

# sensorSift

Balancing Utility and Privacy in Sensor Data

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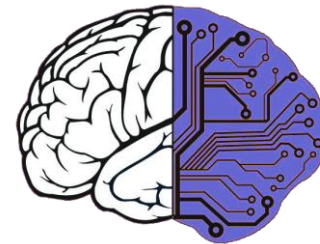
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# Rise of {Sensors + AI}

- People expect rich computational experiences to be available in every context

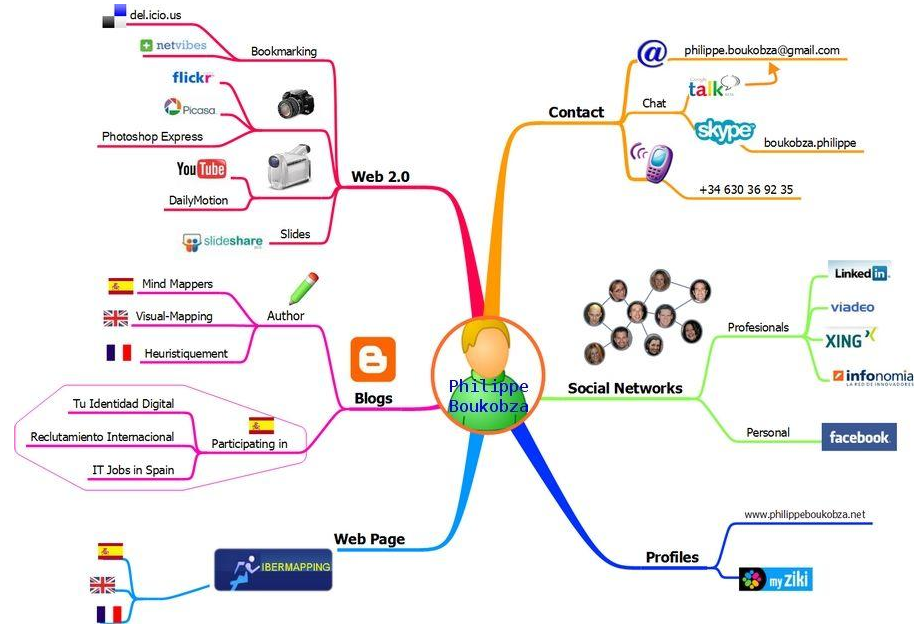
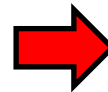
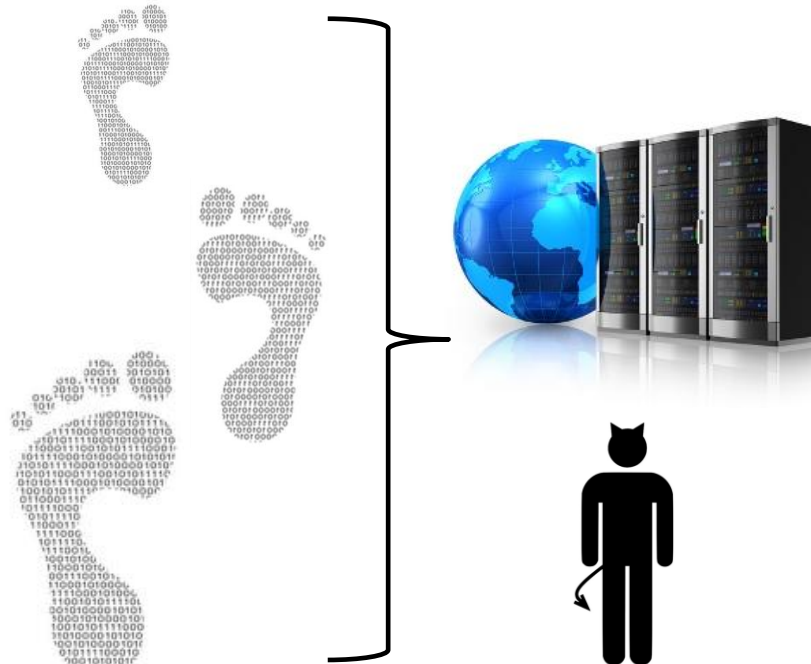


- As a result, our world is increasingly visible to intelligent computers
  - Minimal cost of sensors
  - Cheap computational power
  - Advances in machine reasoning



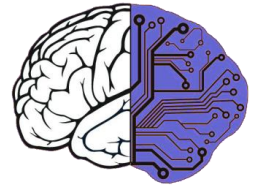
# Lack of Balance

- There are many **benefits** of smart-sensor applications
  - **Increased Productivity, Connectivity, and Interactivity**
- However there are also potential **negative** effects
  - **Privacy Risks**



# Goals

- Develop a quantitative framework for **balancing** privacy and utility in smart sensing applications.
  - Empower users with privacy guarantees
  - Applications retain functionality
- Evaluate the quality of our framework against state of the art machine inference
- Offer a flexible solution so that the future demands of users/applications can be supported

