

# Face Detection

CSE 576

# Face detection



State-of-the-art face detection demo  
(Courtesy [Boris Babenko](#))

# Face detection and recognition



Detection



Recognition

"Sally"

# Face detection

- Where are the faces?

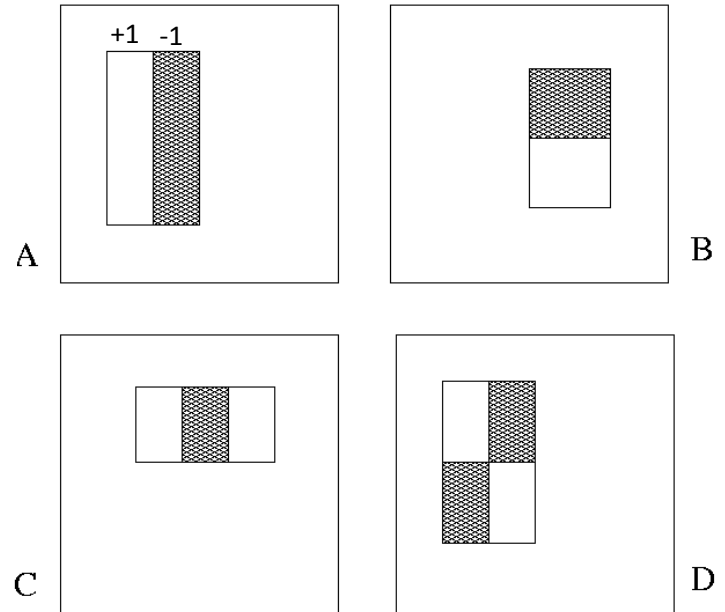


# Face Detection

- What kind of features?
- What kind of classifiers?

# Image Features

“Rectangle filters”

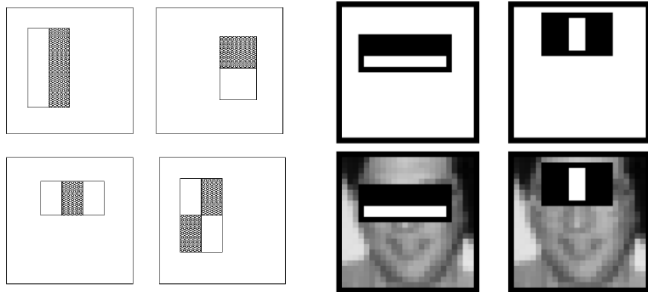


*Value* =

$$\sum (\text{pixels in white area}) - \sum (\text{pixels in black area})$$

# Feature extraction

## “Rectangular” filters



Feature output is difference between adjacent regions

Efficiently computable  
with integral image: any  
sum can be computed in  
constant time

Avoid scaling images  
scale features directly  
for same cost

# Sums of rectangular regions

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How do we compute the sum of the pixels in the red box?

After some pre-computation, this can be done in constant time for any box.

This “trick” is commonly used for computing Haar wavelets (a fundamental building block of many object recognition approaches.)

243	239	240	225	206	185	188	218	211	206	216	225
242	239	218	110	67	31	34	152	213	206	208	221
243	242	123	58	94	82	132	77	108	208	208	215
235	217	115	212	243	236	247	139	91	209	208	211
233	208	131	222	219	226	196	114	74	208	213	214
232	217	131	116	77	150	69	56	52	201	228	223
232	232	182	186	184	179	159	123	93	232	235	235
232	236	201	154	216	133	129	81	175	252	241	240
235	238	230	128	172	138	65	63	234	249	241	245
237	236	247	143	59	78	10	94	255	248	247	251
234	237	245	193	55	33	115	144	213	255	253	251
248	245	161	128	149	109	138	65	47	156	239	255
190	107	39	102	94	73	114	58	17	7	51	137
23	32	33	148	168	203	179	43	27	17	12	8
17	26	12	160	255	255	109	22	26	19	35	24



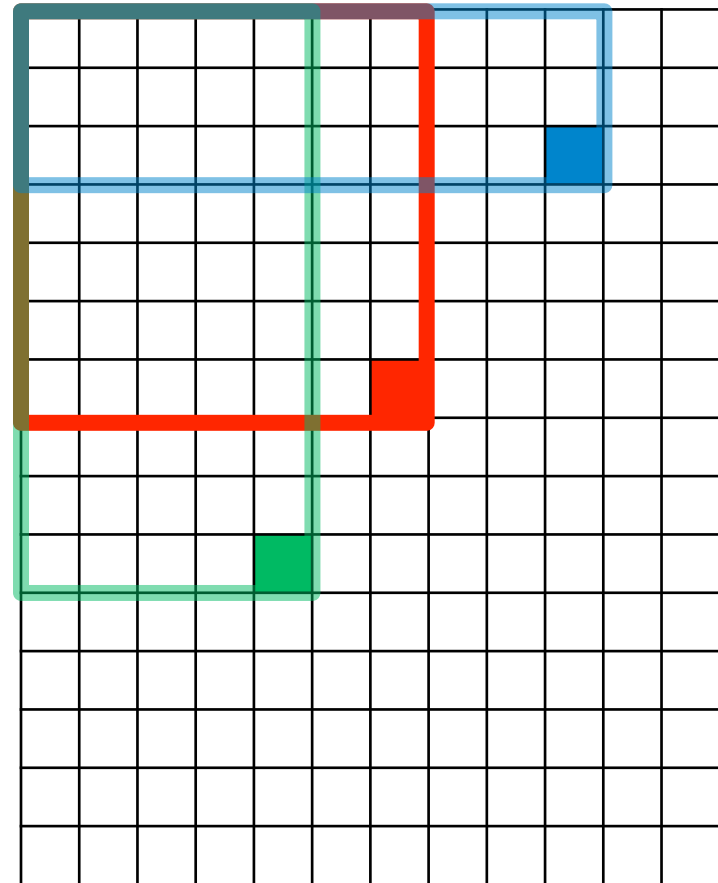
# Sums of rectangular regions

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The trick is to compute an “integral image.” Every pixel is the sum of its neighbors to the upper left.

Sequentially compute using:

$$I(x, y) = I(x, y) + \\ I(x - 1, y) + I(x, y - 1) - \\ I(x - 1, y - 1)$$



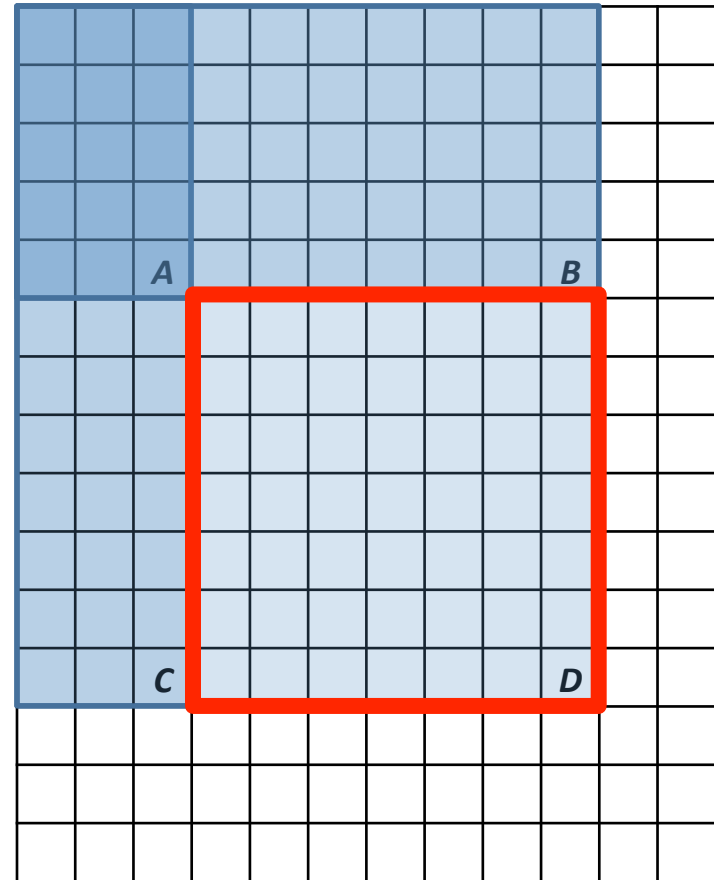
# Sums of rectangular regions

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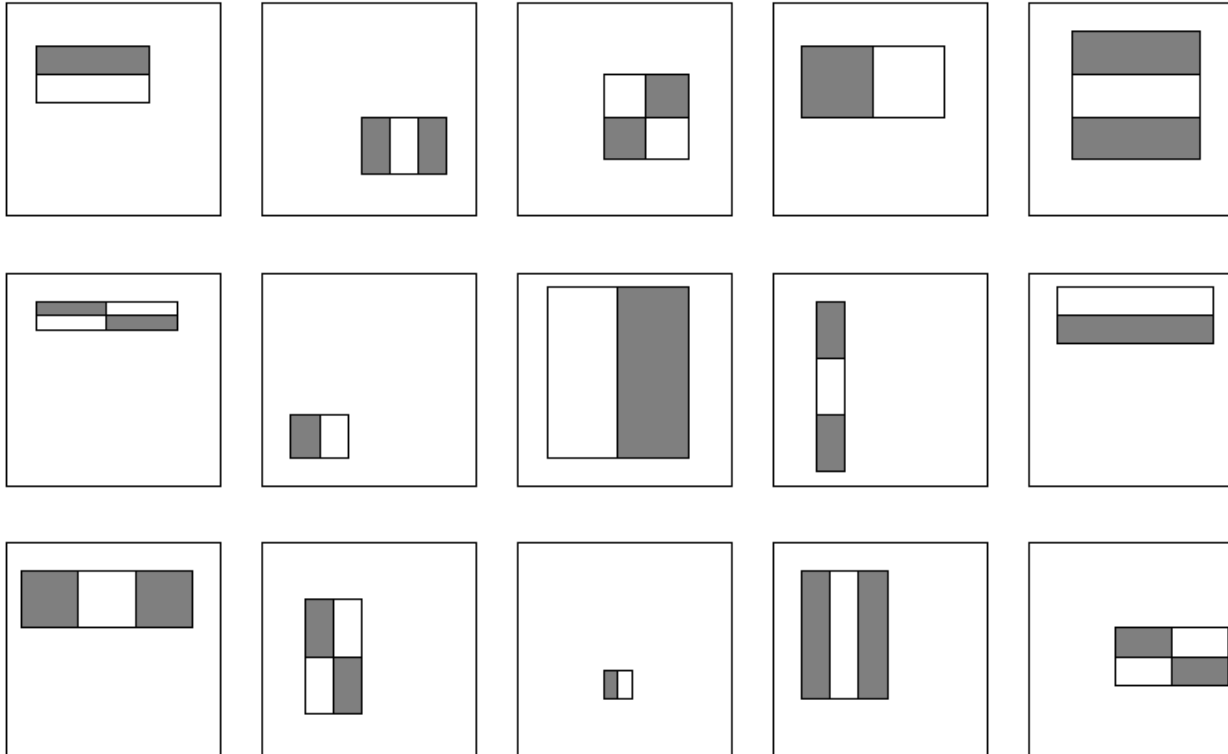
Solution is found using:

$$A + D - B - C$$

What if the position of the box lies  
between pixels?



# Large library of filters



Considering all possible filter parameters:  
position, scale, and type:  
180,000+ possible features associated with each 24 x 24 window

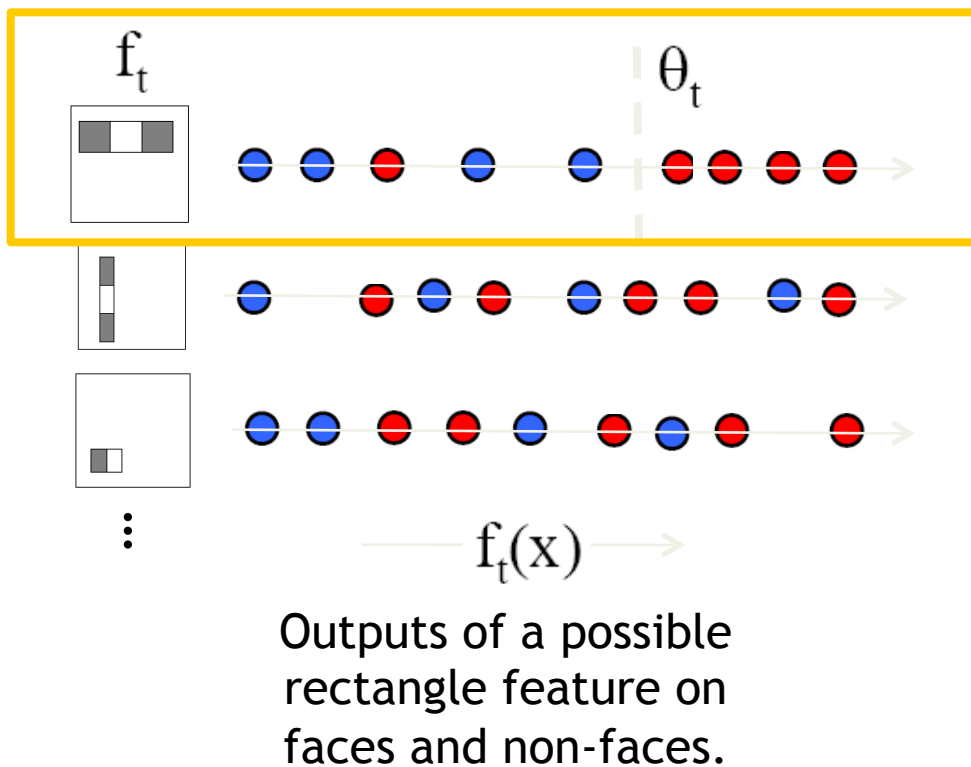
Use AdaBoost both to select the informative features and to form the classifier

# Feature selection

- For a 24x24 detection region, the number of possible rectangle features is ~180,000!
- At test time, it is impractical to evaluate the entire feature set
- Can we create a good classifier using just a small subset of all possible features?
- How to select such a subset?

# AdaBoost for feature+classifier selection

- Want to select the single rectangle feature and a corresponding threshold that best separates **positive** (faces) and **negative** (non-faces) training examples, in terms of *weighted* error.

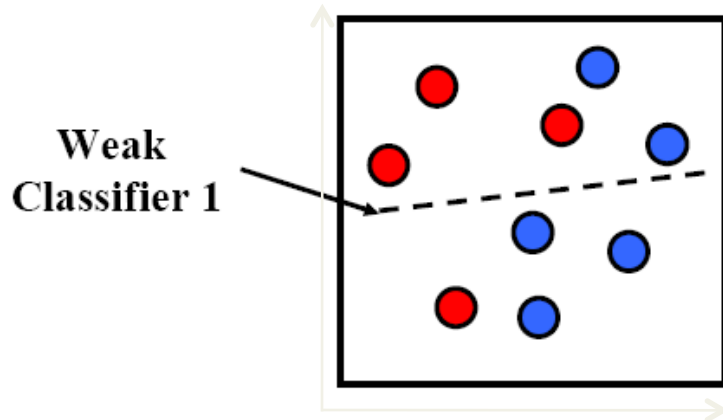


Resulting weak classifier:

$$h_t(x) = \begin{cases} +1 & \text{if } f_t(x) > \theta_t \\ -1 & \text{otherwise} \end{cases}$$

For next round, reweight the examples according to errors, choose another filter/threshold combo.

