Computer Vision

CSE 576 Ali Farhadi

Course Information

- Time:
 - Monday, Wednesday 1:30-2:50
- Location:
 - MGH 238
- Contact:
 - ali@cs.uw.edu , CSE 652
- TA:
 - Hessam Bagherinezhad (hessam@cs.uw.edu)
 - Yuguang Lee (ylee3@uw.edu)
- Website:
 - http://courses.cs.washington.edu/cse576

One Look Is Worth A Thousand Words--

One look at our line of Republic, Firestone, Miller and United States tires can tell you more than a hundred personal letters or advertisements.

WE WILL PROVE THEIR VALUE BEFORE YOU INVEST ONE DOLLAR IN THEM.

Ever consider buying Supplies from a catalog?

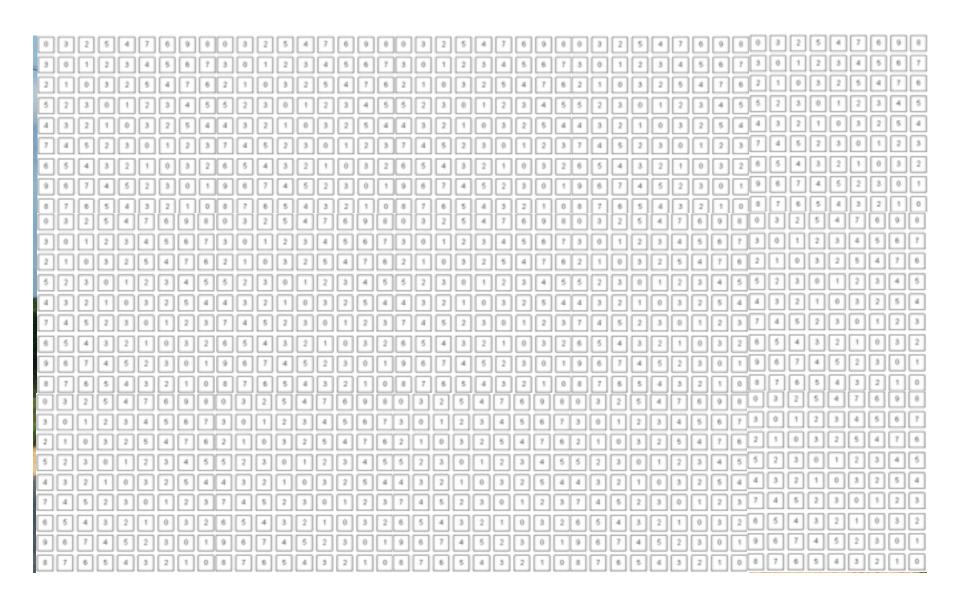
What's the use! Call and see what you are buying. One look at our display of automobile and motorcycle accessories will convince you of the fact.

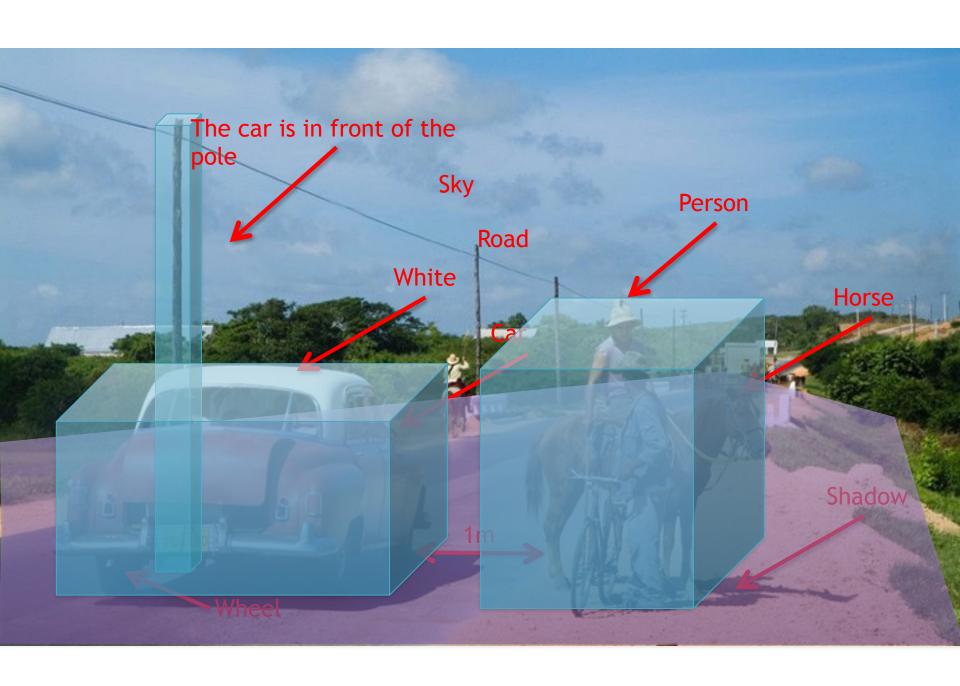
THAT WE HAVE EVERYTHING FOR THE AUTO

Piqua Auto Supply House

133 N. Main St.-Piqua, O.

What does it mean to see?





Computer Vision

Low Level Vision

- Measurements
- Enhancements
- Region segmentation
- Features

Mid Level Vision

- Reconstruction
- Depth
- Motion Estimation

High Level Vision

- Category detection
- Activity recognition
- Deep understandings



Computer Vision

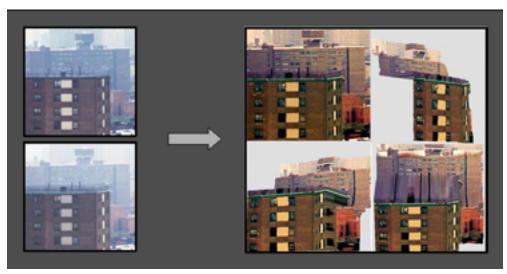
- Low Level Vision
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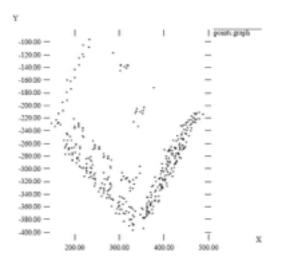
Vision as Measurement Device