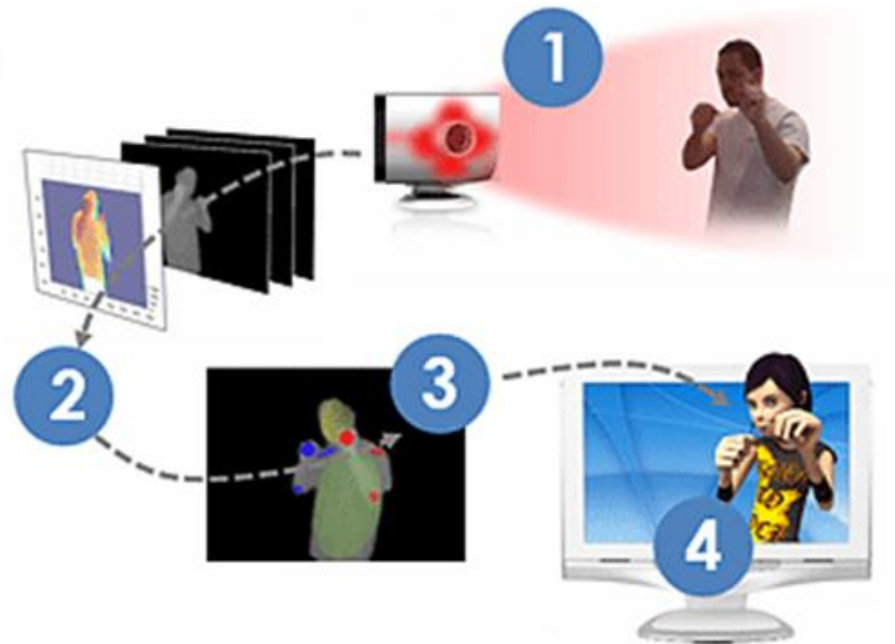


# Usage Model 1

Sensor data releases to smart applications are often **risk carrying**

**Common Practice:** Sensor releases all of the raw data to an Application (e.g. MS Kinect)

**Sensor** :{ **1** sensor data } → **App** :{ **2** feature extract, **3** classify, **4** logic }

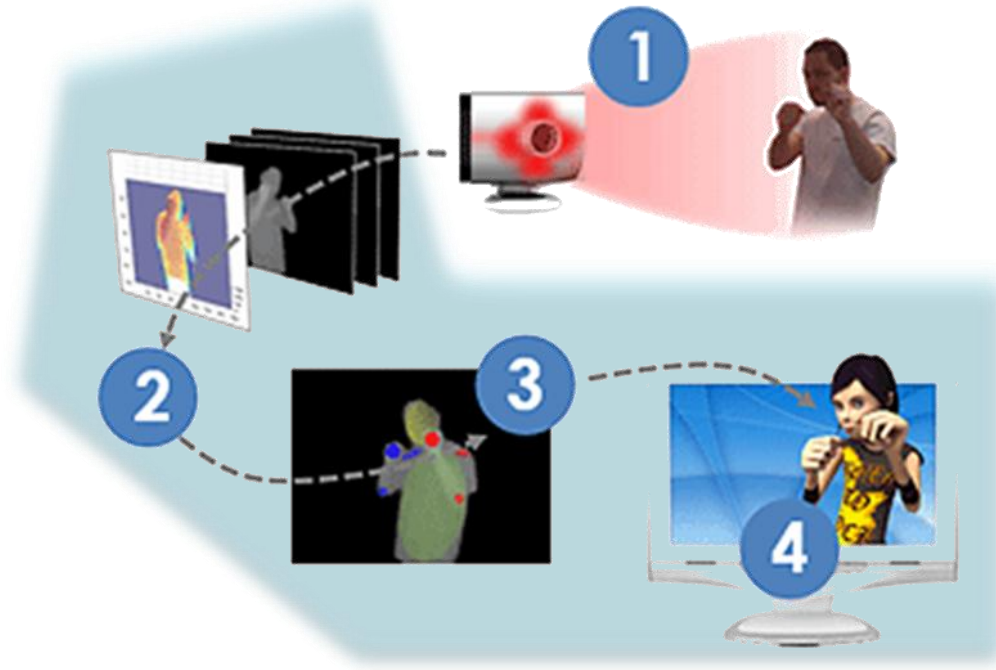


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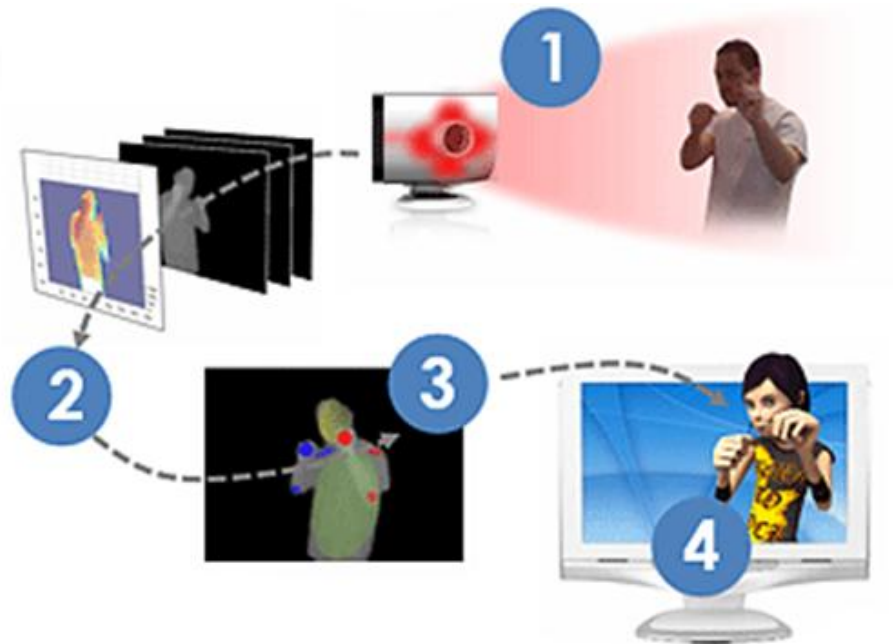
++ INNOVATION  
- PRIVACY

