

Last time

- SVD + applications
- least squares
- perceptron alg.

Today

- PAC learning
- Gradient descent & SGD
- Linear programming (maybe)

Setting: supervised learning setting  
classify email msgs  $\begin{cases} \rightarrow \text{spam} \\ \rightarrow \text{not spam} \end{cases}$

Take a sample of msgs, labelled according to spam y/n.

Goal: given labelled sample, come up with a good rule for classifying future msgs

$h^* : \{0,1\}^n \rightarrow \{0,1\}$   
true label

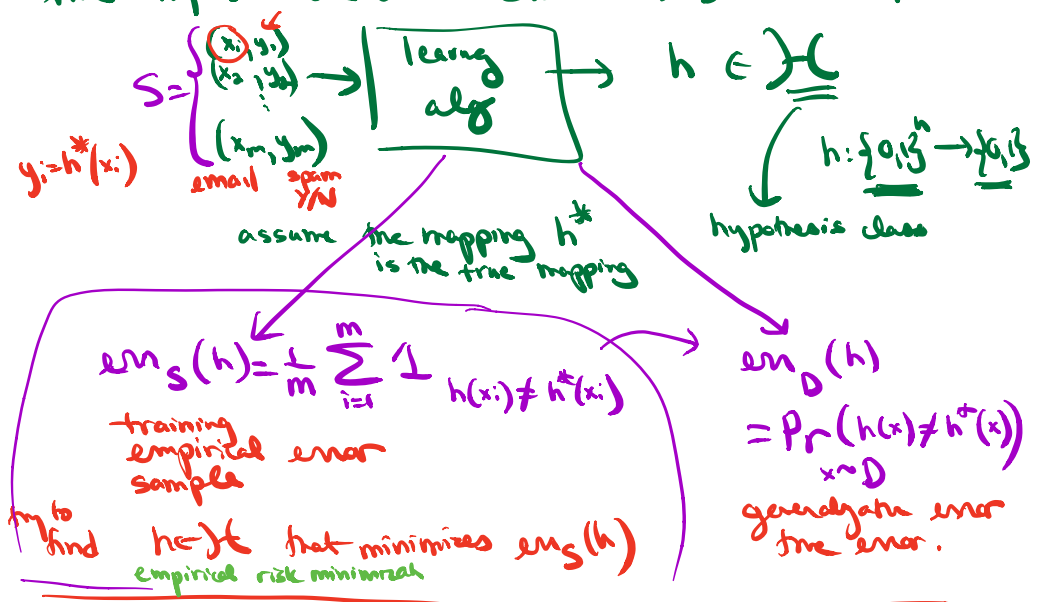
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	money	pills	Mr.	bad spelling	know-sarden	spam?
1	x	22	x	x	2x2	x
2	22	22	22	x	2x2	x
3	22	22	22	222	x	22
4	22	22	22	22	222	22
5	22	22	22	22	22	22
6	22	22	22	22	22	22
7	22	22	22	22	22	22
8	22	22	22	22	22	22
9	22	22	22	22	22	22
10	22	22	22	22	22	22

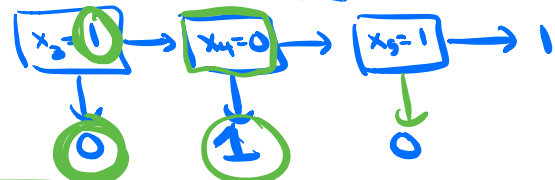
return SPAM if  $\neg$  know and (money or pills)

① distn over inputs  $x \in X$   
 each sample  $x_i$  is drawn indep from ①  
 see  $m$  samples