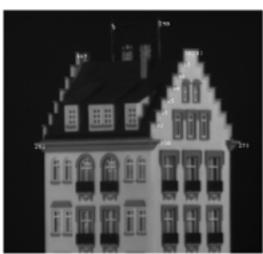
Real-time stereo on Mars



Physics-based Vision



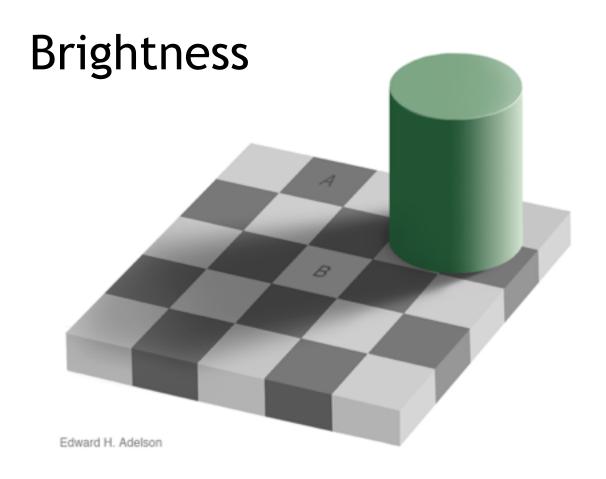
Structure from Motion



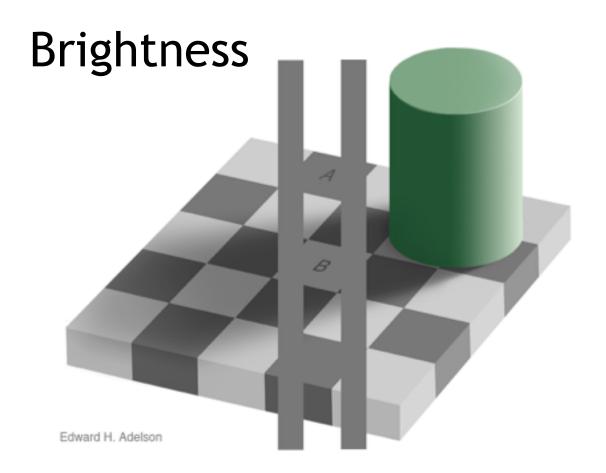


Virtualized Reality
Slide Credit: Alyosha

Measurement

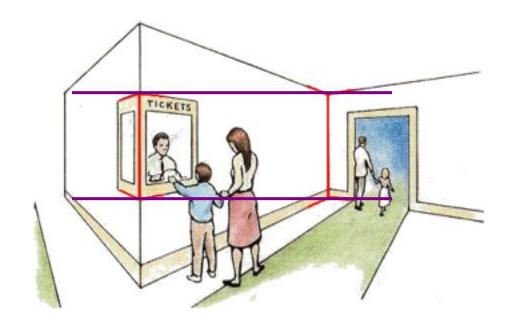


Measurement



Measurement

Length



Müller-Lyer Illusion

Image Enhancement

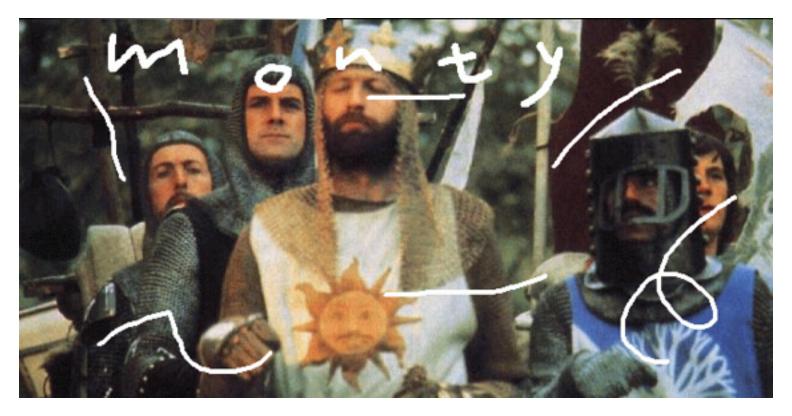


Image Inpainting, M. Bertalmío et al. http://www.iua.upf.es/~mbertalmio//restoration.html

Image Enhancement

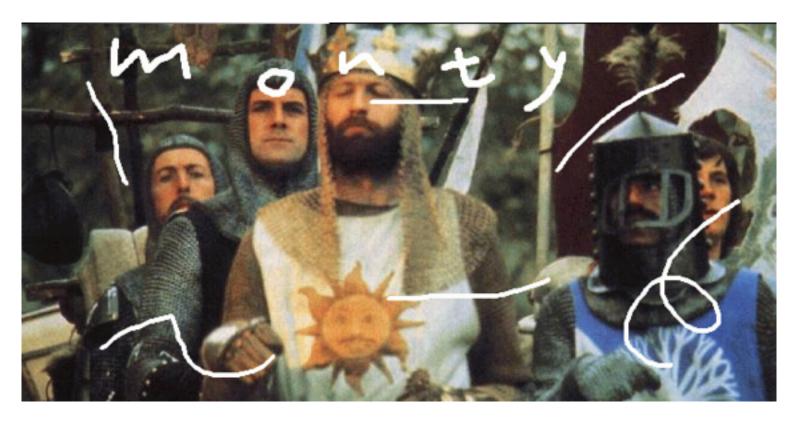


Image Inpainting, M. Bertalmío et al. http://www.iua.upf.es/~mbertalmio//restoration.html

Image Enhancement



Image Inpainting, M. Bertalmío et al. http://www.iua.upf.es/~mbertalmio//restoration.html

Seam Carving





Traditional resizing



Content-aware resizing

[Shai & Avidan, SIGGRAPH 2007]



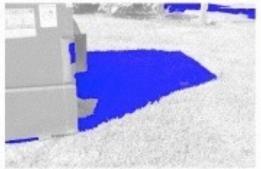








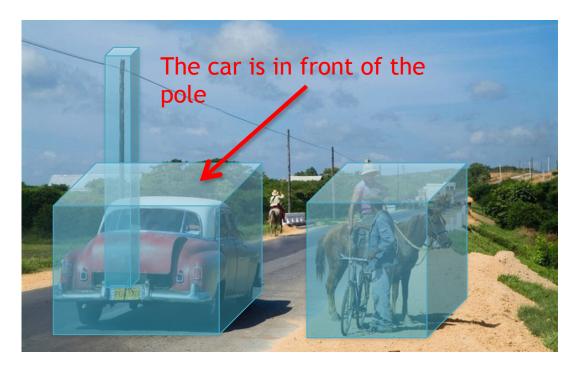






Computer Vision

- Low Level Vision
 - Measurements
 - Enhancements
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 - Features
- Mid Level Vision
 - Reconstruction
 - Depth
 - Motion Estimation
- High Level Vision
 - Category detection
 - Activity recognition
 - Deep understandings





Input Image (1 of 45)