# Usage Model 2

Sensor data releases to smart applications are often **arbitrarily stifling**

**Common Practice:** Only a predefined set of features is available to an Application (e.g., iOS)

**Platform** :{ 1 sensor data , 2 feature extract, 3 classify } → **App** :{4 logic}

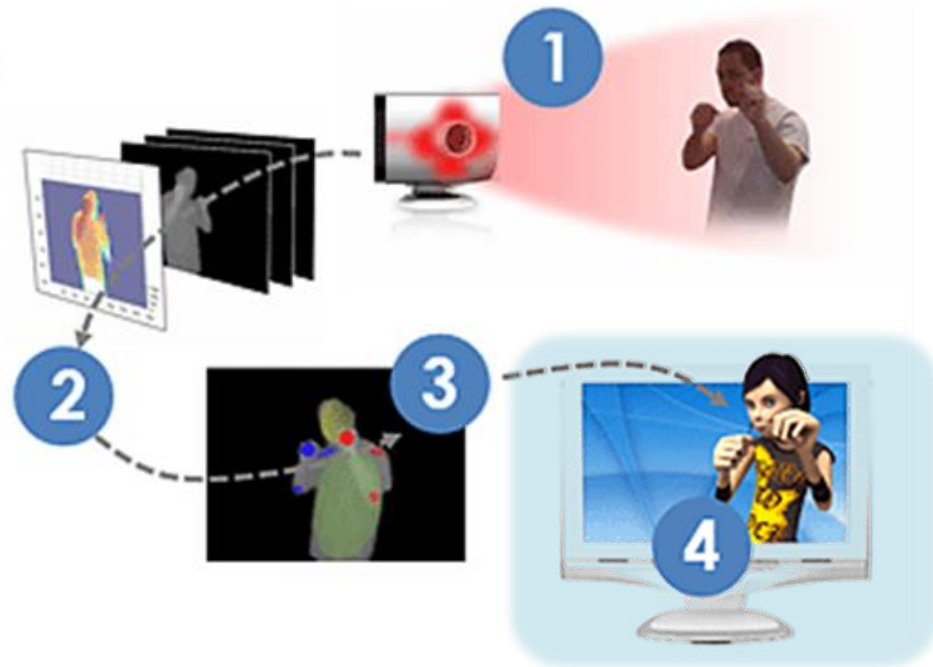


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- INNOVATION  
++ PRIVACY



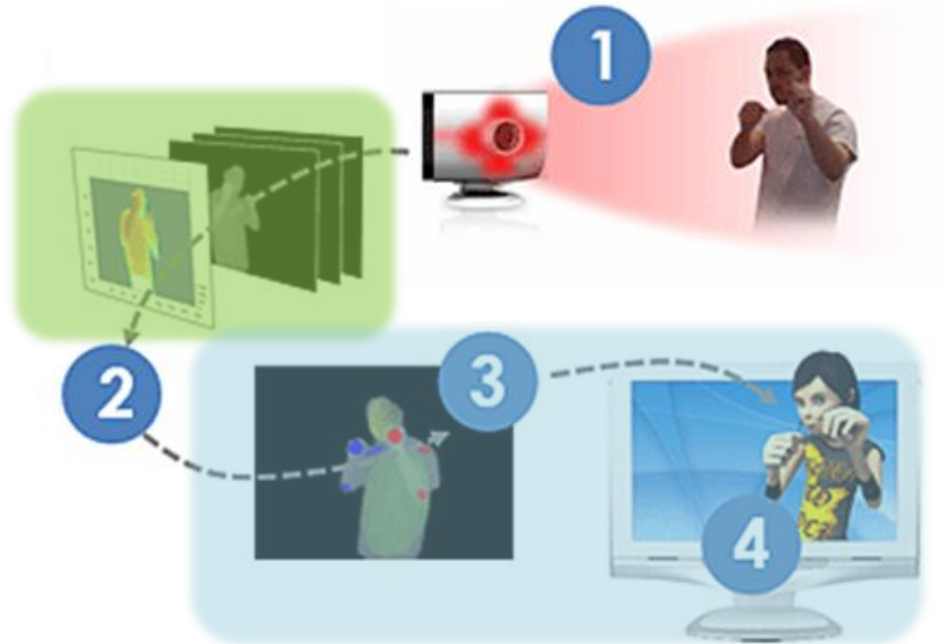
# Solution

- Users choose what attributes to keep **private**
- Applications can request non-private (**public**) attributes
  - Public attributes can be invented!

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- Users choose what attributes to keep **private**
  - Applications can request non-private (**public**) attributes
    - Public attributes can be invented!
- } **POLICY**
- We transform (sift) sensor data to reveal the **public** but hide the **private** attributes