# AdaBoost: Intuition

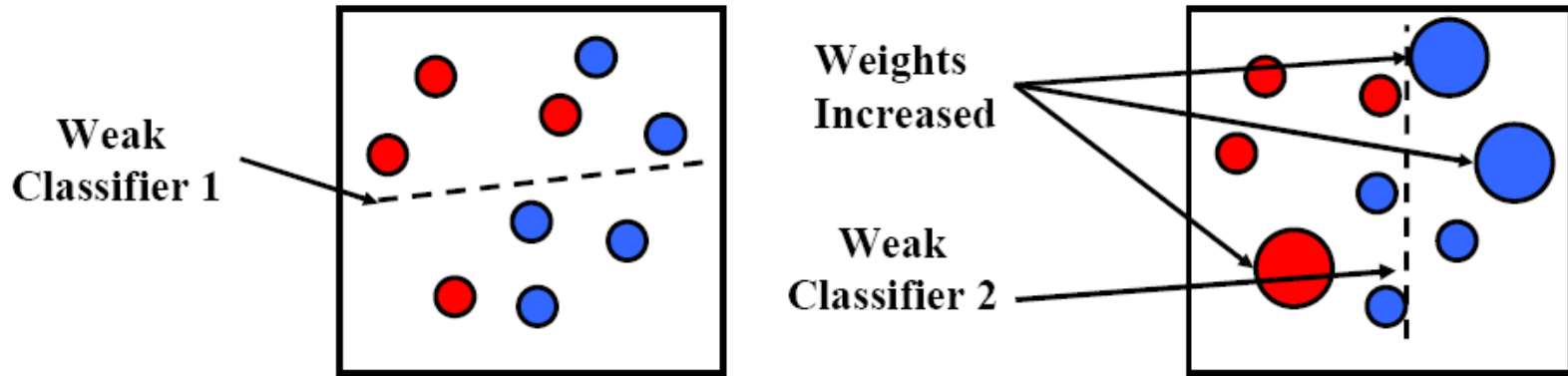


Consider a 2-d feature space with **positive** and **negative** examples.

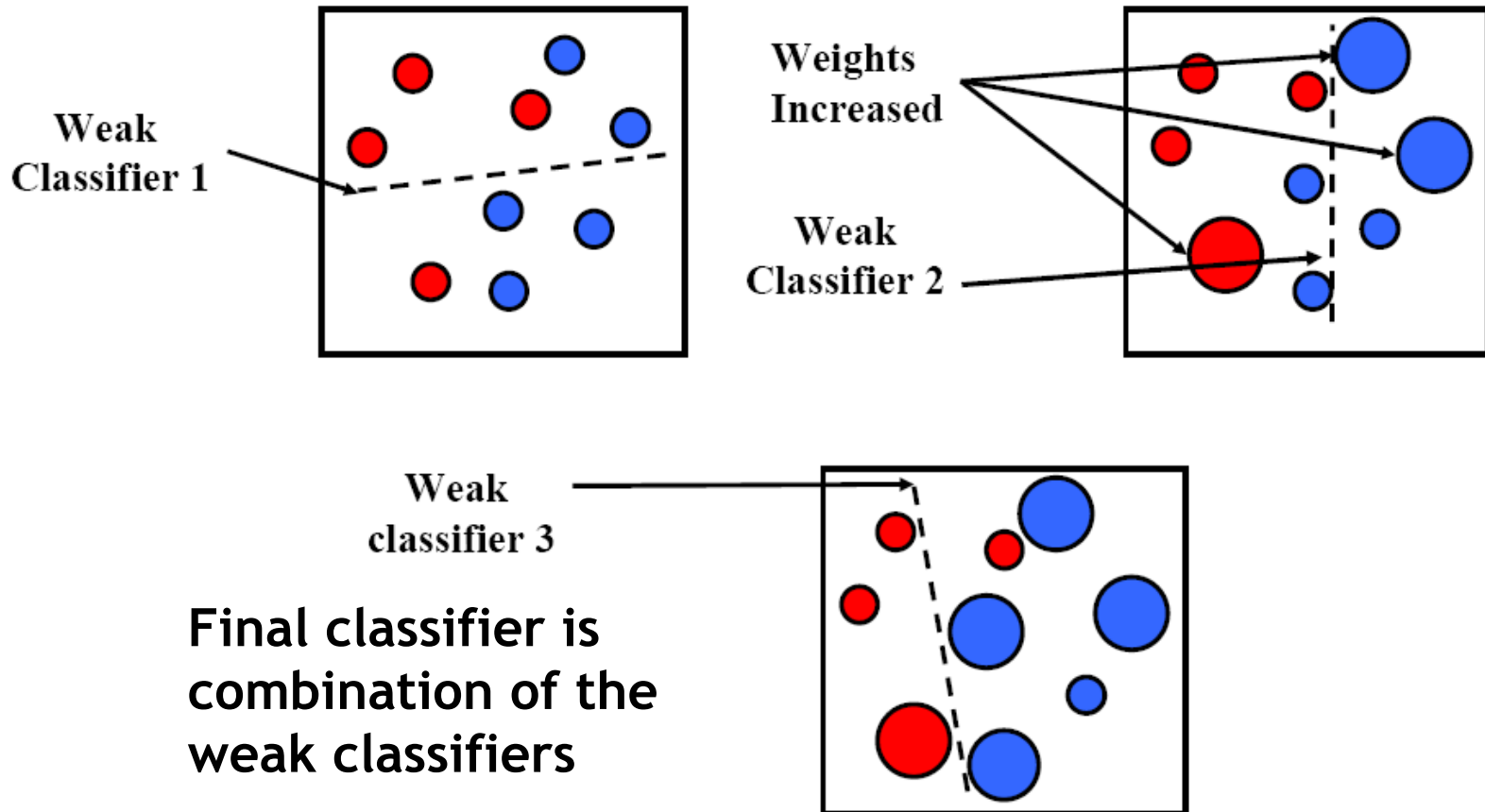
Each weak classifier splits the training examples with at least 50% accuracy.

Examples misclassified by a previous weak learner are given more emphasis at future rounds.

# AdaBoost: Intuition



# AdaBoost: Intuition





- The final strong classifier is:

$$h(x) = \begin{cases} 1 & \sum_{t=1}^T \alpha_t h_t(x) \geq \frac{1}{2} \sum_{t=1}^T \alpha_t \\ 0 & \text{otherwise} \end{cases}$$

where  $\alpha_t = \log \frac{1}{\beta_t}$

Final classifier is combination of the weak ones, weighted according to error they had.

# AdaBoost Algorithm

- Given example images  $(x_1, y_1), \dots, (x_n, y_n)$  where  $y_i = 0, 1$  for negative and positive examples respectively.
- Initialize weights  $w_{1,i} = \frac{1}{2m}, \frac{1}{2l}$  for  $y_i = 0, 1$  respectively, where  $m$  and  $l$  are the number of negatives and positives respectively.
- For  $t = 1, \dots, T$ :

1. Normalize the weights,

$$w_{t,i} \leftarrow \frac{w_{t,i}}{\sum_{j=1}^n w_{t,j}}$$

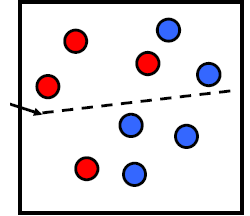
so that  $w_t$  is a probability distribution.

