Online Learning
References and Other Topics

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Online Linear and Convex Optimization

Projected Gradient Descent View

M. Zinkevich. [Online convex programming and generalized infinitesimal gradient ascent](#). *ICML*, 2003.

Green check indicates papers we covered in class.

Follow-the-Regularized-Leader View

- Brendan McMahan. [Follow-the-Regularized-Leader and Mirror Descent: Equivalence Theorems and L1 Regularization](#), AISTATS 2011. ✔
- Shai Shalev-Shwartz, [Online Learning and Online Convex Optimization](#), Foundations and Trends in Machine Learning, 2012. ✔
- Sasha Rakhlin, [Lecture Notes on Online Learning](#).
- Brendan McMahan, [Analysis Techniques for Adaptive Online Learning](#), arXiv 2014. ✔

Kalai-Vempala

Adam Kalai and Santosh Vempala. Efficient algorithms for online decision problems, COLT 2003 (link is to journal version, 2005).

J. Hannan, Approximation to Bayes risk in repeated plays, Contributions to the Theory of Games, 1957.

Model:

- K experts "embedded" in R^d (possibly infinitely many)
- Given an Oracle M: g -> K that finds the best expert given a linear cost function

Kalai-Vempala Algorithm:
Follow-the-Perturbed-Leader

FPL given oracle M, parameter ϵ

For rounds $t = 1, \ldots, T$

- Choose p_t uniformly at random from the cube $[0, 1/\epsilon]^n$
- Let $z = g_{1:t-1} + p_t$
- Play

$$w_t = M(w) = \arg\min_{\text{experts } w} z \cdot w$$

- Pay $g_t \cdot w_t$ and observe g_t

Achieves:

$$\text{Regret} \leq \mathcal{O}(\sqrt{T})$$

(Hiding usual dependence on $\|g_t\|$, $\max_{w,w'} \|w - w'\|$, etc.)

Learning with Structure

Ofer Dekel, Shai Shalev-Shwartz, and Yoram Singer.
[Individual sequence prediction using memory-efficient context trees](). IEEE Transactions on Information Theory, 2009.

Wouter M. Koolen, Manfred K. Warmuth, Jyrki Kivinen.
[Hedging Structured Concepts](), COLT 2010.

David P. Helmbold and Manfred K. Warmuth.
[Learning Permutations with Exponential Weights](),
JMLR 2009.

Log(T) Regret for Strongly Convex f

Elad Hazan,Amit Agarwal and Satyen Kale. **[Logarithmic Regret Algorithms for Online Convex Optimization](#)** Machine Learning, 2007.

Key point:
exp-concavity is really the key property, not strong convexity.

You can get log(T) regret for:
- online linear regression
- online portfolio management

Second-Order Algorithms

We've mostly considered algorithms that approximate f(x) by its gradient. Instead:

FOLLOW THE APPROXIMATE LEADER (**version 1**)

Inputs: convex set $\mathcal{P} \subset \mathbb{R}^n$, and the parameter β.

- On period 1, play an arbitrary $\mathbf{x}_1 \in \mathcal{P}$.

- On period t, play the leader $\mathbf{x}_t$ defined as

$$\mathbf{x}_t \triangleq \arg\min_{\mathbf{x} \in \mathcal{P}} \sum_{\tau=1}^{t-1} \tilde{f}_\tau(\mathbf{x})$$

Where for $\tau = 1, \ldots, t-1$, define $\nabla_\tau = \nabla f_\tau(\mathbf{x}_\tau)$ and

$$\tilde{f}_\tau(\mathbf{x}) \triangleq f_\tau(\mathbf{x}_\tau) + \nabla_\tau^\top(\mathbf{x} - \mathbf{x}_\tau) + \frac{\beta}{2}(\mathbf{x} - \mathbf{x}_\tau)^\top \nabla_\tau \nabla_\tau^\top (\mathbf{x} - \mathbf{x}_\tau)$$

Also for Classification in the Mistake Bound Model

Nicolò Cesa-Bianchi, Alex Conconi, and Claudio Gentile.
[A Second-Order Perceptron Algorithm](),
SIAM Journal on Computing, Volume 34, 2005.

Francesco Orabona and Koby Crammer.
[New Adaptive Algorithms for Online Classification](),
NIPS 2010.

"Second-Order" Algorithms for Linear Functions (aka, AdaGrad)

The per-coordinate gradient descent algorithm is from
> Matthew Streeter, Brendan McMahan
> [Less Regret via Online Conditioning](#), Tech Report, 2010.

