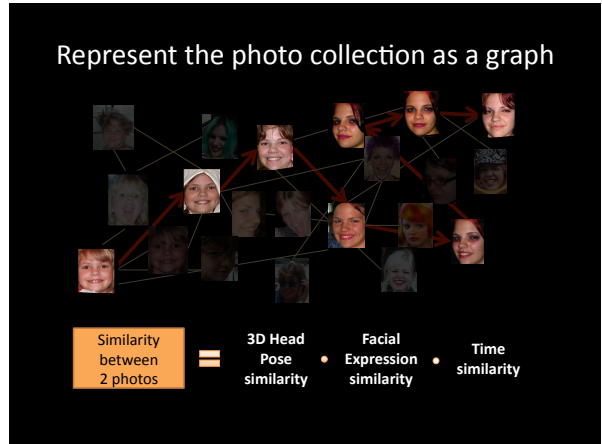
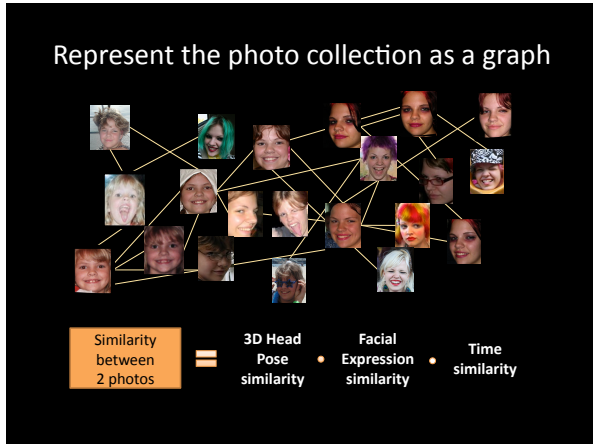
Facial expression similarity = λ_1 Eyes + λ_2 Mouth + λ_3 Hair

Facial expression similarity

Input	Nearest Neighbors
Eyes	
Mouth	
Hair	

Represent the photo collection as a graph

Similarity between 2 photos = 3D Head Pose similarity • Facial Expression similarity • Time similarity



Analyze low dimensional space of Internet images (after pose correction)

$M_4 =$ # Pixels

Expression gets normalized
Shading captured

Warped to frontal

Expression normalized Rank = 4

Why expression normalized by rank=4?

Lighting dominates facial expression

- 1) Rank 4 for rigid has >90% energy
Ramamoorthi & Hanrahan'01, Basri & Jacobs'01
- 2) Lighting affects all pixels (dense)
- 3) Expression (non-rigid) affects mostly edge pixels (sparse) & captured by rank=5,6,...

Kemelmacher and Seitz, Collection Flow, CVPR'12

This is actually a photometric stereo setup

$M_4 =$ # Pixels

rigid object, fixed pose, varying lighting

Photometric Stereo with Constrained Light

Factorization using SVD

$$I(x, y) = \rho(x, y) L^T N(x, y)$$

Ikeuchi, 81, Nayar, 90, Hayakawa JOSA'94, Barsky and Petro, 03, Hertzmann and Seitz, 05 Woodham, Optical Eng.'80, JOSA'94

Photometric Stereo with Arbitrary Light

Using spherical harmonics representation for shape (surface normals) and lighting

Basri, Jacobs and Kemelmacher, *Photometric Stereo with General Unknown Lighting*, IJCV'07