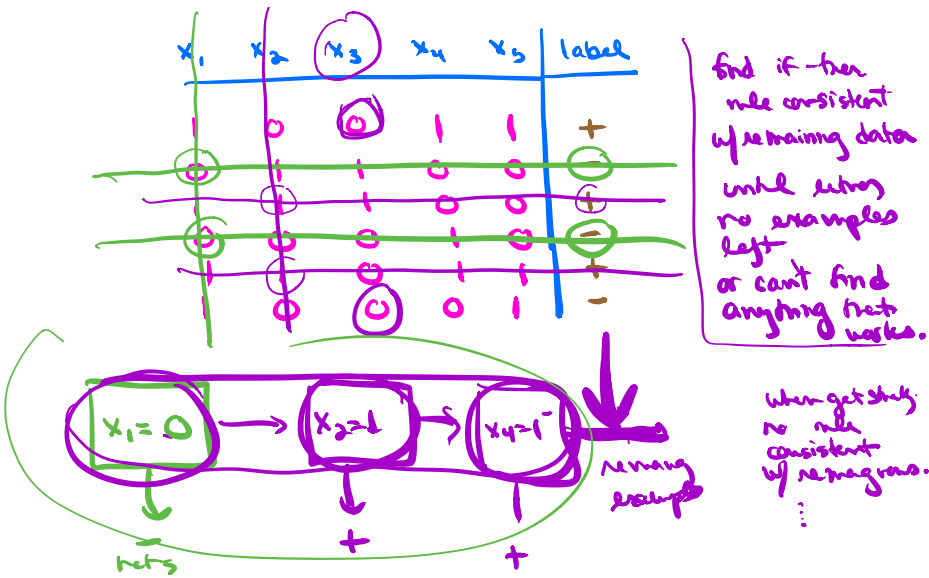
future inputs are also drawn from same distn



$\mathcal{H}$  : decision lists  $\vec{x} \in \{0,1\}^n = (x_1, x_2, \dots, x_n)$



$|\mathcal{H}| = n! \cdot (2 \cdot 2)^n = n! \cdot 4^n$



have a nice alg for finding consistent  $D_2$  if such exists.

Confidence, generalization - Claim: if  $|S|$  was  $\geq \frac{1}{\epsilon} \ln \frac{1}{\delta}$  then w.h.p.  $err_D(h)$  small.

Consider some  $D_2$   $h \in \mathcal{H}$  that  $err_D(h) \geq \epsilon$

Prob( $h$  was consistent w/ our sample)  $\leq (1-\epsilon)^{|S|}$

$\Pr(\exists D_2$   $h$  such that  $err_D(h) \geq \epsilon$  but  $err_S(h) = 0)$

$\leq \sum_{\substack{h \in \mathcal{H} \\ s.t. \ err_D(h) \geq \epsilon}} \Pr(err_S(h) = 0) \leq |\mathcal{H}| (1-\epsilon)^{|S|}$

$(1-x)^n \leq e^{-nx}$

$|\mathcal{H}| e^{-\epsilon |S|}$

$h$  misclassifies  $\epsilon$  but  $h$  classifies correctly

How big does  $S$  need to be so that  $\epsilon |S| > \ln \frac{1}{\delta}$

$|\mathcal{H}| (1-\epsilon)^{|S|} \leq \delta$

$n! 4^n e^{-\epsilon |S|} \leq \delta$

$\frac{n^n 4^n}{n!} \leq e^{\epsilon |S|}$

$$n \ln n + n \ln \frac{1}{\delta} \leq \epsilon |S|$$

$$\frac{2}{\epsilon} (n \ln n + n \ln \frac{1}{\delta}) \leq |S|$$

$\ln |\mathcal{H}|$

if  $|S| = \Omega\left(\frac{1}{\epsilon} (n \ln n + \frac{1}{\delta})\right)$  then  
 $\Pr(\exists h \in \mathcal{H} \text{ s.t. } \underbrace{\text{em}_D(h) \geq \epsilon}_{\text{true}} \text{ and } \underbrace{\text{em}_S(h) = 0}_{\text{true}}) \leq \delta$

If we can find  $h \in \mathcal{H}$  that is consistent w/ sample  
 then rule  $h$  we find  
 is probably approximately correct  
 $\geq 1 - \delta$  error  $\leq \epsilon$