✓

For general feasible sets
> H. Brendan McMahan, Matthew Streeter.
> [Adaptive Bound Optimization for Online Convex Optimization](#), COLT 2010.
>
> John Duchi, Elad Hazan, and Yoram Singer.
> [Adaptive Subgradient Methods for Online Learning and Stochastic Optimization](#), JMLR 2011.

The Idea

When we've analyzed adaptive algorithms, the simplest thing to do is to use add regularization of the form

$$r_t(x) = \sigma_t \|x\|^2 = \sigma_t x^T I x$$

Instead, only add regularization in the direction of the t'th gradient:

$$r_t(x) = \sigma_t x^T (g_t g_t^T) x = x^T A_t x$$

The Experts Setting / Entropic Regularization

Experts Setting
Nick Littlestone and Manfred K. Warmuth. [The weighted majority algorithm](#).
Information and Computation, 1994.

EG vs GD for Squared Error
Jyrki Kivinen and Manfred K. Warmuth.
[Exponentiated Gradient versus Gradient Descent for Linear Predictors](#),
Information and Computation, 1997.

Game Theory View
Yoav Freund and Robert E. Schapire.
[Adaptive game playing using multiplicative weights](#),
Games and Economic Behavior, 1999. (Earlier version, 1996).

The unification of these ideas as online linear optimization using entropic regularization is a more recent view.

Minimax Analysis and Unconstrained Linear Optimization

Abernethy et. al. [Optimal Strategies and Minimax Lower Bounds for Online Convex Games](#), COLT 2008.

Matthew Streeter, H. Brendan McMahan. [No-Regret Algorithms for Unconstrained Online Convex Optimization](#), NIPS 2012.

H. Brendan McMahan, Jacob Abernethy. [Minimax Optimal Algorithms for Unconstrained Linear Optimization](#). NIPS 2013.

H. Brendan McMahan, Francesco Orabona. [Unconstrained Online Linear Learning in Hilbert Spaces: Minimax Algorithms and Normal Approximations](#). To appear, COLT 2014.

K-Armed Bandits (EXP3) and Contextual Bandits (EXP4)

Original EXP3 and EXP4 Analysis

Peter Auer, Nicolò Cesa-Bianchi,Yoav Freund, Robert E. Schapire
The Nonstochastic Multiarmed Bandit Problem,
SIAM Journal on Computing, 2003.

Analysis for Losses (No Mixing Needed)

S. Bubeck. Bandits Games and Clustering Foundations.
PhD thesis, 2010.
G. Stoltz. Incomplete information and internal regret in prediction of individual sequences. PhD thesis, 2005.

Improved EXP4 Analysis

H. Brendan McMahan, Matthew Streeter
Tighter Bounds for Multi-Armed Bandits with Expert Advice,
COLT 2009.

(but we did a different analysis)

High-probability bounds for EXP4

Beygelzimer, Langford, Li,Reyzin, and Schapire, Contextual Bandit Algorithms with Supervised Learning Guarantees, AISTATS 2011.

Stochastic Approaches to the Contextual Bandits Problem

Stochastic Setting

Peter Auer. [Using Confidence Bounds for Exploitation-Exploration Trade-offs](#), JMLR 2002.

L. Li, W. Chu, J. Langford and R. E. Schapire. [A contextual-bandit approach to personalized news article recommendation](#), WWW 2010.

Chu, Li, Reyzin, Schapire, R. [Contextual bandits with linear payoff functions](#), AISTATS 2011.

Model
- On each round each action has a feature vector x(a) associated with it. These can be chosen arbitrarily as long as:
- There exists a weight vector z* such that <z*, x> = E[Reward(a)| x] (realizability assumption).
- Goal: Do almost as well as selecting actions with the best weight vector.

Bandit Convex Optimization

General T^(3/4) Regret
Abraham Flaxman, Adam Tauman Kalai, H. Brendan McMahan
[Online convex optimization in the bandit setting: gradient descent without a gradient](), SODA 2005.

Robert Kleinberg. [Nearly Tight Bounds for the Continuum-Armed Bandit Problem](), NIPS 2005.

For strongly convex functions T^(2/3) Regret
Alekh Agarwal, Ofer Dekel, and Lin Xiao, [Optimal Algorithms for Online Convex Optimization with Multi-Point Bandit Feedback](), COLT 2010.

For smooth convex functions, T^(2/3) Regret
Ankan Saha and Ambuj Tewari, [Improved Regret Guarantees for Online Smooth Convex Optimization with Bandit Feedback](), AISTATS 2011.