Reconstruction



Reconstruction



Reconstruction

Source: S. Seitz



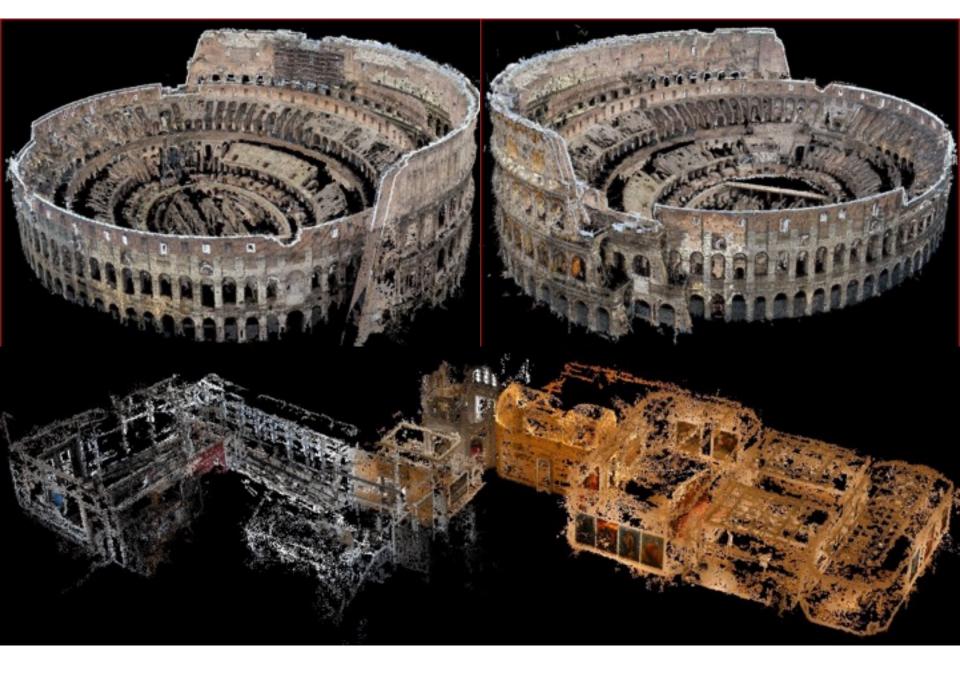
Input Image (1 of 100)



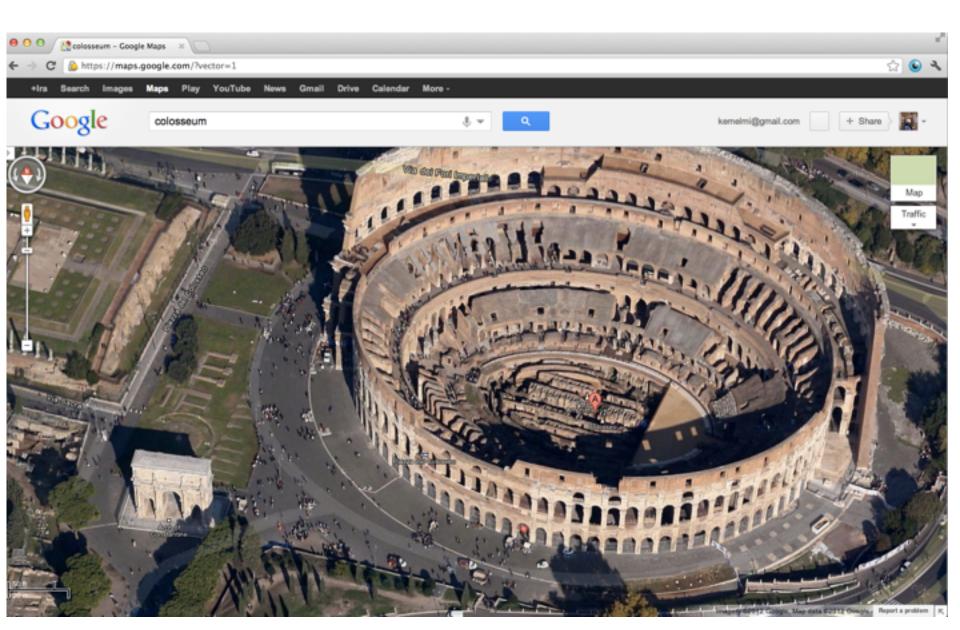
Views of Reconstruction



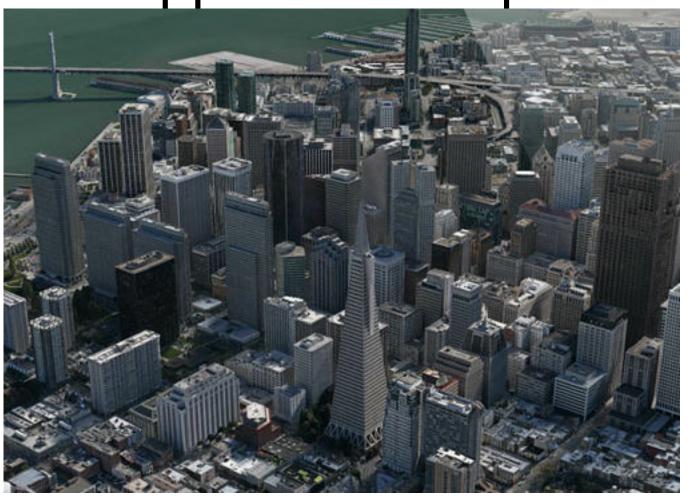
Yasutaka Furukawa and Jean Ponce, <u>Carved Visual Hulls for Image-Based Modeling</u>, ECCV 2006.



Google's 3D Maps Structure estimation from tourist photos

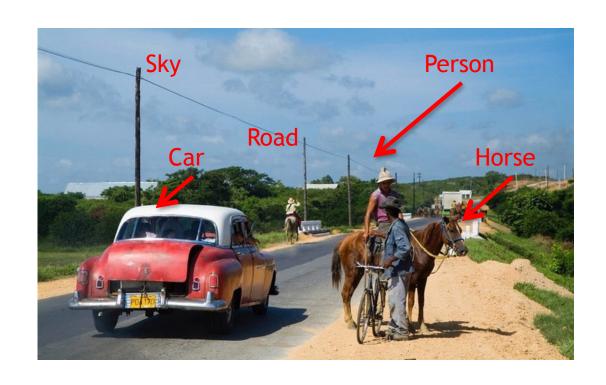


Apple's 3D maps



Computer Vision

- Low Level Vision
 - Measurements
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- Features
- Mid Level Vision
 - Reconstruction
 - Depth
 - Motion Estimation
- High Level Vision
 - Category detection
 - Activity recognition
 - Deep understandings
 - Pose estimation

