# Supplementary Materials for "Reactive Learning: Active Learning with Relabeling"

### 1 Theorem 1

*Proof.* We first show that the theorem is true when X<sub>L</sub> only contains singly-labeled examples. US<sup>α</sup><sub>X</sub> will always pick an unlabeled example x<sub>u</sub> over a singly-labeled example x<sub>l</sub>, if α is set such that  $(1 - α)M_A(x_l) + αM_L(x_l) < (1 - α)M_A(x_u) + αM_L(x_u)$  for all x<sub>l</sub>, x<sub>u</sub> pairs. This condition holds true when  $α > \frac{M_A(x_l) - M_A(x_u)}{M_A(x_l) - M_A(x_u) + M_L(x_u) - M_L(x_l)}$  for all x<sub>l</sub>, x<sub>u</sub> pairs. We set α' = sup<sub>xl∈X<sub>L</sub>, x<sub>u∈X<sub>L</sub></sub>  $\frac{0.69}{0.69 + (M_L(x_u) - M_L(x_l))}$ . Note that since x<sub>l</sub> is singly-labeled and will have lower label entropy compared to x<sub>u</sub>, which is unlabeled,  $M_L(x_u) > M_L(x_l)$ . Therefore, α' < 1.0. Also, since M<sub>A</sub> is an entropy of a binary random variable,  $|M_A(x_l) - M_A(x_u)| < 0.69$ . Combining all these facts, the condition holds true when  $α > α' > \frac{0.69}{0.69 + (M_L(x_u) - M_L(x_l))}$  for all x<sub>l</sub>, x<sub>u</sub> and  $α < \frac{0.69}{0.69 - (M_L(x_u) - M_L(x_l))} > 1.0$  for all x<sub>l</sub>, x<sub>u</sub>. Since all unlabeled examples have the same label uncertainty and because US<sup>α</sup><sub>X</sub> always picks an unlabeled example, the example it picks will be determined based on the classifier's uncertainty, just as in US<sub>X<sub>U</sub></sub>. Now, since both US<sup>α</sup><sub>X</sub> and US<sub>X<sub>U</sub></sub> start with X<sub>L</sub> = Ø, by induction, X<sub>L</sub> will only ever contain singly-labeled examples, and so these two strategies are equivalent.</sub>

## 2 Theorem 2

Let  $P_{\mathcal{A}}(h^*(x_i) = y)$  denote the probability currently output by learning algorithm,  $\mathcal{A}$ , that  $h^*(x_i) = y$ . For ease of notation and clarity, we denote with shorthand  $p_0(x_i) = P_{\mathcal{A}}(h^*(x_i) = 0)$  and  $p_1(x_i) = P_{\mathcal{A}}(h^*(x_i) = 1)$ . Because we are considering a setting with no noise, the total expected impact of a point  $x_i$  is  $\sum_{y \in \mathcal{Y}} p_y(x_i) \psi_y(x_i)$ .

#### Lemma 1. If

$$\begin{aligned} I. \ (\psi_1(x_i) - \psi_0(x_i)) &\geq \frac{\psi_0(x_j) - \psi_0(x_i) + (\psi_1(x_j) - \psi_0(x_j))p_1(x_j)}{p_1(x_i)}, \text{ or} \\ 2. \ (\psi_0(x_i) - \psi_1(x_i)) &\geq \frac{\psi_1(x_j) - \psi_1(x_i) + (\psi_0(x_j) - \psi_1(x_j))p_0(x_j)}{p_0(x_i)}, \text{ or} \\ 3. \ (\psi_0(x_i) - \psi_1(x_i)) &\geq \frac{\psi_0(x_j) - \psi_1(x_i) + (\psi_1(x_j) - \psi_0(x_j))p_1(x_j)}{p_0(x_i)}, \text{ or} \\ 4. \ (\psi_1(x_i) - \psi_0(x_i)) &\geq \frac{\psi_1(x_j) - \psi_0(x_i) + (\psi_0(x_j) - \psi_1(x_j))p_0(x_j)}{p_1(x_i)}, \end{aligned}$$

then, the total expected impact of  $x_i$  is at least as large as that of  $x_j$ :  $\sum_{y \in \mathcal{Y}} p_y(x_i) \psi_y(x_i) \ge \sum_{y \in \mathcal{Y}} p_y(x_i) \psi_y(x_i)$  $\sum_{y \in \mathcal{Y}} p_y(x_j) \psi_y(x_j).$ 

*Proof.* For condition (1), we have that  $\sum_{y \in \mathcal{Y}} p_y(x_i) \psi_y(x_i)$ 

$$\begin{split} &= p_0(x_i)\psi_0(x_i) + p_1(x_i)\psi_1(x_i) \\ &= p_1(x_i)(\psi_1(x_i) - \psi_0(x_i)) + \psi_0(x_i) \\ &\geq p_1(x_i)\frac{\psi_0(x_j) - \psi_0(x_i) + (\psi_1(x_j) - \psi_0(x_j))p_1(x_j)}{p_1(x_i)} + \psi_0(x_i) \\ &= \psi_0(x_j) - \psi_0(x_i) + (\psi_1(x_j) - \psi_0(x_j))p_1(x_j) + \psi_0(x_i) \\ &= \psi_0(x_j) + (\psi_1(x_j) - \psi_0(x_j))p_1(x_j) \\ &= \sum_{y \in \mathcal{Y}} p_y(x_j)\psi_y(x_j). \end{split}$$

Proofs of conditions (2-4) proceed similarly.