Bandit Linear Optimization

Brendan McMahan, Avrim Blum. [Online Geometric Optimization in the Bandit Setting Against an Adaptive Adversary](), COLT 2004.
Gives a O(T^(3/4) log(T)) for online linear optimization against an adaptive adversary, using Kalai-Vempala as a black box.

Varsha Dani, Thomas Hayes. [Robbing the bandit: Less regret in online geometric optimization against an adaptive adversary](), SODA 2006.
Improves to regret O(poly(d) T^(2/3)).

Varsha Dani, Thomas Hayes, & Sham M. Kakade. [The Price of Bandit Information for Online Optimization](), NIPS 2007.
The first O(sqrt(T)) bound for online linear optimization, but with an inefficient algorithm. Also does lower bounds.

J. Abernethy, E. Hazan, and A. Rakhlin. [Competing in the dark: An efficient algorithm for bandit linear optimization](),COLT 2008.
An efficient O(sqrt(T)) algorithm using self-concordant barrier functions.

Peter L. Bartlett, et. al. [High-Probability Regret Bounds for Bandit Online Linear Optimization](), COLT 2008.
High-probability O(sqrt(T)) bounds, but the algorithm is not efficient.

Jacob Abernethy and Alexander Rakhlin. [Beating the Adaptive Bandit with High Probability](), COLT 2009.
Extends "competing in the dark" with an efficient algorithm with high-probability bounds against an adaptive adversary, but only for some specific feasible sets. Has a good summary of existing results.

Online Submodular Minimization

Elad Hazan and Satyen Kale, Online Submodular Minimization, NIPS 2009.

Decision space is the set of all subsets of a ground set.
Cost functions on each round are *sub-modular*:

A function $f : 2^{[n]} \to \mathbb{R}$ is called *submodular* if for all sets $S, T \subseteq [n]$ such that $T \subseteq S$, and for all elements $i \in E$, we have

$$f(T + i) - f(T) \geq f(S + i) - f(S).$$

Diminishing costs: adding i to a larger set increases the cost less than adding i to a smaller set. (For this to be interesting, we need the left-hand-side to be negative for some i). Submodularity is a kind of discrete analogue to convexity.

Simple case: linear set functions:
(For minimization, again only
interesting if some $a_i < 0$)

$$f(S) = \sum_{i \in S} a_i$$

Online Kernel Methods
with a Budget of Support Vectors

We've mostly used simple hypothesis classes, e.g., generalized linear models. But what if we want to use kernels?

We don't know how to do this in the offline case, but online we have results:

Ofer Dekel, Shai Shalev-Shwartz, and Yoram Singer.
The Forgetron: A kernel-based perceptron on a budget,
SIAM Journal on Computing, 2008.

G. Cavallanti, N. Cesa-Bianchi, and C. Gentile.
Tracking the best hyperplane with a simple budget Perceptron,
Machine Learning,2007.

Selective Sampling / Online Active Learning / Label Efficient Learning

For rounds t = 1, 2, ...

- adversary reveals feature vector x
- we predict a label (and incur loss)
- we only observe the true label y if we select to query it

Goal: Achieve a good tradeoff between classification accuracy and the number of label queries we make.

This is a partial information setting, but we can control whether or not we observe the label.

Selective Sampling / Online Active Learning / Label Efficient Learning

N. Cesa-Bianchi, G. Lugosi, and G. Stoltz.
Minimizing regret with label efficient prediction,
IEEE Transactions on Information Theory, 2005.

F. Orabona and N. Cesa-Bianchi.
Better algorithms for selective sampling, ICML 2011.

N. Cesa-Bianchi, C. Gentile, and F. Orabona.
Robust bounds for classification via selective sampling, ICML 2009.

N. Cesa-Bianchi, C. Gentile, and L. Zaniboni.
Worst-case analysis of selective sampling for linear classification
Journal of Machine Learning Research, 2006.

Ofer Dekel, Claudio Gentile, and Karthik Sridharan.
Robust selective sampling from single and multiple teachers, COLT 2010.

Other Problems

Online PCA
Manfred K. Warmuth, Dima Kuzmin
[Randomized Online PCA Algorithms with Regret Bounds that are Logarithmic in the Dimension](),
Journal of Machine Learning Research, 2008.

Online One-Class Prediction (e.g., outlier detection)
Koby Crammer, Ofer Dekel, Joseph Keshet, Shai Shalev-Shwartz, and Yoram Singer. [Online passive-aggressive algorithms](). Journal of Machine Learning Research, 2006.

Online Ranking
Koby Crammer and Yoram Singer
[PRanking with Ranking](), NIPS 2001.