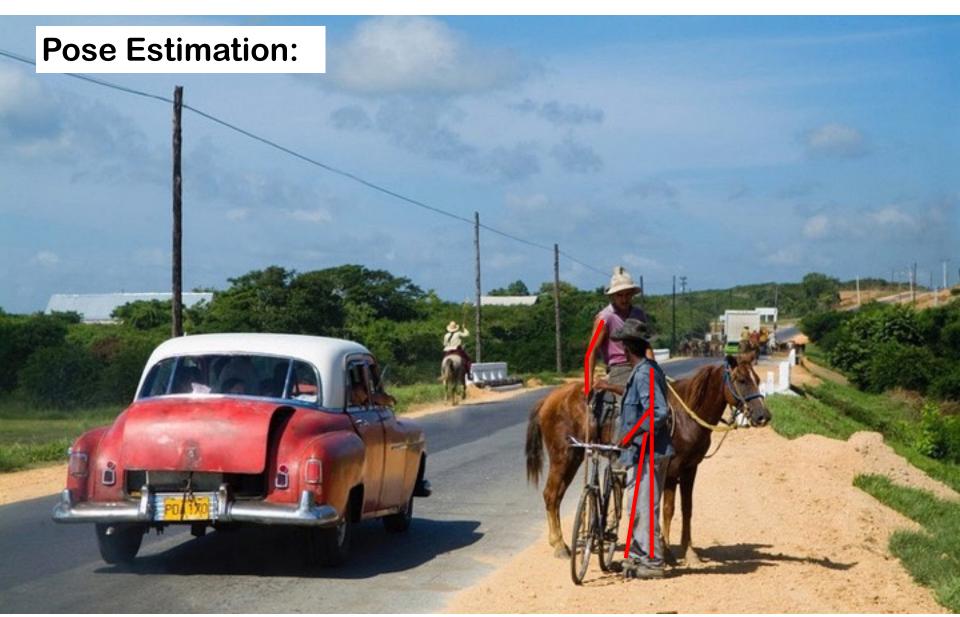


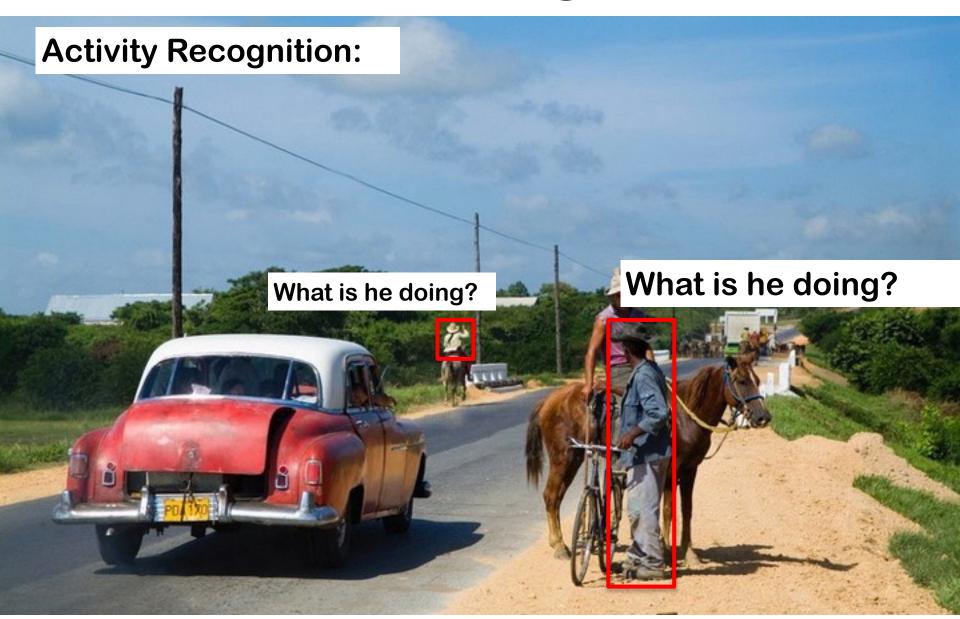
- What does it mean to "see"?
 - "What" is "where", Marr 1982
- Get computers to "see"

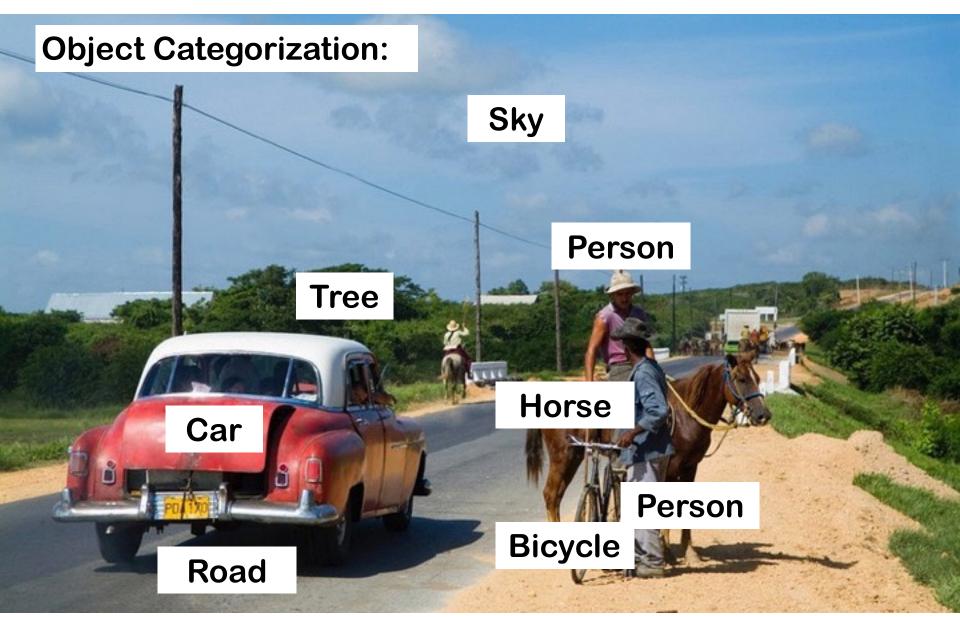


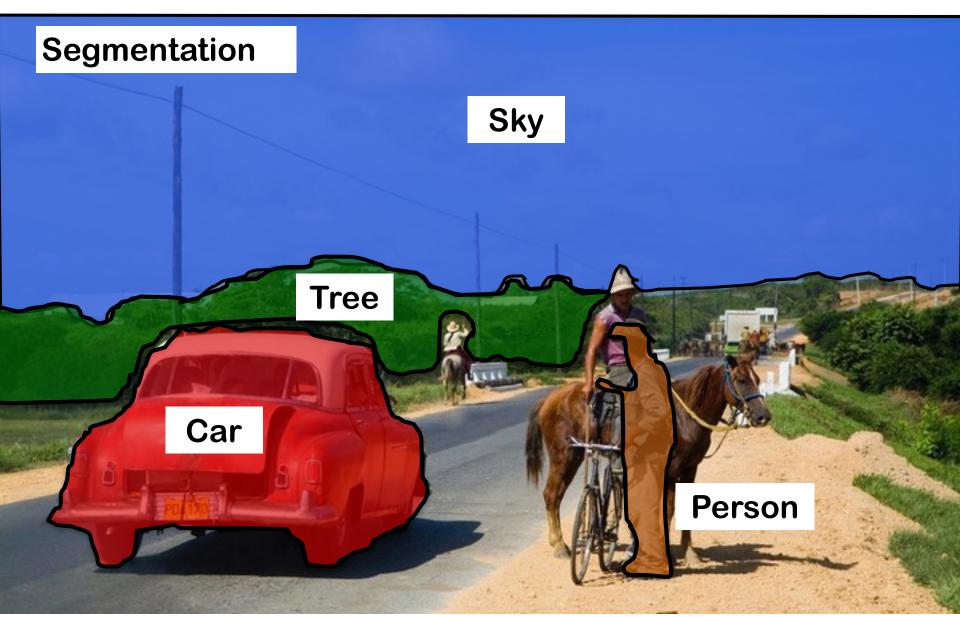




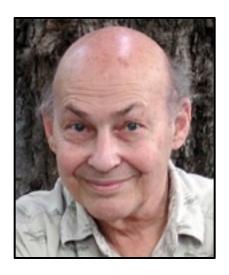








How hard is computer vision?



Marvin Minsky, MIT Turing award, 1969

"In 1966, Minsky hired a first-year undergraduate student and assigned him a problem to solve over the summer: connect a television camera to a computer and get the machine to describe what it sees."