**Plat.** : { **1** sensor data, **2** sift features } → **App** { **3** classify, **4** logic }



+ INNOVATION  
+ PRIVACY

# Evaluation Context



**ATTRIBUTES:** visually describable characteristics about a face

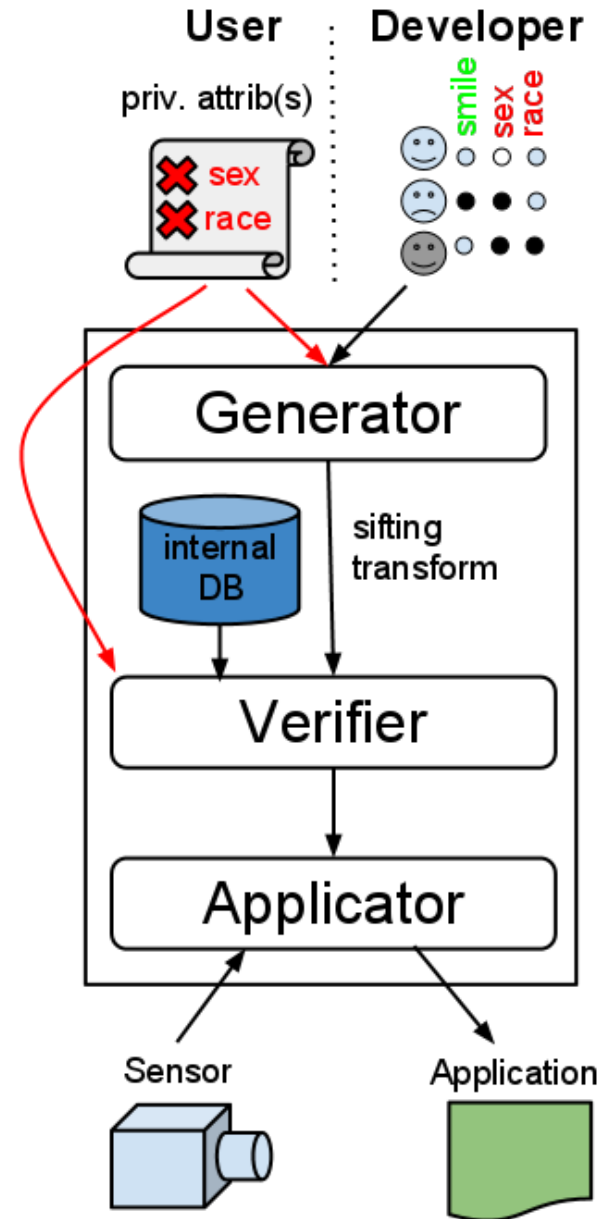
# System Overview

## Scenario:

- **USER:** I don't want apps. to have knowledge about my **race** and **gender**
- **APPLICATION:** Is the user **smiling**?
  - > **POLICY:** **PRIVATE** {**race, gender**}, **PUBLIC** {**smiling**}

## System:

1. Generates Sift
2. Verifies Sift
3. Applies Verified Sift



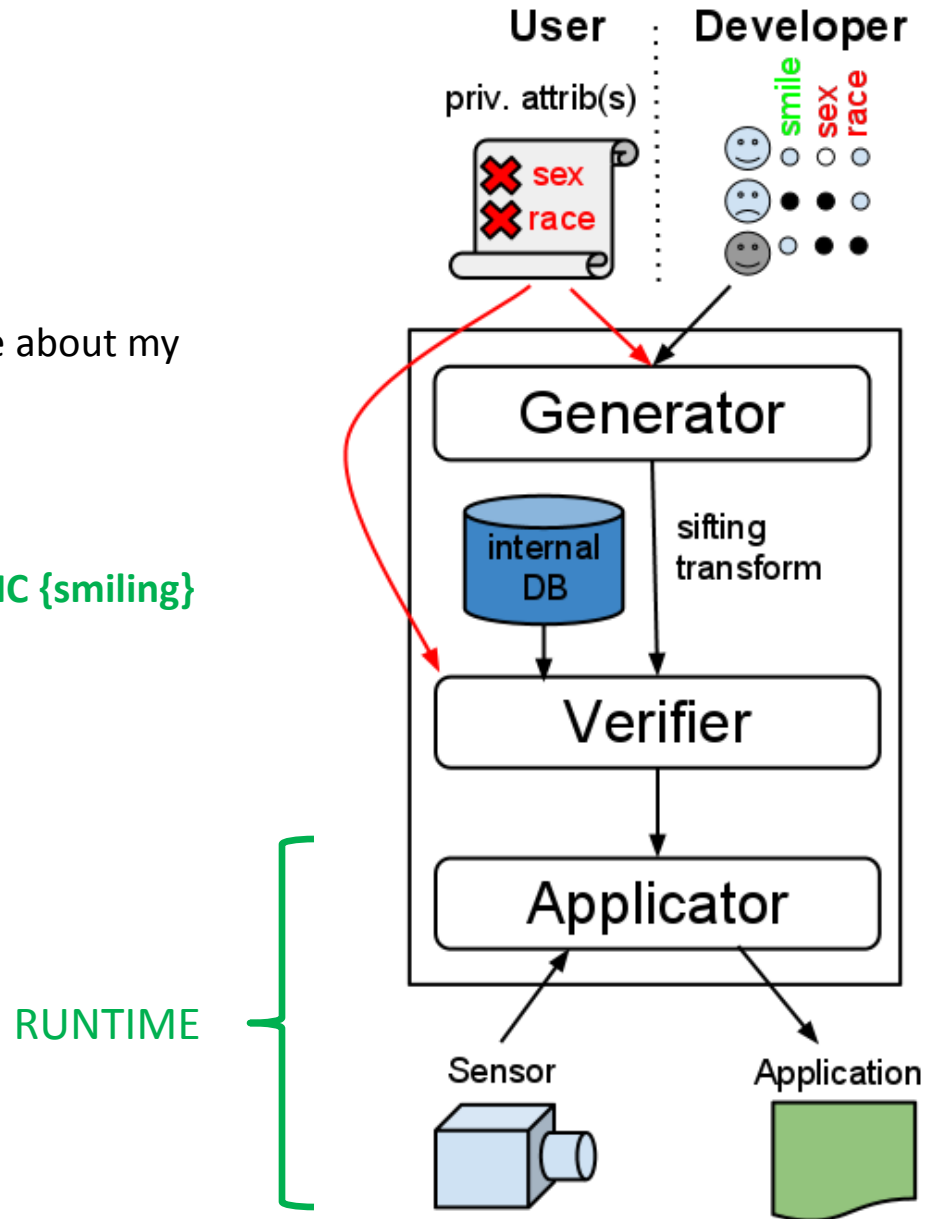
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# Generating Sifts

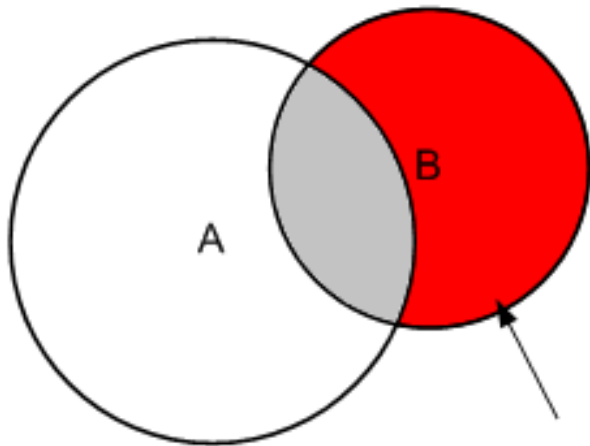
database

Intuitively, sifting finds the safe region(s) in feature space which are in the public feature set **B** but not in the private one **A**.