#### 2.1 **Proof of Theorem 2**

*Proof.* Let  $x_i$  be the point chosen by uncertainty sampling. We prove the theorem by showing that  $\mathcal{P}$  satisfies the conditions of Lemma 1 for  $x_i$  and all candidate points  $x_j$ . We prove the case when  $x_i > t$  and  $x_j > t$  (then  $x_j > x_i$ , because otherwise  $x_i$  would not have been picked by uncertainty sampling). The 3 other cases proceed in exactly the same manner, because of symmetry. Let us also assume that  $x_i < x_{\leq}$ , because if not, the theorem holds trivially, because all points will have 0 impact. Let t be the currently learned threshold,  $x_{\leq} = \max\{x \in \mathcal{X}_L : x < t\}$  denote the current greatest labeled example less than the threshold, and  $x_{>} = \min\{x \in \mathcal{X}_{L} : x > t\}$  denote the current smallest labeled example greater than the threshold. Now we define  $d_{*_1,*_2}$  to be the proportion of points in  $\mathcal{X}$  between points  $*_1$  and  $*_2$ . Precisely,

$$d_{*_1,*_2} = P_{x \in \mathcal{D}}(x \in \{x : *_1 < x < *_2\}).$$

For example,  $d_{x_{<},t}$  is the proportion of points between  $x_{<}$  and t. We also know that  $\begin{aligned} d_{x_j,t} &\geq d_{x_i,t} \text{ because } x_j > x_i. \text{ Now we show that condition 1 of Lemma 1 is satisfied,} \\ \text{that } (\psi_0(x_i) - \psi_1(x_i)) &\geq \frac{\psi_0(x_j) - \psi_0(x_i) + (\psi_1(x_j) - \psi_0(x_j))p_1(x_j)}{p_1(x_i)} \text{ for all } x_j > x_i \\ \text{We have that for any } x_j, \psi_0(x_j) &= d_{t,x_j} + \frac{d_{x_j,x_j}}{2} \text{ and } \psi_1(x_j) = d_{x_{<},x_j} - (\frac{d_{x_{<},x_j}}{2} + d_{x_{<},x_{<}}) \\ \text{Therefore } d_{x_{<},x_{<}} = (x_i) + (x_i) + (x_i) \\ \text{Therefore } d_{x_{<},x_{<}} = (x_i) + (x_i) + (x_i) + (x_i) + (x_i) \\ \text{Therefore } d_{x_{<},x_{<}} = (x_i) + (x_i)$ 

 $d_{t,x_j}$ ). Therefore,  $\psi_1(x_j) - \psi_0(x_j)$ 

$$= d_{x_{<},x_{j}} - \left(\frac{d_{x_{<},x_{j}}}{2} + d_{t,x_{j}}\right) - \left(d_{t,x_{j}} + \frac{d_{x_{j},x_{>}}}{2}\right)$$
$$= d_{x_{<},t} - \frac{d_{x_{<},x_{j}}}{2} - \frac{d_{x_{j},x_{>}}}{2} - d_{t,x_{j}}$$
$$= d_{x_{<},t} - d_{d_{<},t} - d_{t,x_{j}}$$
$$= -d_{t,x_{j}}.$$

Next, we have that  $\frac{\psi_0(x_j)-\psi_0(x_i)+(\psi_1(x_j)-\psi_0(x_j))p_1(x_j)}{p_1(x_i)}$ 

$$= \frac{d_{t,x_j} + \frac{d_{x_j,x_j}}{2} - (d_{t,x_i} + \frac{d_{x_i,x_j}}{2}) - d_{t,x_j}p_1(x_j)}{p_1(x_i)}$$
  
= 
$$\frac{d_{x_i,x_j} - 0.5(d_{x_i,x_j}) - d_{t,x_j}p_1(x_j)}{p_1(x_i)}$$
  
= 
$$\frac{0.5d_{x_i,x_j} - d_{t,x_j}p_1(x_j)}{p_1(x_i)}.$$

And then,

$$\frac{0.5d_{x_i,x_j} - d_{t,x_j}p_1(x_j)}{p_1(x_i)} \leq -d_{t,x_i} = (\psi_1(x_i) - \psi_0(x_j))$$

$$\begin{array}{c} & \\ & \\ & \\ 0.5d_{x_i,x_j} - d_{t,x_j}p_1(x_j) \leq -d_{t,x_i}p_1(x_i) \\ & \\ & \\ & \\ & \\ 0.5d_{x_i,x_j} \leq d_{t,x_j}p_1(x_j) - d_{t,x_i}p_1(x_i) \\ & \\ & \\ & \\ & \\ 0.5d_{x_i,x_j} \leq d_{t,x_j}[p_1(x_i) + \beta] - d_{t,x_i}p_1(x_i), \quad \beta = p_1(x_j) - p_1(x_i) \\ & \\ & \\ & \\ & \\ & \\ & \\ & \\ & \\ 0.5d_{x_i,x_j} \leq p_1(x_i)d_{x_i,x_j} + \beta d_{t,x_j}, \quad \beta = p_1(x_j) - p_1(x_i)
\end{array}$$

 $\beta > 0$  because  $x_j > x_i$ , and  $p_1(x_i) > 0.5$  because  $x_i > t$ , and therefore  $0.5d_{x_i,x_j} \le p_1(x_i)d_{x_i,x_j} + \beta d_{t,x_j}$ , and the theorem is proved.