Crevier 1993, pg. 88

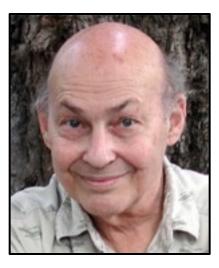
MASSACHUSETTS INSTITUTE OF TECHNOLOGY PROJECT MAC

Artificial Intelligence Group Vision Memo. No. 100. July 7, 1966

THE SUMMER VISION PROJECT

Seymour Papert.

The summer vision project is an attempt to use our summer workers effectively in the construction of a significant part of a visual system. The particular task was chosen partly because it can be segmented into sub-problems which will allow individuals to work independently and yet participate in the construction of a system complex enough to be a real landmark in the development of "pattern recognition".



Marvin Minsky, MIT Turing award, 1969



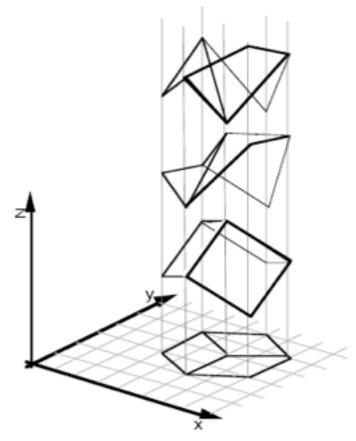
Gerald Sussman, MIT

"You'll notice that Sussman never worked in vision again!" – Berthold Horn

Why vision is so hard?

Why is vision so hard?

Ill-posed problem



[Sinha and Adelson 1993]

Challenges 1: view point variation

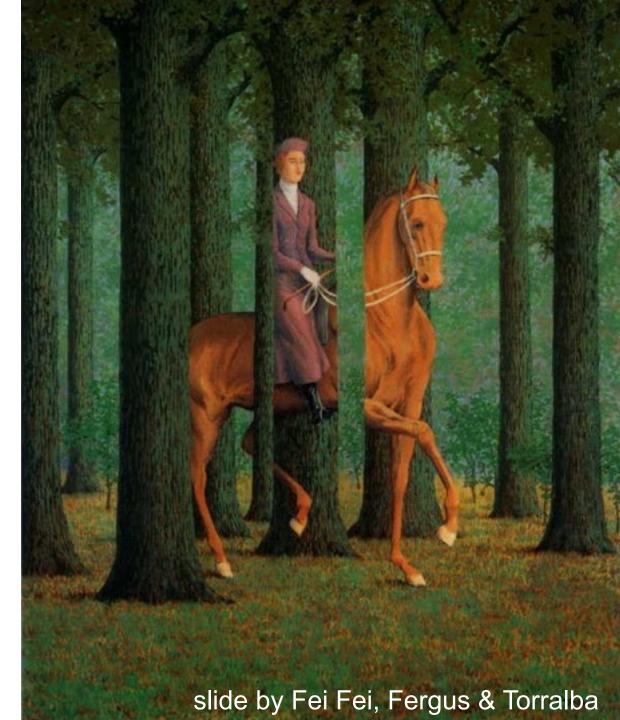


Challenges 2: illumination





Challenges 3: occlusion

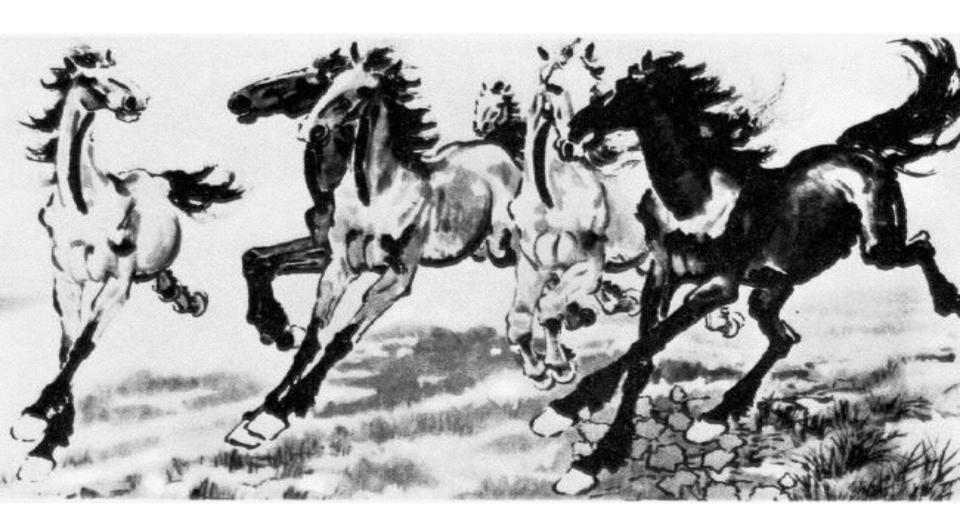


Challenges 4: scale

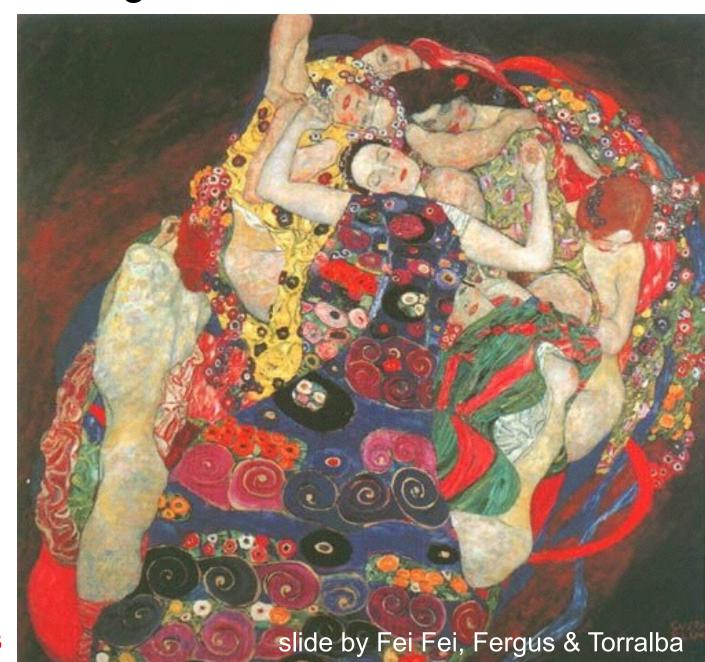


slide by Fei Fei, Fergus & Torralba

Challenges 5: deformation



Challenges 6: background clutter



Challenges 7: object intra-class variation



slide by Fei-Fei, Fergus & Torralba

Challenges 8: local ambiguity



slide by Fei-Fei, Fergus & Torralba

Challenges 9: the world behind the image



What Works Today?

Reading license plates, zip codes, checks

```
3681796691
6757863485
2179712845
4819018894
7618641560
7592658197
1222234480
0 2 3 8 0 7 3 8 5 7
0146460243
7128169861
```

Biometrics



Fingerprint scanners on many new laptops, other devices





Face recognition systems now beginning to appear more widely http://www.sensiblevision.com/

Source: S. Seitz

Mobile visual search: Google Goggles

Google Goggles in Action

Click the icons below to see the different ways Google Goggles can be used.