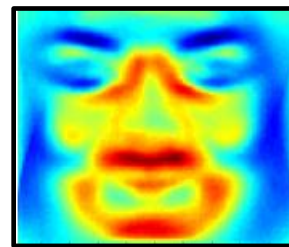
feature regions are based on a large database of sensor samples

**A = eyewear (private)**

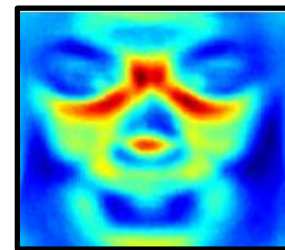
**B = gender (public)**



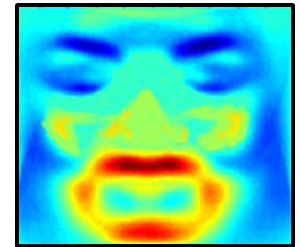
**OVERLAP  
(UNSAFE)**



**gender**



**eyewear**



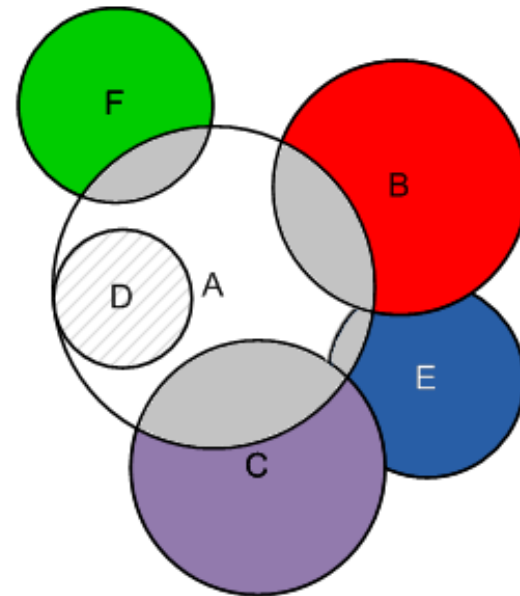
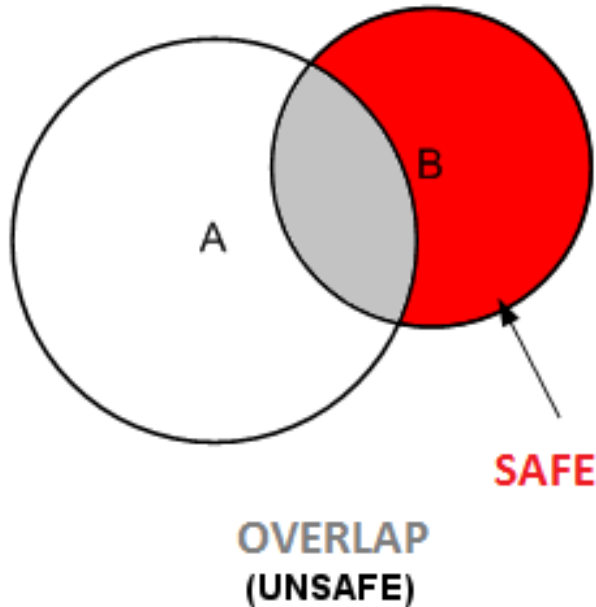
**safe region**



# Generating Sifts

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**A = eyewear (private)**  
**B = gender (public)**



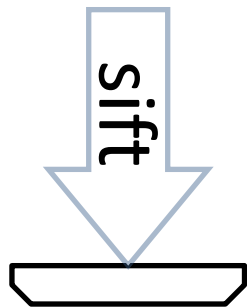
Safe region(s) may not always exist for certain attribute correlations.

# Sifting Details

$X$  = Raw Features  
 $X'$  = Sifted Features



$X_n, n > 100k$



$X'_n, n \sim 5$

sifting in detail

## PPLS

**Algorithm 1** Privacy Partial Least Squares

1. Set  $j = 0$  and cross-product  $S_j = X^\top Y^+$
2. if  $j > 0$ ,  $S_j = S_{j-1} - P(P^\top P)^{-1} P^\top S_{j-1}$
3. Compute the largest eigenvector  $w_j$ :  
 $[S_j^\top S_j - X^\top Y^- (Y^-)^\top X] w_j = \lambda w_j$
4. Compute  $p_j = \frac{X^\top X w_j}{w_j^\top X^\top X w_j}$
5. If  $j = k$ , stop; otherwise let  $P = [p_0, \dots, p_j]$  and  $j = j + 1$  and go back to step 2

$$\text{find } \max_w \left[ \text{cov}(Xw, Y^+)^2 - \lambda * \text{cov}(Xw, Y^-)^2 \right]$$

$Y^+$  = labels of public attribute(s)

$Y^-$  = labels of private attribute(s)



# Performance Metrics

- A successful sift will have low scores on both **PubLoss** and **PrivLoss**
  - **PubLoss**: Decrease in sifted public attribute classification accuracy relative to the achievable accuracy using raw (unsifted) data.
  - **PrivLoss**: Gain in sifted private attribute classification accuracy relative to chance.