PAC-learning

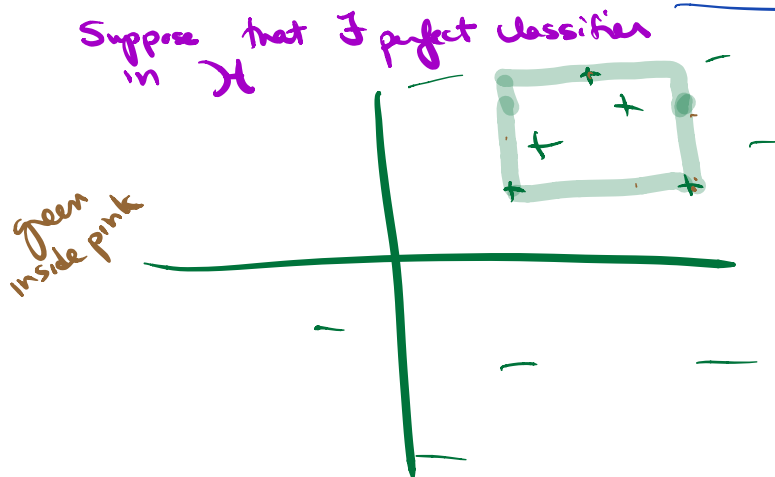
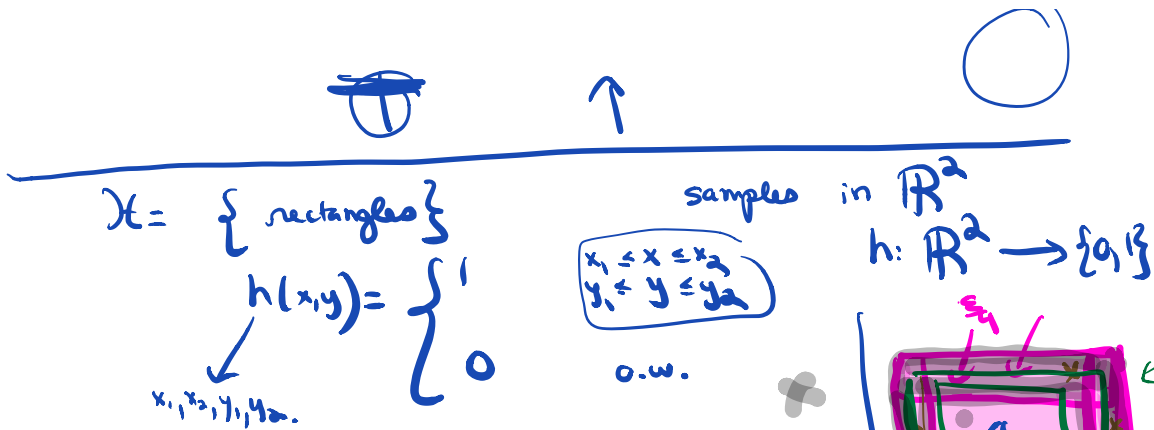
Turning around.  
 Leslie Valiant.

\* If  $|S| \geq \frac{1}{\epsilon} (\ln |\mathcal{H}| + \ln \frac{1}{\delta})$  Sample complexity  
 then w prob  $\geq 1 - \delta$ , any  $h \in \mathcal{H}$   
 that has  $\text{em}_D(h) \geq \epsilon$  will have  $\text{em}_S(h) > 0$

assumed  $\exists h \in \mathcal{H}$  s.t.  $\text{em}_S(h) = 0$

Thm:

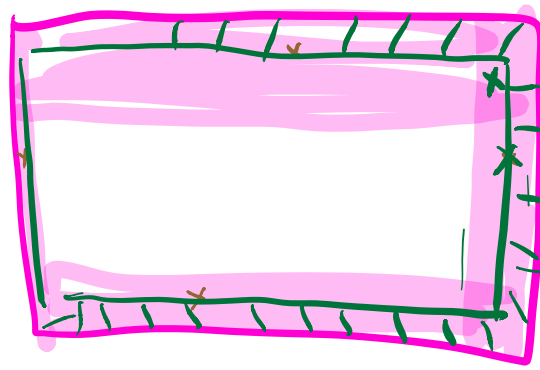
If  $|S| \geq \frac{1}{2\epsilon^2} (\ln |\mathcal{H}| + \ln \frac{1}{\delta})$  Sample complexity  
 then w prob  $\geq 1 - \delta$ , for every  $h \in \mathcal{H}$   
 $|\text{em}_S(h) - \text{em}_D(h)| \leq \epsilon$   $h^*$



output shallest possible bounding rectangle.