Face detection

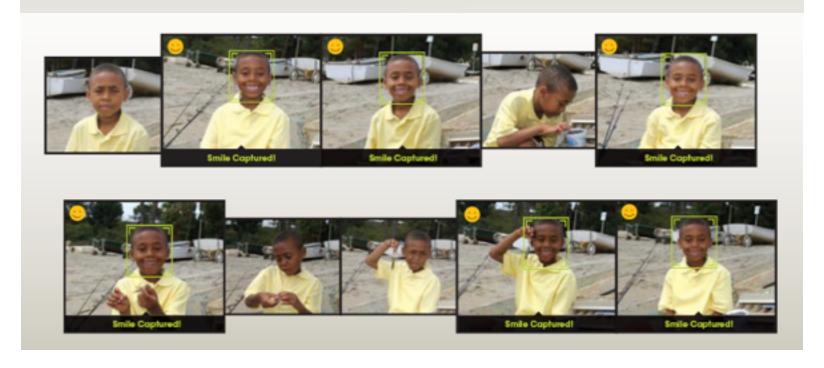


- Many new digital cameras now detect faces
 - Canon, Sony, Fuji, ...

Smile detection

The Smile Shutter flow

Imagine a camera smart enough to catch every smile! In Smile Shutter Mode, your Cyber-shot® camera can automatically trip the shutter at just the right instant to catch the perfect expression.



Face recognition: Apple iPhoto, Facebook, Google, etc



Object recognition (in supermarkets)



LaneHawk by EvolutionRobotics

"A smart camera is flush-mounted in the checkout lane, continuously watching for items. When an item is detected and recognized, the cashier verifies the quantity of items that were found under the basket, and continues to close the transaction. The item can remain under the basket, and with LaneHawk, you are assured to get paid for it... "

BB@ NEWS

■ Watch One-Minute World News

Last Updated: Wednesday, 31 August 2005, 05:44 GMT 06:44 UK

E-mail this to a friend



Computer alert for drowning girl

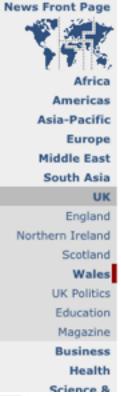
A 10-year-old girl has been saved from drowning by a computer system designed to raise the alarm when swimmers get into difficulties.

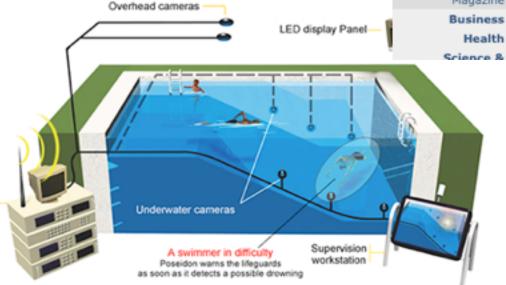


The girl, from Rochdale, was at the deep end of the

pool in Bangor, north Wales, when she sank to the bottom.

The £65,000 system, called Poseidon, detected her on the pool floor and sounded the alarm. A lifeguard pulled her out and she recovered in hospital.





Security



Cameras help confirm Scott suicide ruling



TAGS: local, paul meincke

P Comment Now Email Print Report a typo 🔝 🖪 💆 🏰 📑



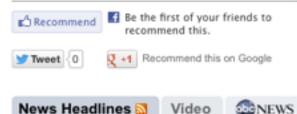
Paul Meincke More: Bio, News Team

December 4, 2009 (CHICAGO) (WLS) -- Chicago police have closed the case in the death of Chicago School Board President Michael Scott.

Police Supt. Jody Weis says investigators used police cameras in the city to trace Scott's last steps in the hours before his body was found in November.

Scott's death has been ruled a suicide. The medical examiner's office concluded --not long after Scott's body was found -- that he had committed suicide. Police did not dispute the finding but wanted to pursue all the investigative leads they could. They say they have done that and have now reached the same conclusion.

Share this Story



- 2 suspects arrested in volleyball star's murder 47 min ago
- BP Gas Recall: BP finds, fixes source of bad gas
- Teachers union, board resume negotiating
- Back to School
- 5 injured in South Side shooting 49 min ago
- Pastor: Stacy Peterson said she lied for Drew

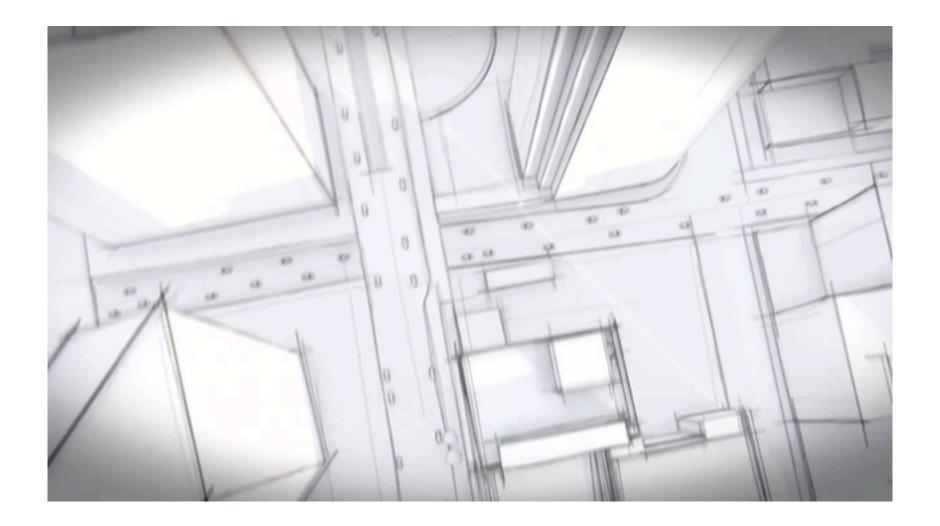


Automotive safety



- Mobileye: Vision systems in high-end BMW, GM, Volvo models
 - Pedestrian collision warning
 - Forward collision warning
 - Lane departure warning
 - Headway monitoring and warning

Source: A. Shashua, S. Seitz



Google cars



Oct 9, 2010. "Google Cars Drive Themselves, in Traffic". The New York Times. John Markoff

June 24, 2011. "Nevada state law paves the way for driverless cars". Financial Post. Christine Dobby

Aug 9, 2011, "Human error blamed after Google's driverless car sparks five-vehicle crash". The Star (Toronto)

Vision-based interaction: Xbox Kinect





Kinect Fusion

SIGGRAPH Talks 2011

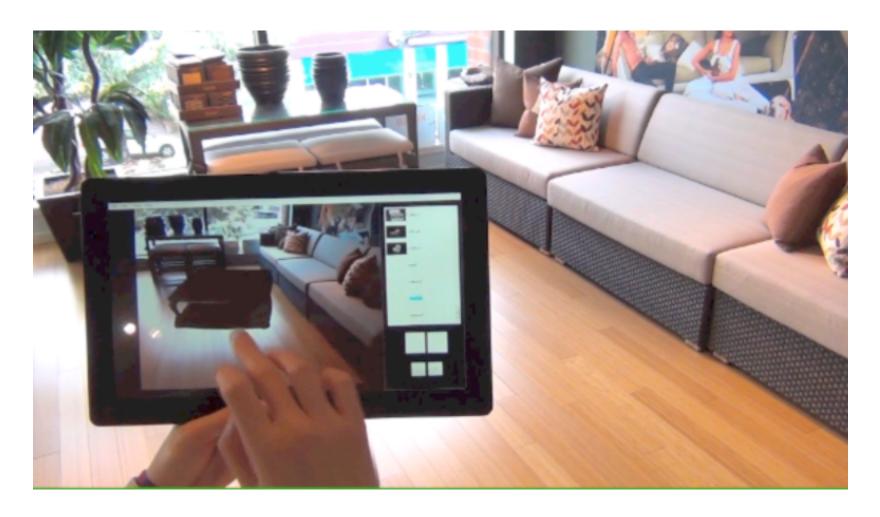
KinectFusion:

Real-Time Dynamic 3D Surface Reconstruction and Interaction

Shahram Izadi 1, Richard Newcombe 2, David Kim 1,3, Otmar Hilliges 1,
David Molyneaux 1,4, Pushmeet Kohli 1, Jamie Shotton 1,
Steve Hodges 1, Dustin Freeman 5, Andrew Davison 2, Andrew Fitzgibbon 1

1 Microsoft Research Cambridge 2 Imperial College London 3 Newcastle University 4 Lancaster University 5 University of Toronto

Augmented reality, consumer products



Special effects: shape and motion capture



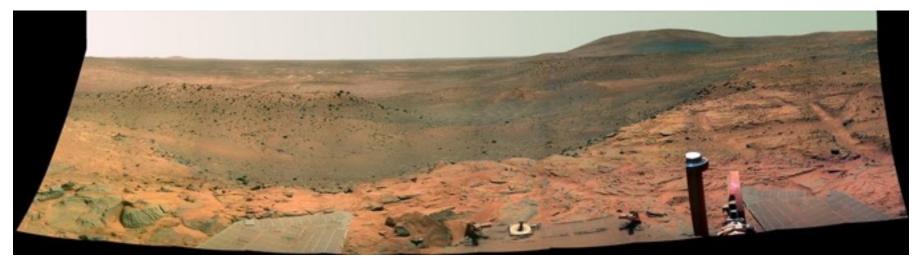






Source: S. Seitz

Vision for robotics, space exploration



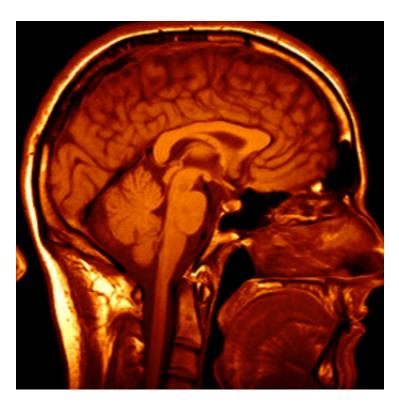
NASA'S Mars Exploration Rover Spirit captured this westward view from atop a low plateau where Spirit spent the closing months of 2007.

Vision systems (JPL) used for several tasks

- Panorama stitching
- 3D terrain modeling
- Obstacle detection, position tracking
- For more, read "Computer Vision on Mars" by Matthies et al.

Source: S. Sei

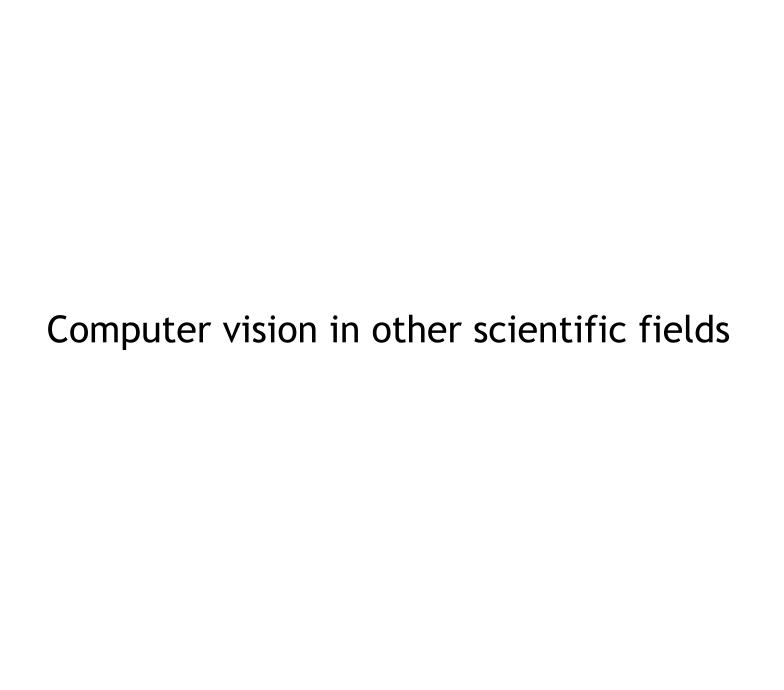
Medical imaging



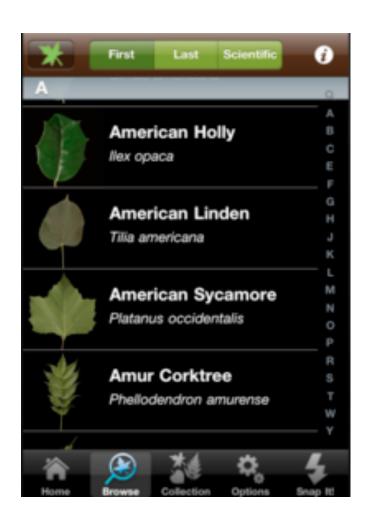
3D imaging MRI, CT

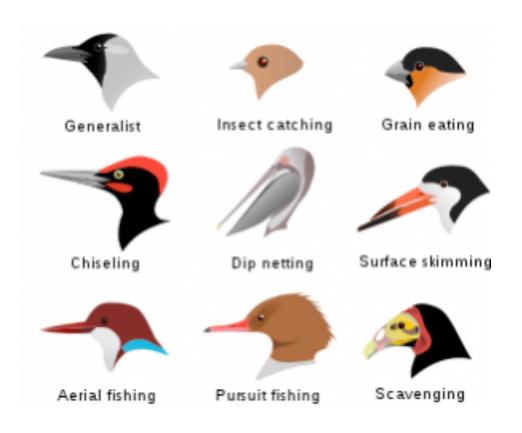


Image guided surgery Grimson et al., MIT



Computer vision research in biology



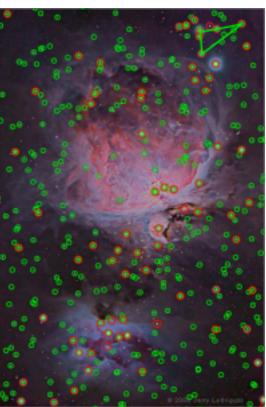


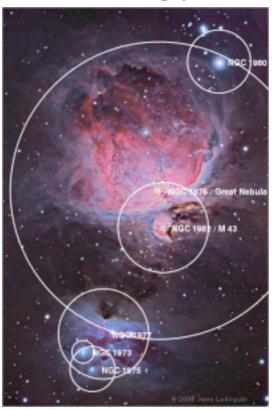
http://leafsnap.com/

http://www.vision.caltech.edu/visipedia/

Computer vision in cosmology







Computer vision research in healthcare



assisted living, patient monitoring [Lan et al, PAMI 2012]



autism screening
http://www.gatech.edu/newsroom/
release.html?nid=60509

Computer vision in the real-world

- Most examples are less than 5 years old
- Very active research area. Many new applications to come.
- A website of computer vision industries maintained by Prof. David Lowe (UBC):

http://www.cs.ubc.ca/~lowe/vision.html

Tentative Syllabus

- Image Processing (2 weeks)
- filtering, convolution
- image pyramids
- edge detection
- feature detection (corners, lines)
- hough transform
- Image Transformation (2 weeks)
- image warping (parametric transformations, texture mapping)
- image compositing (alpha blending, color mosaics)
- segmentation and matting (snakes, scissors)
- Motion Estimation (1 week)
- optical flow
- image alignment
- image mosaics
- feature tracking