$$PubLoss = ML_m(X, Y^+) - ML_m(PM_{Y^+, Y^-}(X, K), Y^+)$$

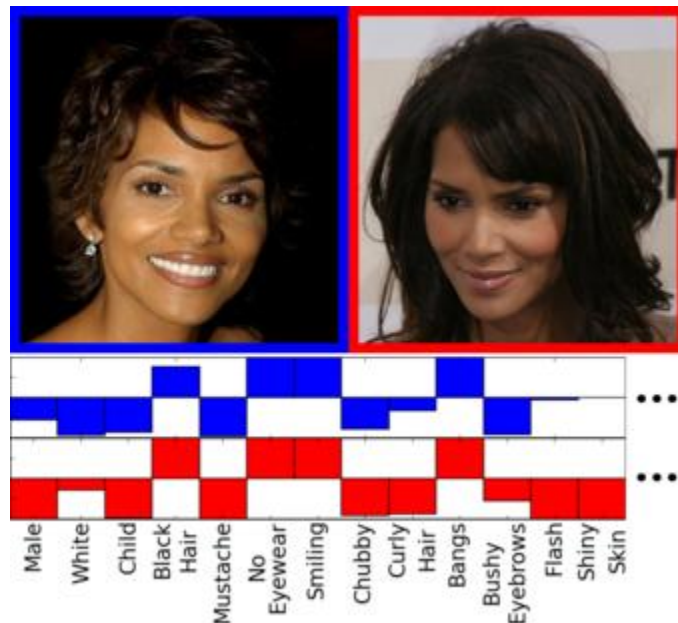
$$PrivLoss = ML_m(PM_{Y^+, Y^-}(X, K), Y^-) - .5$$

\*Classifiers : Linear Support Vector Machine (SVM), Non-Linear SVM, Neural Network, Random Forest, kNearest Neighbors

# Dataset & Attributes

PubFig Database ~45,000 face images of 200 celebrities, 72 attributes

**Attributes** are [binary] labels for visually describable characteristics,



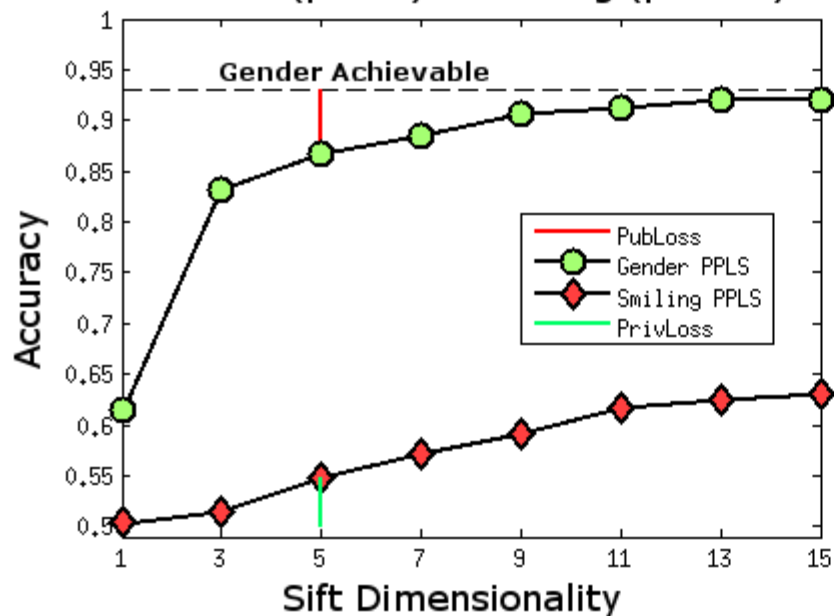
## Attribute Clusters

Wavy Hair  
Arched Eyebrows  
Wearing Lipstick  
Blond Hair  
Youth

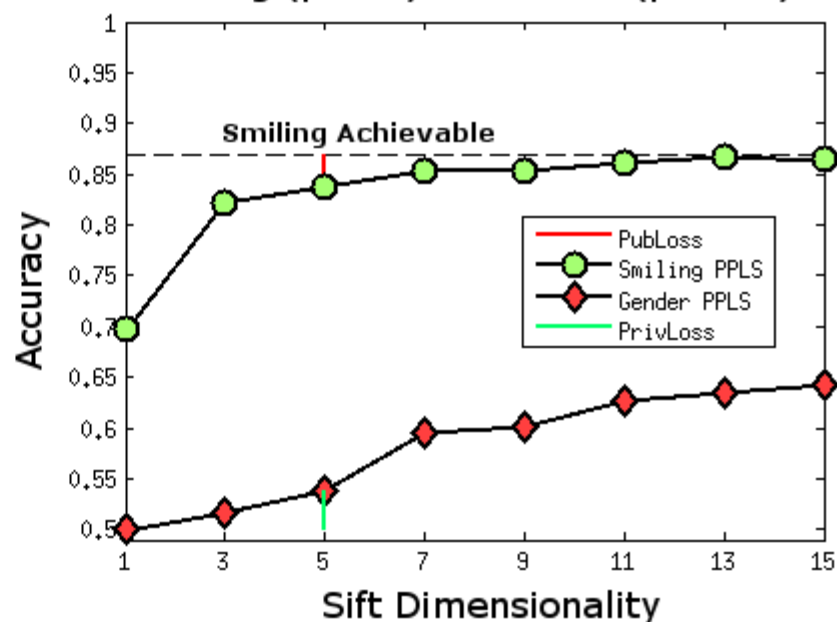
Attractive Female

Male - **M**, Attractive Female - **AF**, White - **W**,  
Youth - **Y**, Smiling - **S**, Frowning - **F**, No Eyewear - **nE**,  
Obstructed Forehead - **OF**, No Beard - **nB**, and Outdoors - **O**.