2. For each feature,  $j$ , train a classifier  $h_j$  which is restricted to using a single feature. The error is evaluated with respect to  $w_t$ ,  $\epsilon_j = \sum_i w_i |h_j(x_i) - y_i|$ .
3. Choose the classifier,  $h_t$ , with the lowest error  $\epsilon_t$ .
4. Update the weights:

$$w_{t+1,i} = w_{t,i} \beta_t^{1-e_i}$$

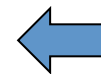
where  $e_i = 0$  if example  $x_i$  is classified correctly,  $e_i = 1$  otherwise, and  $\beta_t = \frac{\epsilon_t}{1-\epsilon_t}$ .

Start with uniform weights on training examples

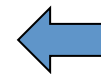


$\{x_1, \dots, x_n\}$

For T rounds



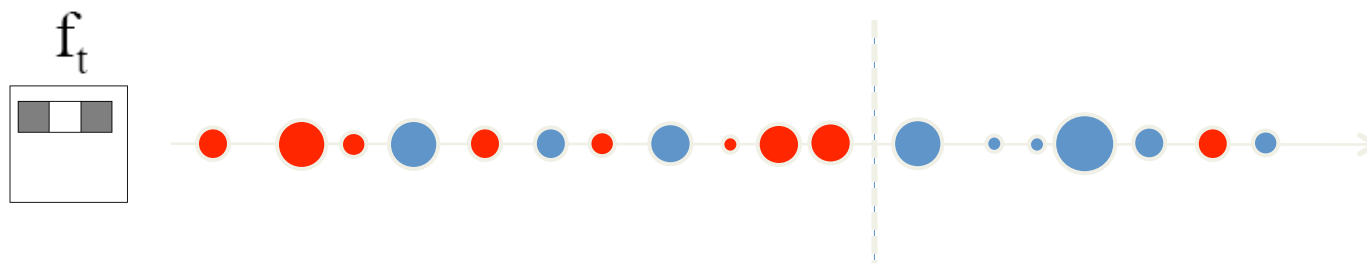
Find the best threshold and polarity for each feature, and return error.



Re-weight the examples:  
Incorrectly classified -> more weight  
Correctly classified -> less weight

# Picking the best classifier

Efficient single pass approach:



At each sample compute:

$$e = \min ( S + (T - S), S + (T - S) )$$

Find the minimum value of  $e$ , and use the value of the corresponding sample as the threshold.

$S$  = sum of samples below the current sample

$T$  = total sum of all samples

# Measuring classification performance

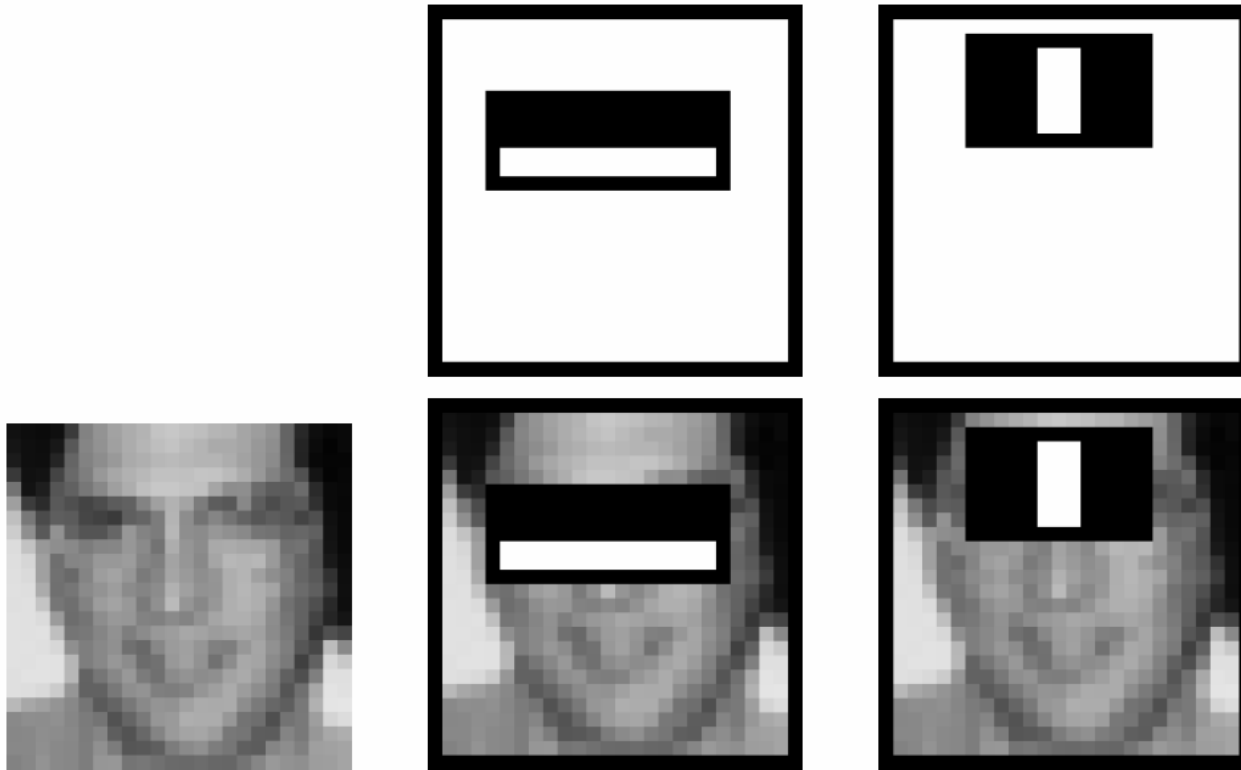
- Confusion matrix
- Accuracy
  - $(TP+TN)/(TP+TN+FP+FN)$
- True Positive Rate=Recall
  - $TP/(TP+FN)$
- False Positive Rate
  - $FP/(FP+TN)$
- Precision
  - $TP/(TP+FP)$
- F1 Score
  - $2*Recall*Precision/(Recall+Precision)$

		Predicted class		
		Class1	Class2	Class3
Actual class	Class1	40	1	6
	Class2	3	25	7
	Class3	4	9	10

		Predicted	
		Positive	Negative
Actual	Positive	True Positive	False Negative
	Negative	False Positive	True Negative