$\Pr(\text{green rectangle has error} \geq \epsilon)$

If  $\exists$  sample in each of 4 little pink rectangles, then  $\Pr(\text{error on random draw} \leq \epsilon)$



if get a sample in each of 4 pink subrectangles then  $\Pr(\text{making a mistake}) \leq 4 \cdot \frac{\epsilon}{4} \leq \epsilon$

$\rightarrow \Pr \frac{\epsilon}{4}$

$\Pr(\text{error}_D(\text{shallest bounding rectangle}) > \epsilon)$   
 $\leq \Pr(\exists \text{ pink subrectangle w/ no sample in it})$

$$\leq 4 \cdot \text{Pr}(\text{no sample in particular sub rectangle})$$

$$= 4 \left(1 - \frac{\epsilon}{4}\right)^{|S|} \leq \epsilon$$

$$\frac{4}{\epsilon} \ln\left(\frac{4}{\epsilon}\right) \leq |S|$$

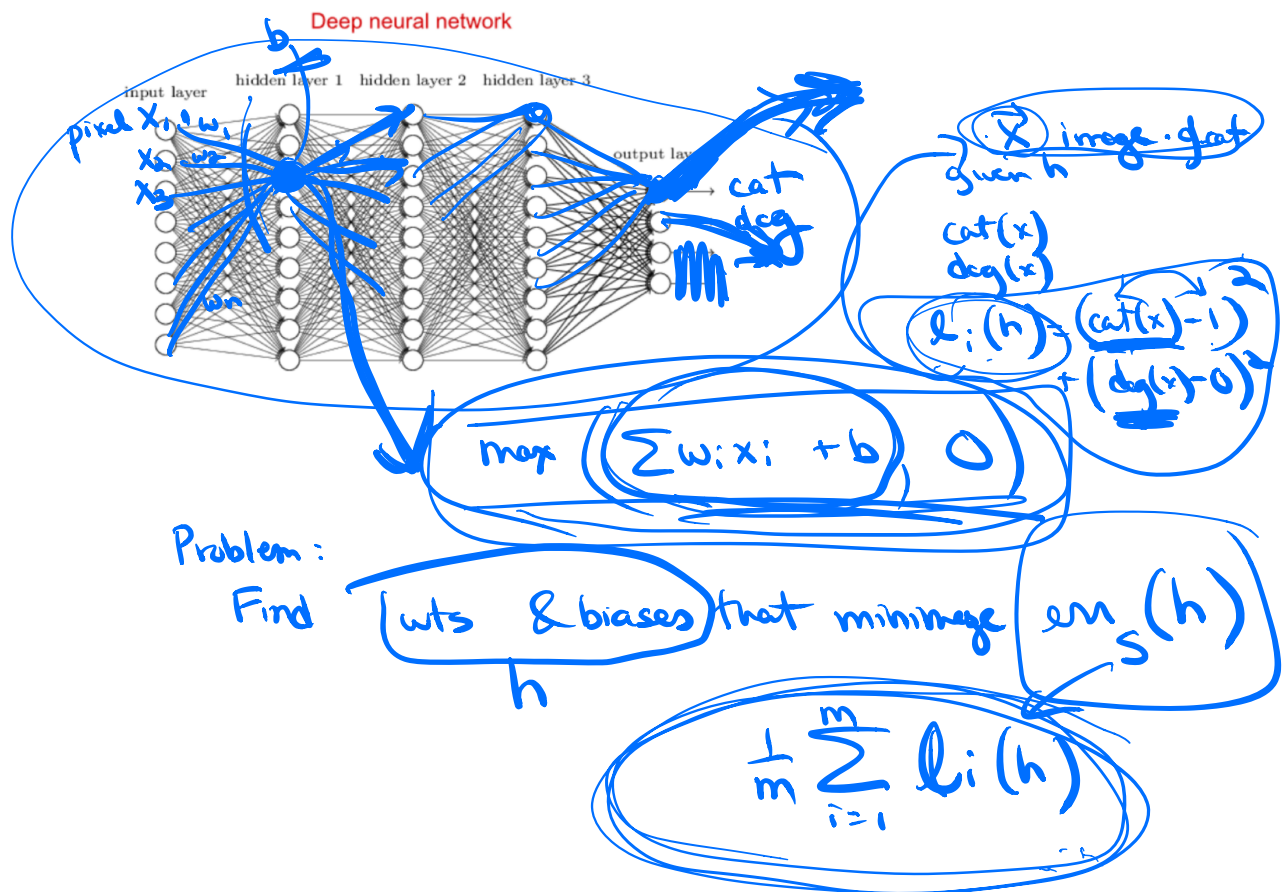
find  $h \in \mathcal{H}$  to minimize  $err_S(h)$