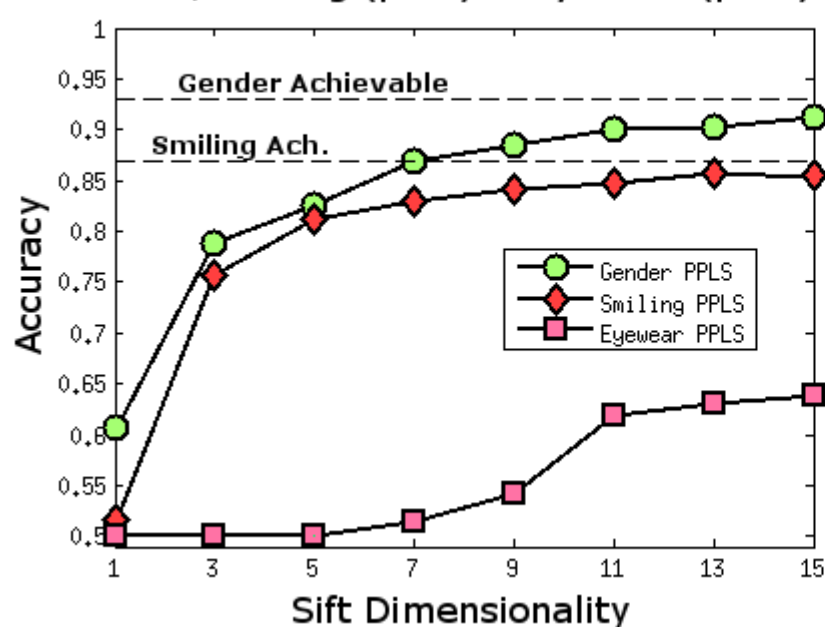
Gender (public) :: Smiling (private)



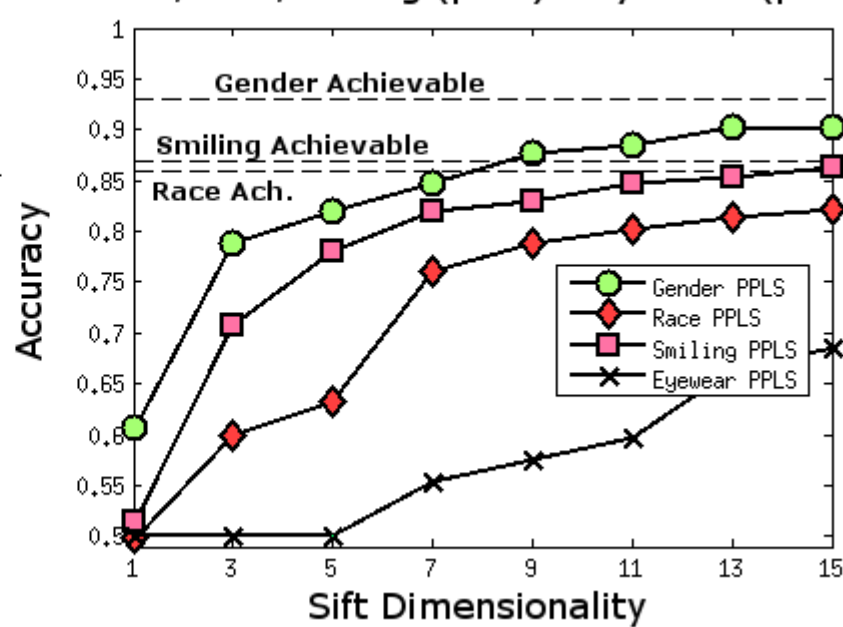
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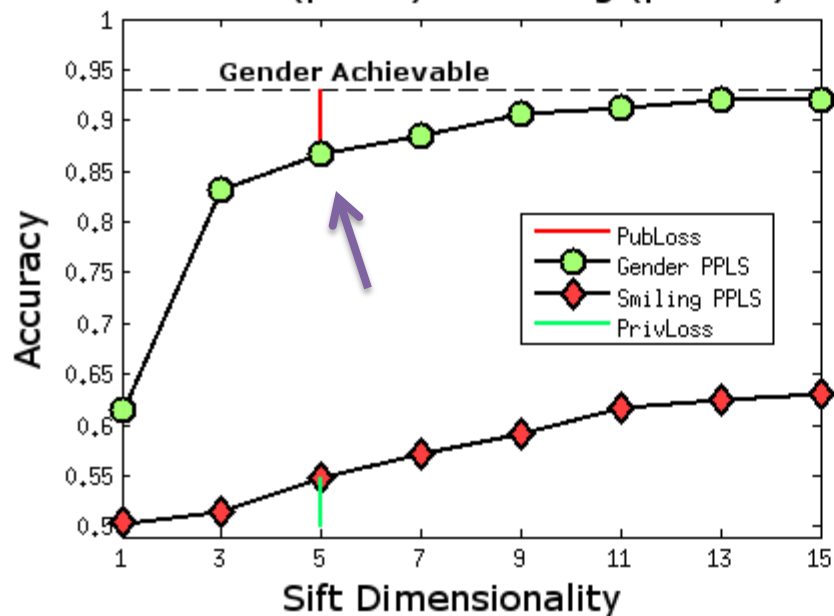
Gender, Smiling (pub.) :: Eyewear (priv.)