Photometric Stereo with Arbitrary Light

Solving for 4x4 ambiguity
Up to Lorenz transformation (6dof)

$$\sqrt{n_x^2 + n_y^2 + n_z^2} = 1$$

$$p^T J p = 0$$

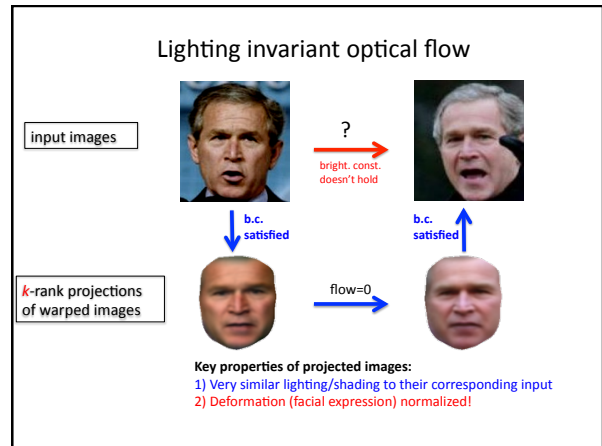
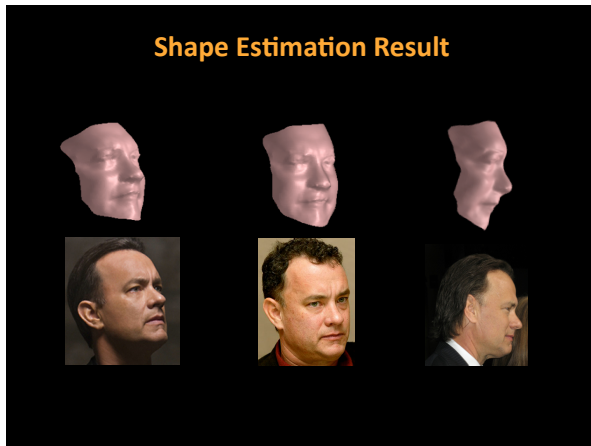
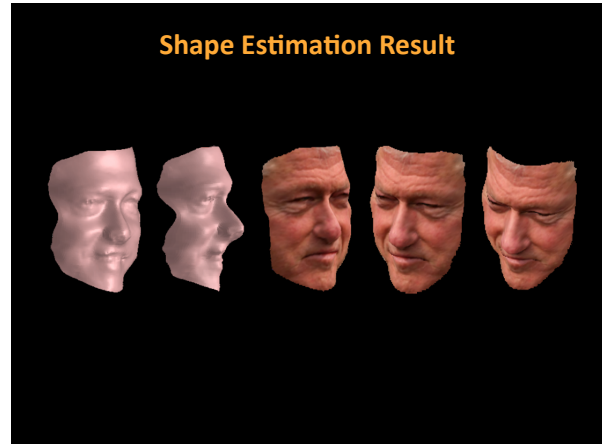
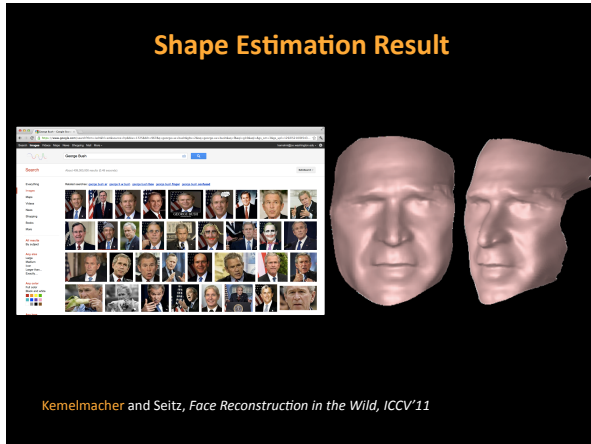
$$J = \text{diag}(-1, 1, 1, 1)$$

Basri, Jacobs and Kemelmacher, *Photometric Stereo with General Unknown Lighting*, IJCV'07

Photometric Stereo with Arbitrary Light

For faces use another person's face to solve the ambiguity

Kemelmacher and Seitz, *Face Reconstruction in the Wild*, ICCV'11



Result of flow estimation applied to morphing

Accounts for lighting
and shape changes



Challenging for state of the art

Note the *distortions*
due to violation of the
brightness constancy



C. Liu. PhD thesis, MIT, 2009
Brox et al. ECCV'04
Bruhn et al. IJCV'05

State of the art flow on unstructured photos

TV- L_1



Chambolle & Pock, J. Mathematical Imaging and Vision 2011

State of the art flow on unstructured photos


SIFT Flow



C. Liu, J. Yuen, and A. Torralba. Sift flow: Dense correspondence across scenes.. PAMI'11

Collection Flow (ours)