optimization problem.

$\Rightarrow$

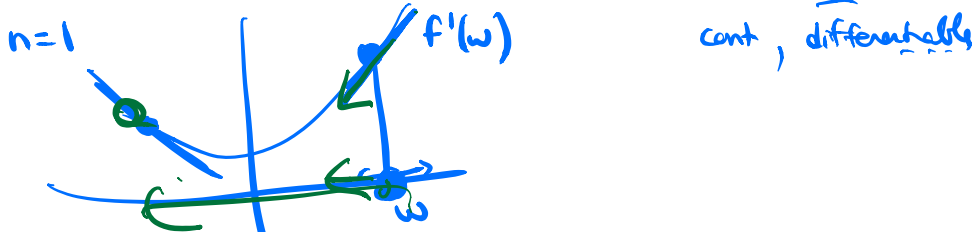
$$= \frac{1}{m} \sum_{i=1}^m \text{loss}(h, \text{sample } i)$$

$\uparrow$   
 $l_i(h)$



# Gradient descent

method for "trying" to minimize a fn.  $f: \mathbb{R}^n \rightarrow \mathbb{R}$



cont, differentiable

$$f(w+s) \approx f(w) + s \cdot f'(w)$$

$$\frac{f(w+s) - f(w)}{s} \approx f'(s)$$

$s > 0 \Rightarrow s < 0$   
 $s < 0 \Rightarrow s > 0$

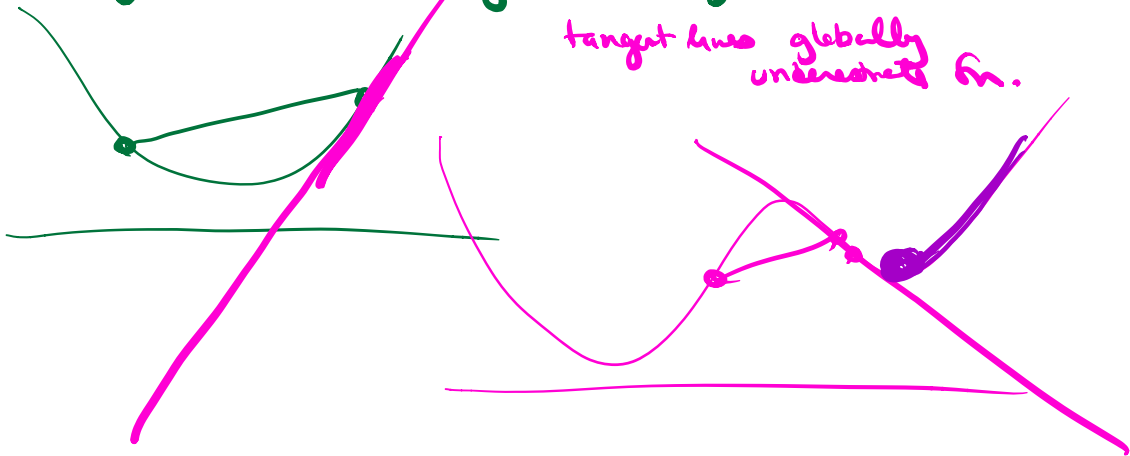
$w_0 :=$  arbitrary  
 for  $t=1, \dots$  "done"