# Boosting for face detection

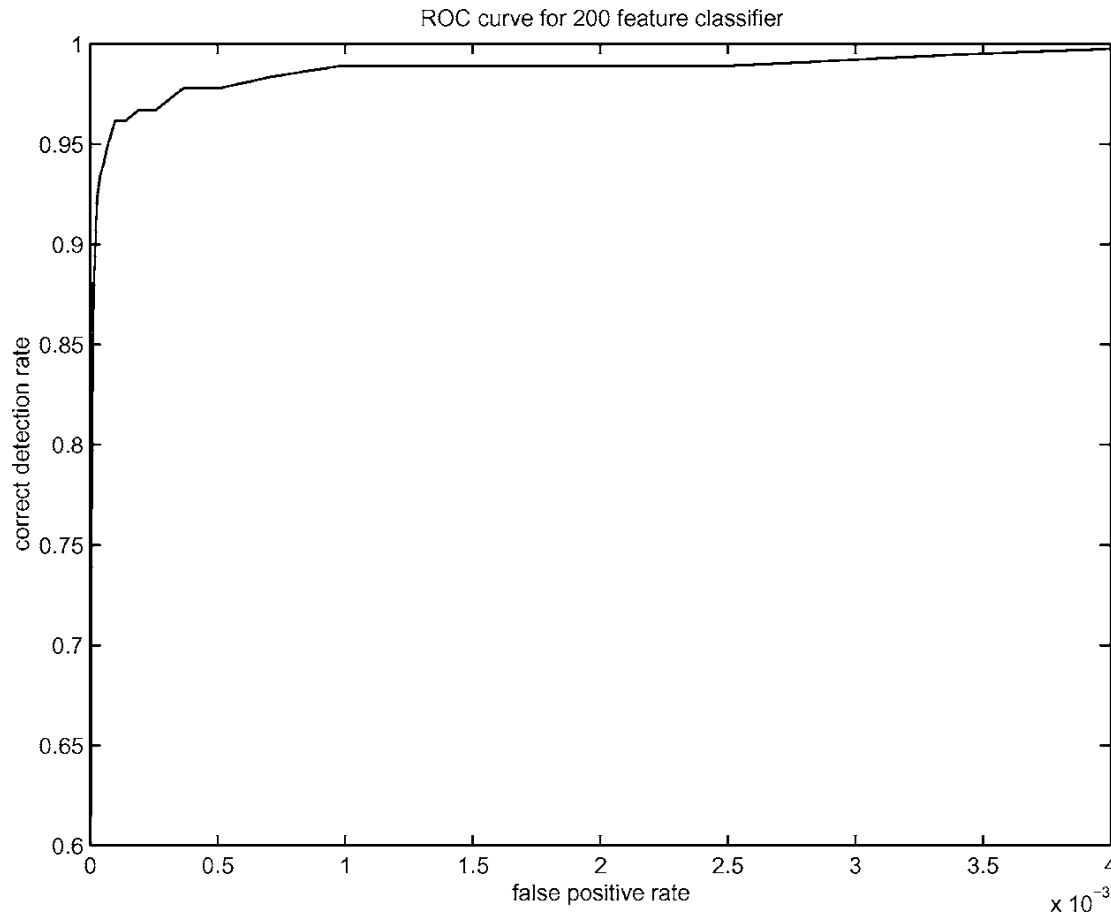
- First two features selected by boosting:



This feature combination can yield 100% detection rate and 50% false positive rate

# Boosting for face detection

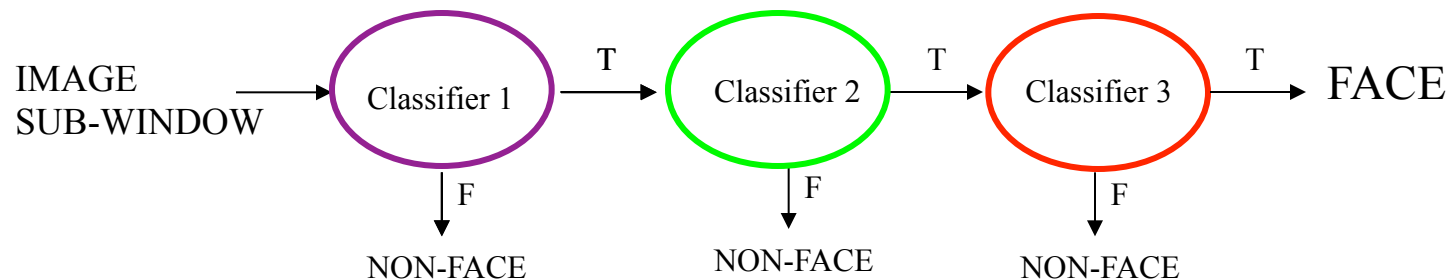
- A 200-feature classifier can yield 95% detection rate and a false positive rate of 1 in 14084



Receiver operating characteristic (ROC) curve

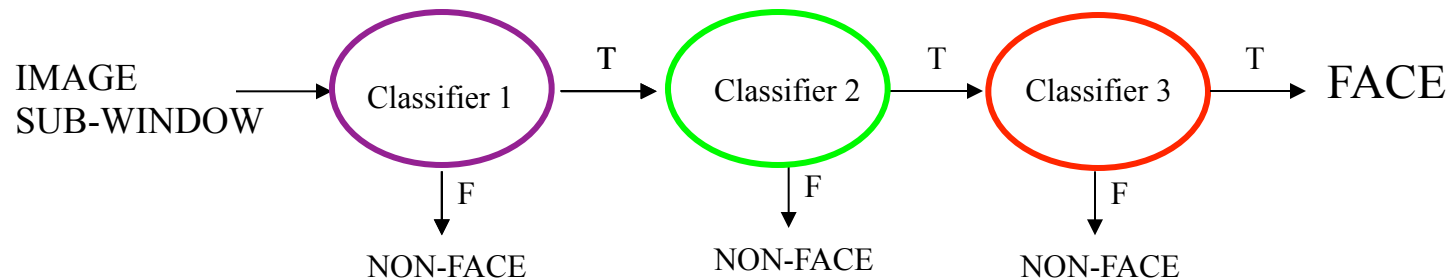
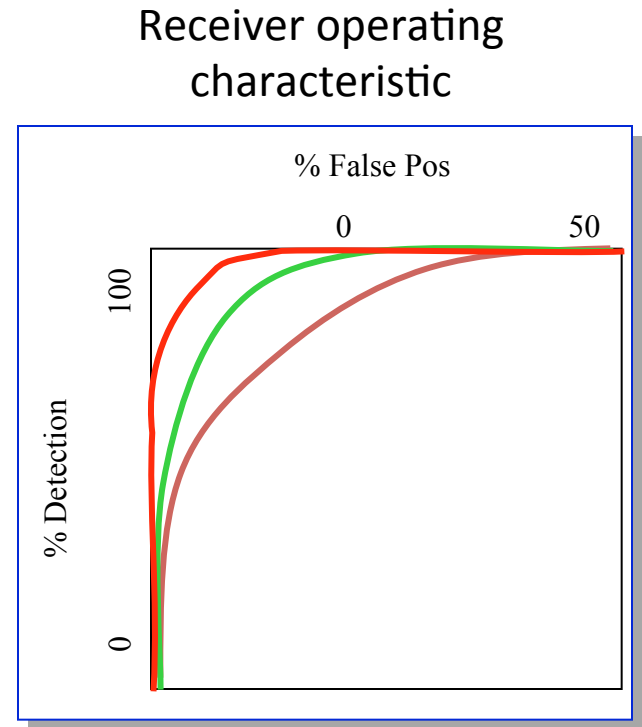
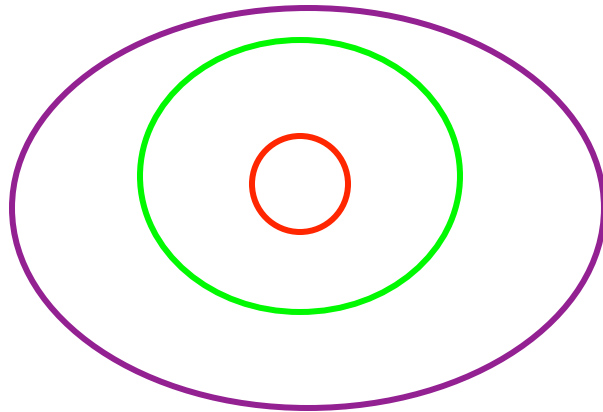
# Attentional cascade

- We start with simple classifiers which reject many of the negative sub-windows while detecting almost all positive sub-windows
- Positive response from the first classifier triggers the evaluation of a second (more complex) classifier, and so on
- A negative outcome at any point leads to the immediate rejection of the sub-window