Accounts for lighting and shape changes



Kemelmacher and Seitz, *Collection Flow*, CVPR'12

Collection Flow

Automatically synthesized photos




TV-L


Brox et al. & Bruhn et al.

Result of flow estimation applied to morphing

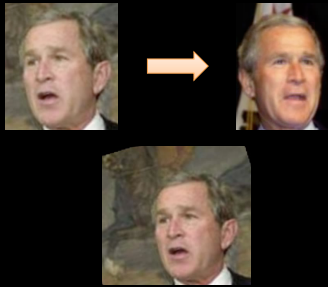
Accounts for lighting and shape changes



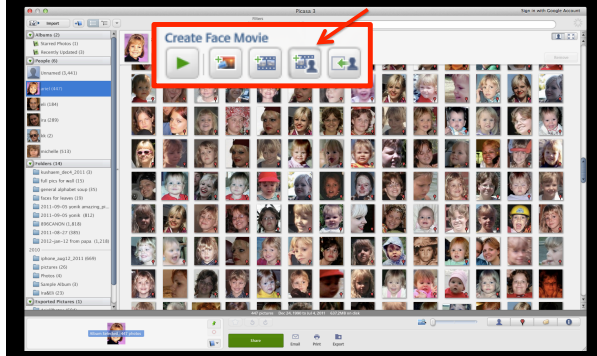
Automatically synthesized photos

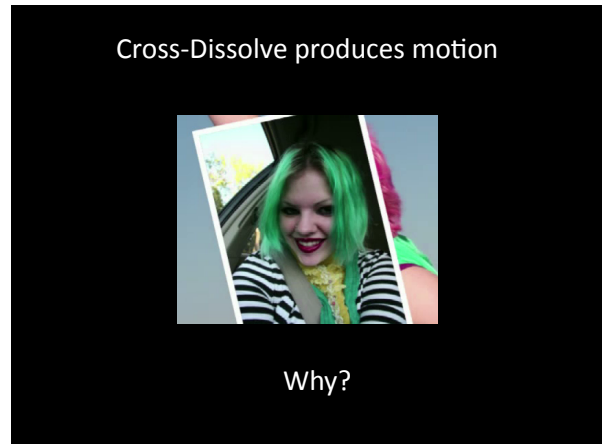
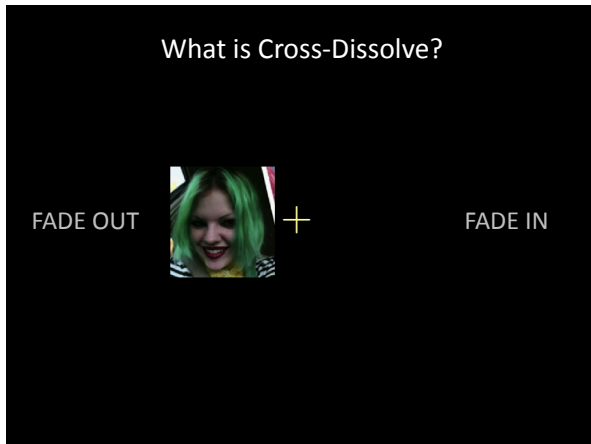
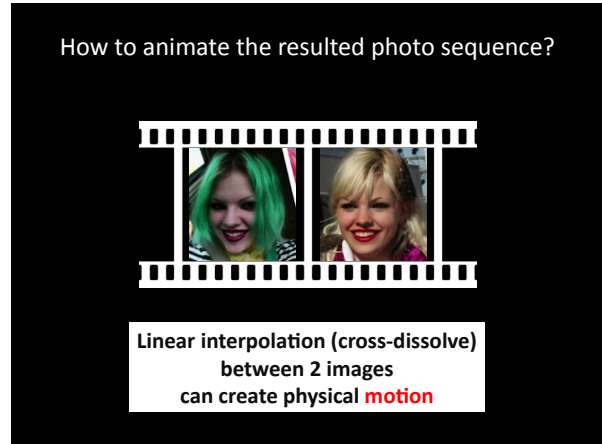
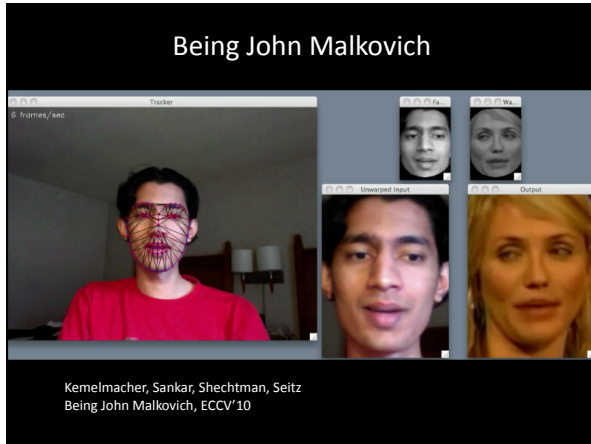