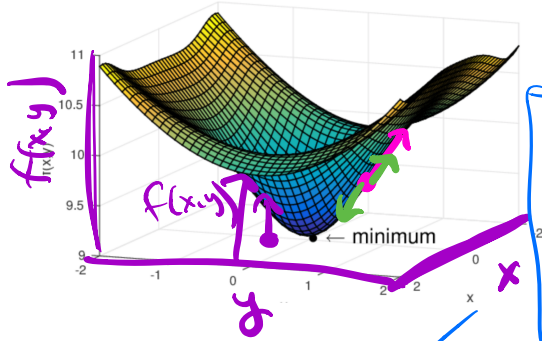
$$w_{t+1} := w_t - \eta_t f'(w_t)$$

para  
 take s opposite  
 direct of  
 devolved

If fn is convex, then w/ appropriately  
 selected values of  $\eta_t$   
 guaranteed to converge to global min

tangent lines globally  
 underestimate fn.





$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$f(x,y) = x^2 + 2xy + 4y^2$$

$$\frac{\partial f(x,y)}{\partial x} = 2x + 2y$$

$$\frac{\partial f(x,y)}{\partial y} = 2x + 8y$$

$$f(\vec{w} + \vec{s}) \approx f(\vec{w}) + \vec{s} \cdot \nabla f(\vec{w})$$

$(w_1, \dots, w_n)$      $(s_1, s_2, \dots, s_n)$   
 $(w_1, s_1, w_2, s_2, \dots)$

gradient of  $f$

$$\begin{pmatrix} \frac{\partial f}{\partial x}(\vec{w}) \\ \frac{\partial f}{\partial y}(\vec{w}) \\ \vdots \end{pmatrix}$$

$$\nabla f(1,1) = \begin{pmatrix} 4 \\ 10 \end{pmatrix}$$

$$f(1+s_1, 1+s_2) \approx f(1,1) + 4s_1 + 10s_2$$

$(s_1, s_2)$      $\begin{pmatrix} 4 \\ 10 \end{pmatrix}$

$$= \|\vec{s}\| \|\nabla f\| \cos \theta$$

want to move in direction opposite



$$\vec{w}_{t+1} = \vec{w}_t + \eta \nabla f(\vec{w}_t)$$

direction of negative gradient.  
gradient descent.

$$em_S(w_1, \dots, w_n)$$

cost of single update  
fn of  $n; m$  # sample pts  
fn we're trying to minimize

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$\frac{1}{m} \sum_{i=1}^m \ell_i(\vec{w})$$

error on  $i$ th sample pt.

$$\nabla f = \frac{1}{m} \sum_{i=1}^m \nabla \ell_i(\vec{w})$$

$n$  # wts & biases  
 $m$  # images

at each  $t$ ,  
pick one random image  
uniformly at random

$$I_t \in \{1, \dots, m\}$$

$$E(\nabla \ell_{I_t}(\vec{w})) = \sum_{i=1}^m \Pr(\text{select } i) \nabla \ell_i(\vec{w})$$

$$= \frac{1}{m} \sum_{i=1}^m \nabla \ell_i(\vec{w})$$

$$= \nabla \text{loss fn}$$



Define  $w^*$  to be min of  $f_n$  ( $em_s(w)$ )

$$\mathbb{E} [em_s(\bar{w}) - em_s(w^*)] \leq \frac{R \cdot G}{T} \text{ convts.}$$

run SGD  
for  $T$  steps

$$\bar{w} = \frac{1}{T} \sum_{t=1}^T w_t$$

$$\|w_0 - w^*\|^2 \leq R$$

$$\max \|\nabla \ell_i(w)\|^2 \leq G$$