# Attentional cascade

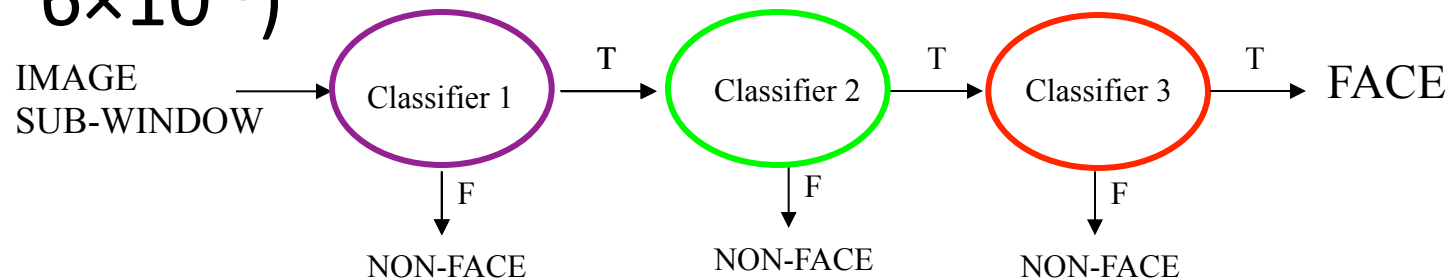
- Chain classifiers that are progressively more complex and have lower false positive rates:





# Attentional cascade

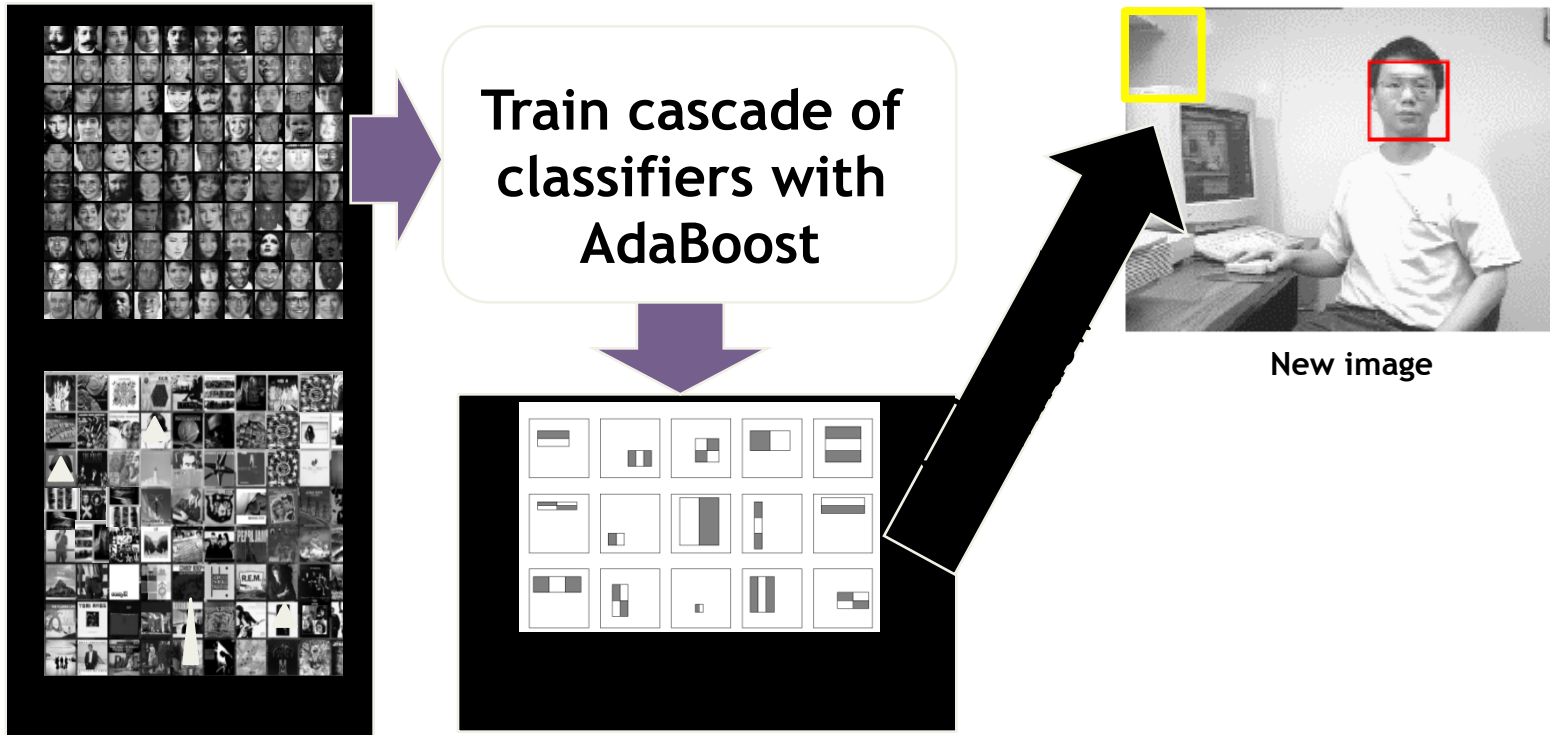
- The detection rate and the false positive rate of the cascade are found by multiplying the respective rates of the individual stages
- A detection rate of 0.9 and a false positive rate on the order of  $10^{-6}$  can be achieved by a 10-stage cascade if each stage has a detection rate of 0.99 ( $0.99^{10} \approx 0.9$ ) and a false positive rate of about 0.30 ( $0.3^{10} \approx 6 \times 10^{-6}$ )



# Training the cascade

- Set target detection and false positive rates for each stage
- Keep adding features to the current stage until its target rates have been met
  - Need to lower AdaBoost threshold to maximize detection  
(as opposed to minimizing total classification error)
  - Test on a *validation set*
- If the overall false positive rate is not low enough, then add another stage
- Use false positives from current stage as the negative training examples for the next stage

# Viola-Jones Face Detector: Summary



- Train with 5K positives, 350M negatives
- Real-time detector using 38 layer cascade
- 6061 features in final layer
- [Implementation available in OpenCV: <http://www.intel.com/technology/computing/opencv/>]

# The implemented system

- Training Data
  - 5000 faces
    - All frontal, rescaled to 24x24 pixels
  - 300 million non-faces
    - 9500 non-face images
  - Faces are normalized
    - Scale, translation
- Many variations
  - Across individuals
  - Illumination
  - Pose