Syllabus

3D Modeling (1 weeks)

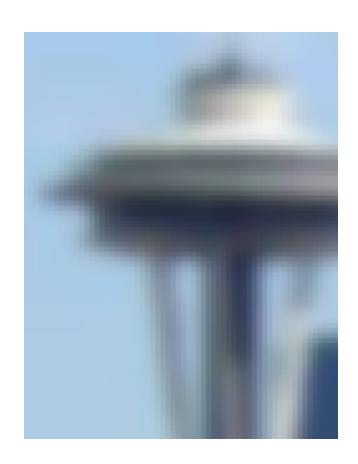
- projective geometry
- camera modeling
- single view metrology
- camera calibration
- stereo
- Computational Photography (1 week)
- Super resolution
- Alpha Matting
- Blur removal
- Poisson Blending
- Visual Recognition (3 week)
- Eigenfaces
- Category Recognition
- Object Detection
- Kinect

Grading

- Four assignments (10 each+ extra points)
 - Mix of coding and written answers.
 - Using Qt (cross platform UI in c++) qt.nokia.com
 - Use of interactive UIs for exploring and gaining intuition
 - 1. Filters and edge detection
 - 2. Creating panoramas
 - 3. Computing depth from stereo
 - 4. Face detection
- FINAL PROJECT (60 points + 20 extra points)

Assignment 1: Image Filtering 10 Points





Assignment 2: Panorama Stitching 10 Points



Assignment 3: Stereo Reconstruction 10 Points







Assignment 4: Face Detection 10 Points

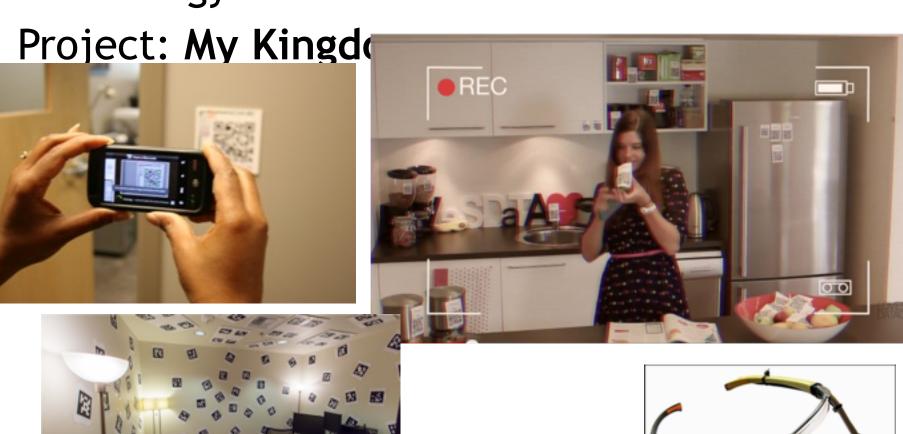


Final Project 60 Points + 20 Extra points

- Big Project
 - Better if related to your own research
 - Demo is a **BIG** plus
- Proposal is due on 4/8
 - One Paragraph,
 - Crisp final outcome/deliverable
- Progress Reports are due on
 - -4/20, 5/4, 5/18, 6/1
 - What has changed since last report
- Final Presentation will be on 6/3,
 - Demo/Posters @ CSE atrium

Sample Projects

From Taskar Center for Accessible Technology



Sample Projects

From Taskar Center for Accessible Technology

Project: Curb Alert





Sample Projects

From Taskar Center for Accessible Technology



Samples of Previous Projects

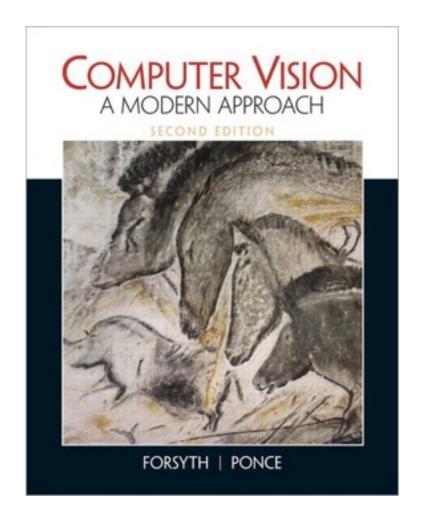
- Visual Calculator
- Seam Carving
- X-ray bone fracture detection
- Pipe leak detection
- Is it gonna be viral?
- Deep learning for object recognition
- •

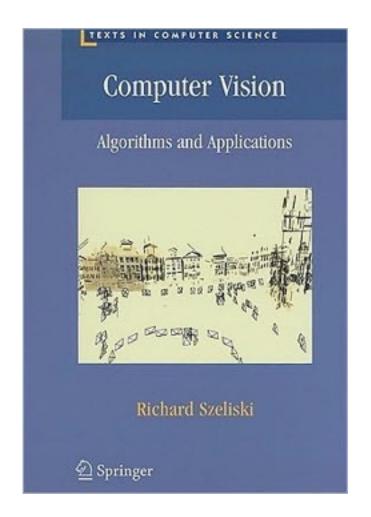
Project Ideas

- Seam Carving
- Detecting Shadows
- Features
 - Learning Features
 - Features for regions
 - Comparison of features in the literature
- Action Recognition
 - Human pose
 - Objects and Interactions
 - Using Kinect
 - Detecting unattended luggages
 - Egocentric
- Grab cut

- Video Stabilization
- RGBD object Detection
- Object Detection in Videos
 - Video Google
- Matching Images and Videos in the wild
- Reading Street Signs
 - Wearable Cameras for visually impaired users
 - Auto Zooming
- Visual Odometer
 - Smart stop lights
- Language & Vision

Books





Calibration

- How many of you
 - have taken an undergrad vision course?
 - have taken an ML course?
 - have taken a Graphics course?
 - Remember your linear algebra course in your undergrad?
 - have any concerns about programming?

Do these words remind you of something?

Interest Point	SIFT
Laplacian	Eigenvalue
SVD	SVM
MRF	STEREO
Random Forest	Graph cut

Preferences

Low level vision?

Mid level vision?

High level vision?