Animation from Internet photos

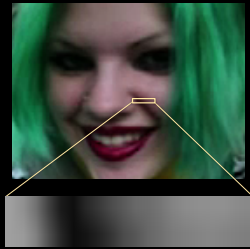


Face Movie feature in Google's Picasa

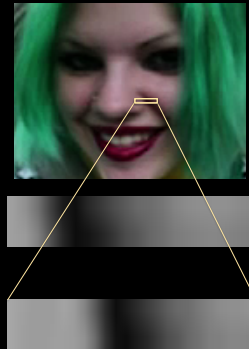




Lets represent an image as a collection of edges



Lets represent an image as a collection of edges



Can we move one edge to another?

Image 1

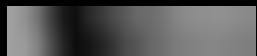


Image 2



Let's approximate with a sine

$\sin(mx)$



$\sin(mx+d)$



While doing cross-dissolve we see motion!

$\sin(mx)$

Cross dissolve

$\sin(mx+d)$

It is actually a physical motion!

$\sin(mx)$

Cross dissolve

$\sin(mx+d)$

$c \sin(mx+k)$

Motion effect with larger phase shift

$\sin(mx)$

Cross dissolve

$\sin(mx+d)$

$c \sin(mx+k)$

The motion is non linear

$$k = \arctan \frac{t \sin d}{(1-t) + t \cos d}$$

There is slow-in slow-out dynamics

Rule of Thumb in animation

Walt Disney Animation Principles, 1930
J. Lasseter, SIGGRAPH'87

Kemelmacher et al. SIGGRAPH'11

When motion is produced?

- Approximately same frequency edges
- The distance edges can move depends on the frequency

Cross-dissolve produces edge **rotation**

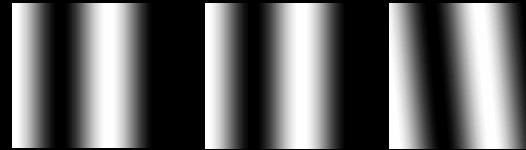


Image 1 Cross dissolve Image 2
= edge rotation (proof in the paper)

Cross-dissolve produces **light** motion

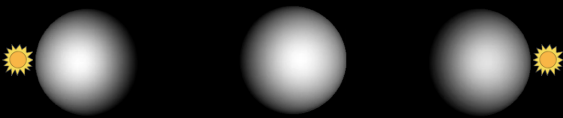


Image 1 Cross dissolve Image 2
= light motion (proof in the paper)