# System performance

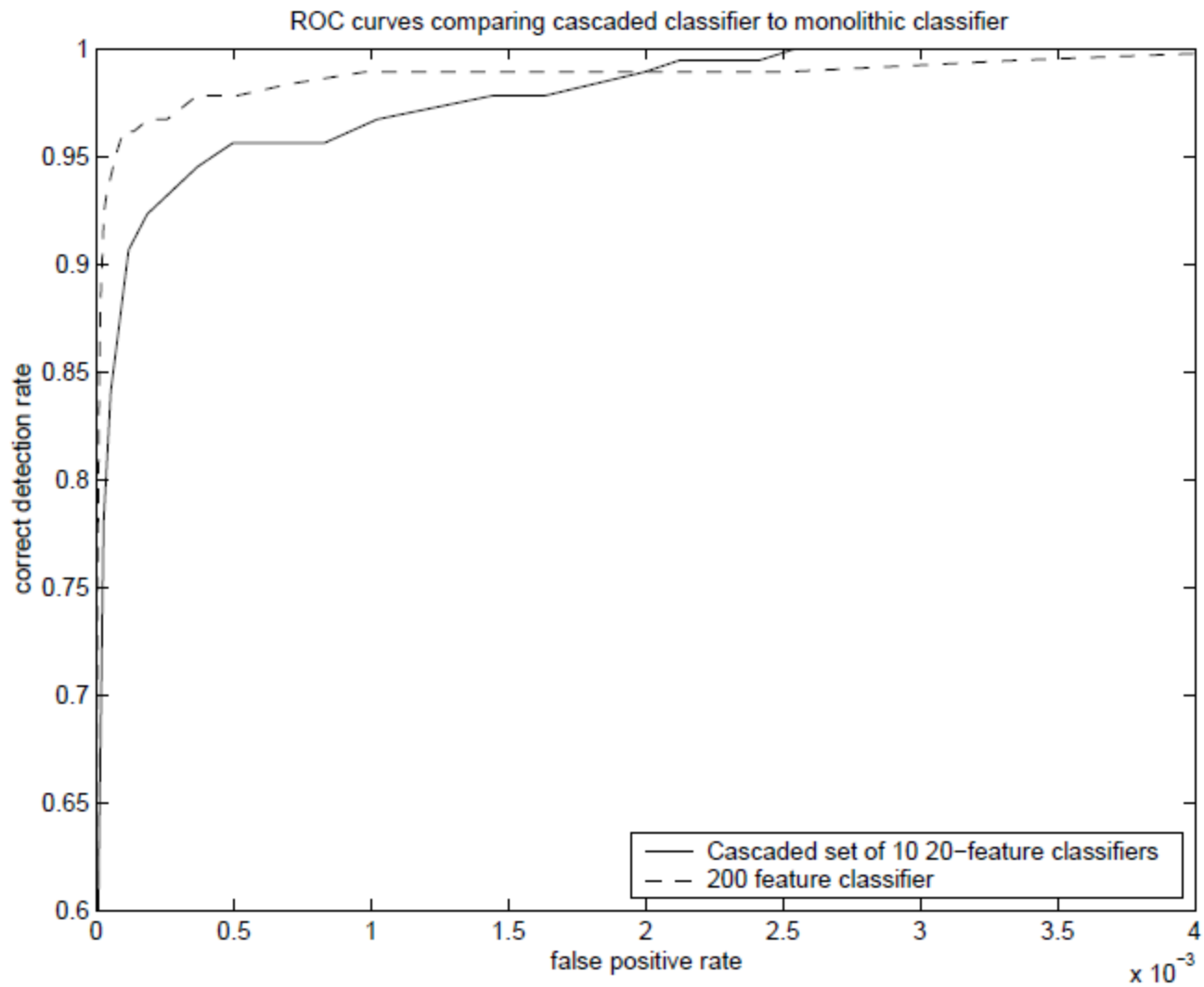
- Training time: “weeks” on 466 MHz Sun workstation
- 38 layers, total of 6061 features
- Average of 10 features evaluated per window on test set
- “On a 700 Mhz Pentium III processor, the face detector can process a 384 by 288 pixel image in about .067 seconds”
  - 15 Hz
  - 15 times faster than previous detector of comparable accuracy (Rowley et al., 1998)



Many detections above threshold.

# Non-maximal suppression (NMS)

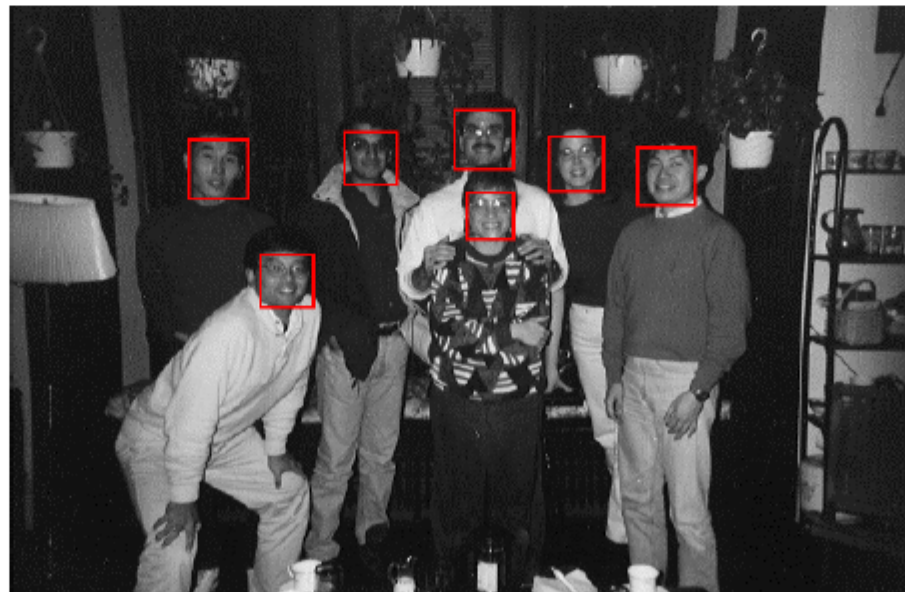
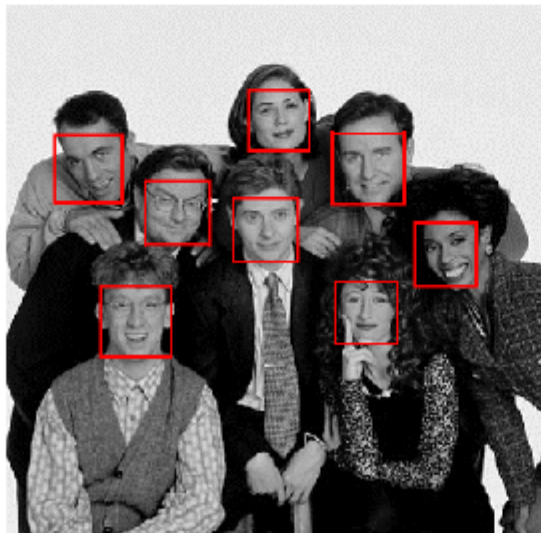
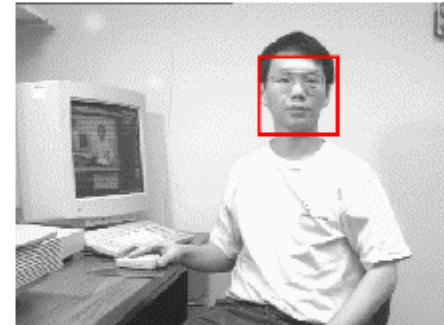
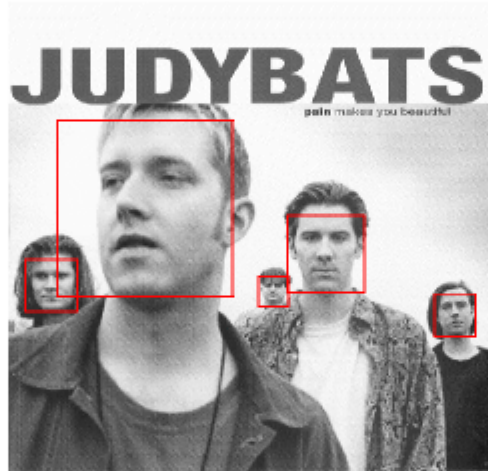




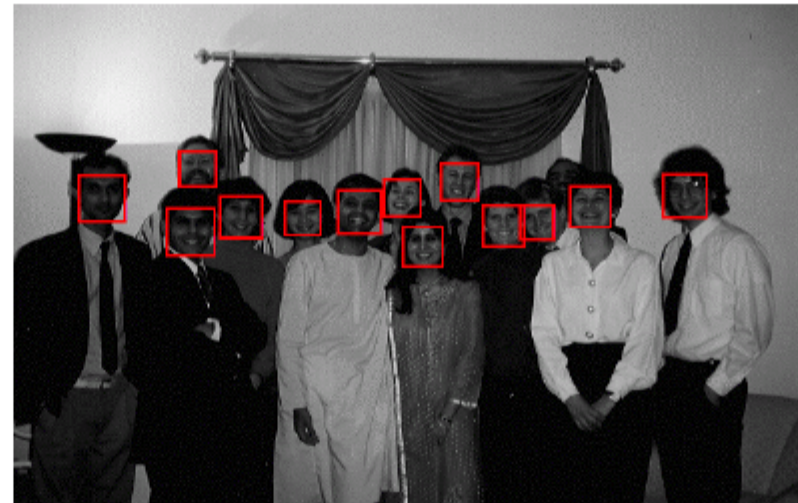
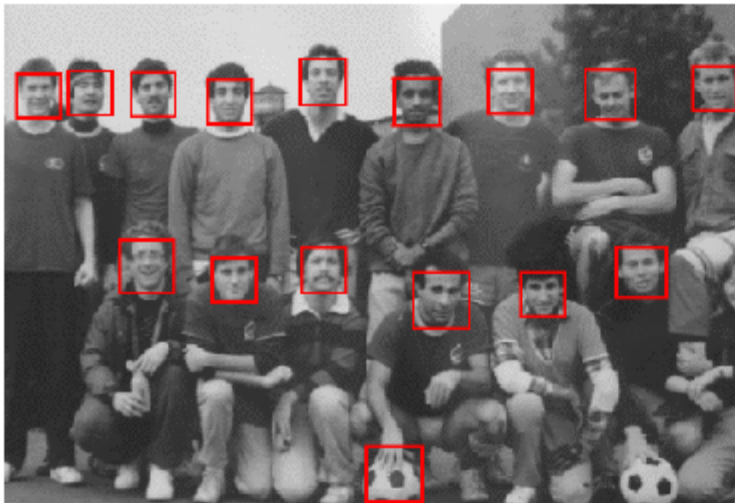
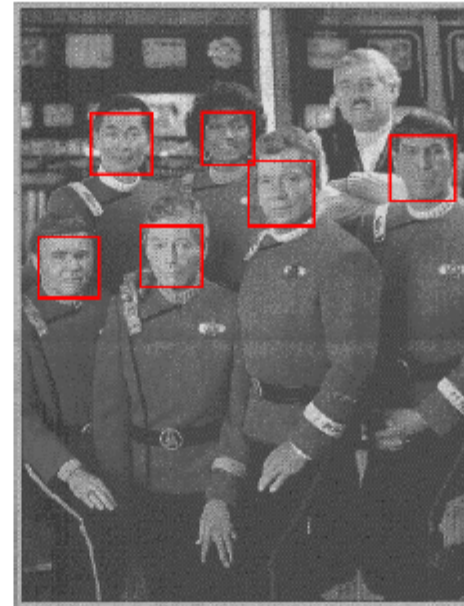
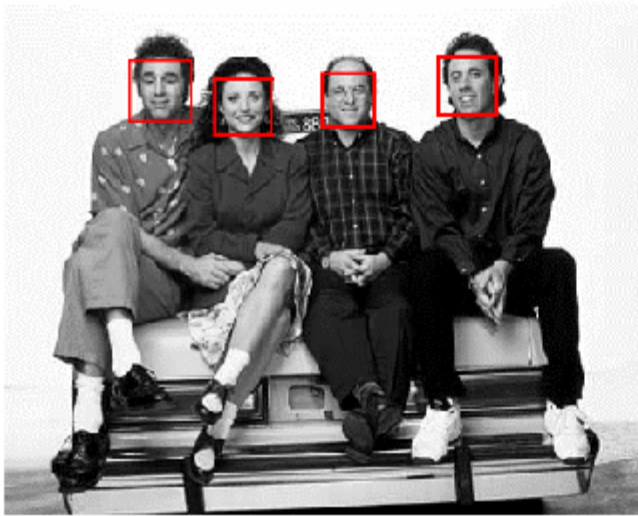
Similar accuracy, but 10x faster



# Viola-Jones Face Detector: Results



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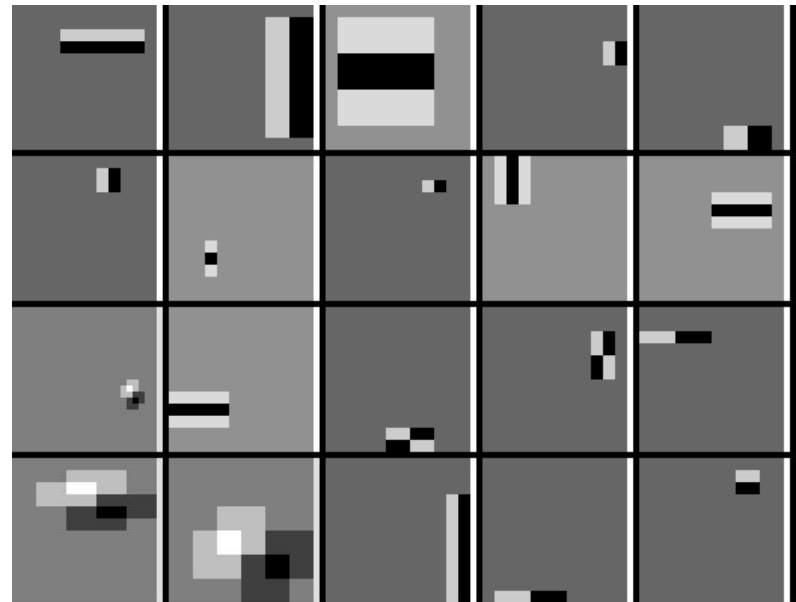


# Viola-Jones Face Detector: Results

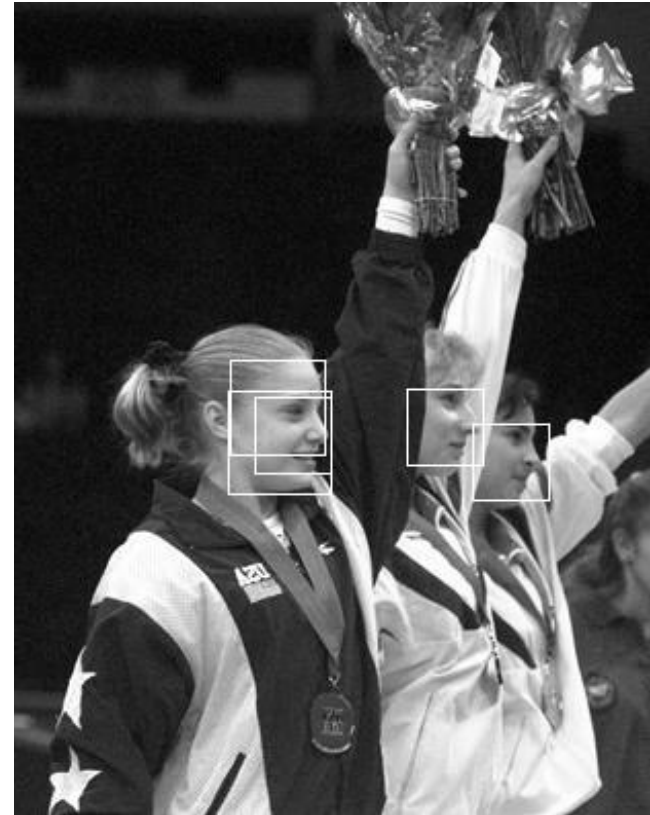


# Detecting profile faces?

Detecting profile faces requires training separate detector with profile examples.



# Viola-Jones Face Detector: Results



# Summary: Viola/Jones detector

- Rectangle features
- Integral images for fast computation
- Boosting for feature selection
- Attentional cascade for fast rejection of negative windows

# Recall

- Classification
  - NN
  - Naïve Bayes
  - Logistic Regression
  - Boosting

- Face Detection
  - Simple Features
  - Integral Images
  - Boosting