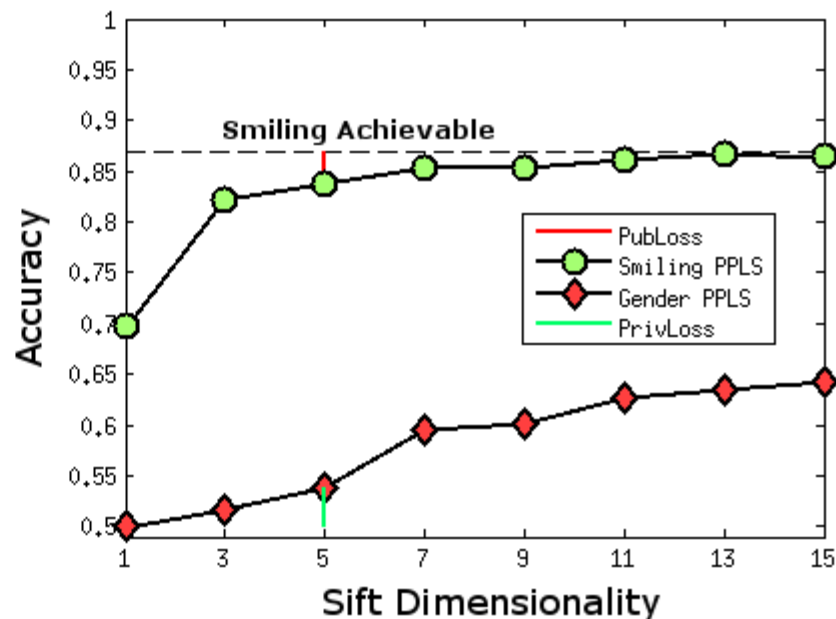
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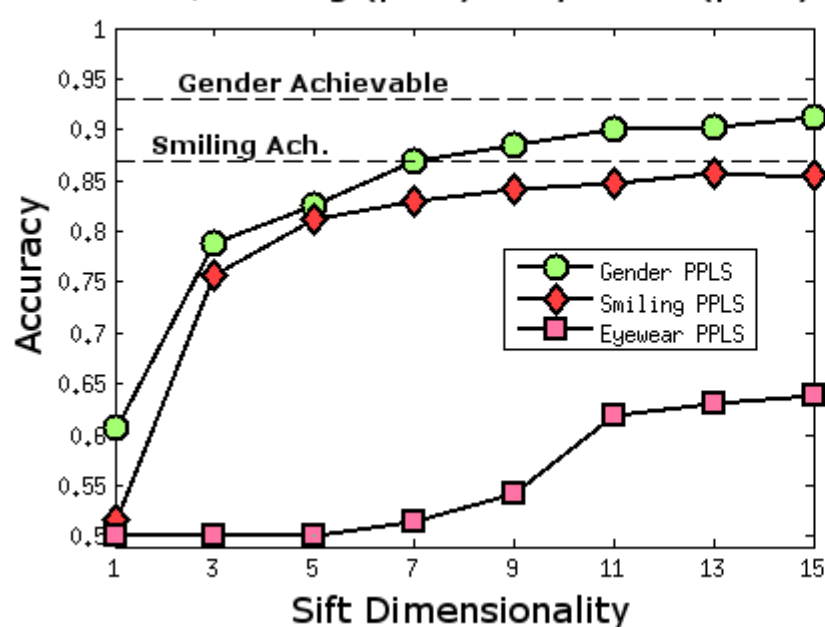
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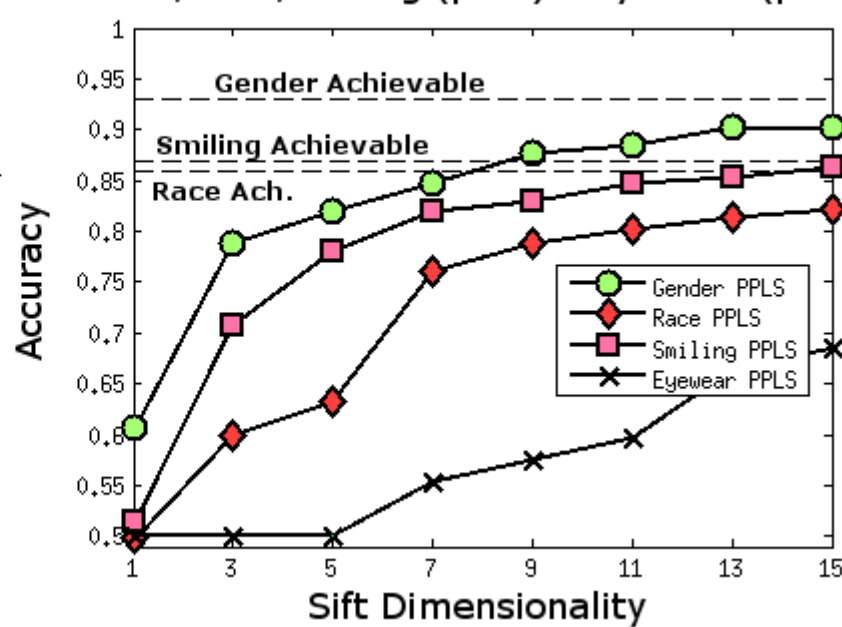
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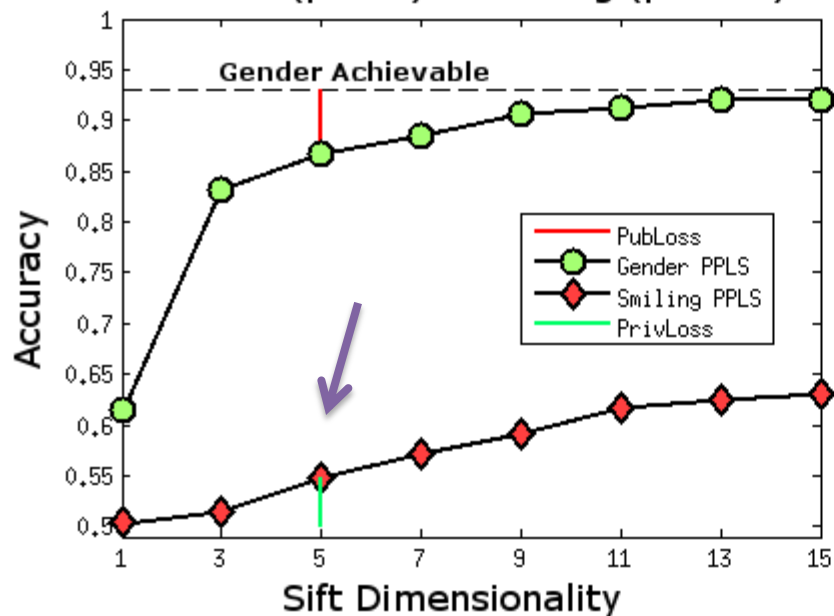
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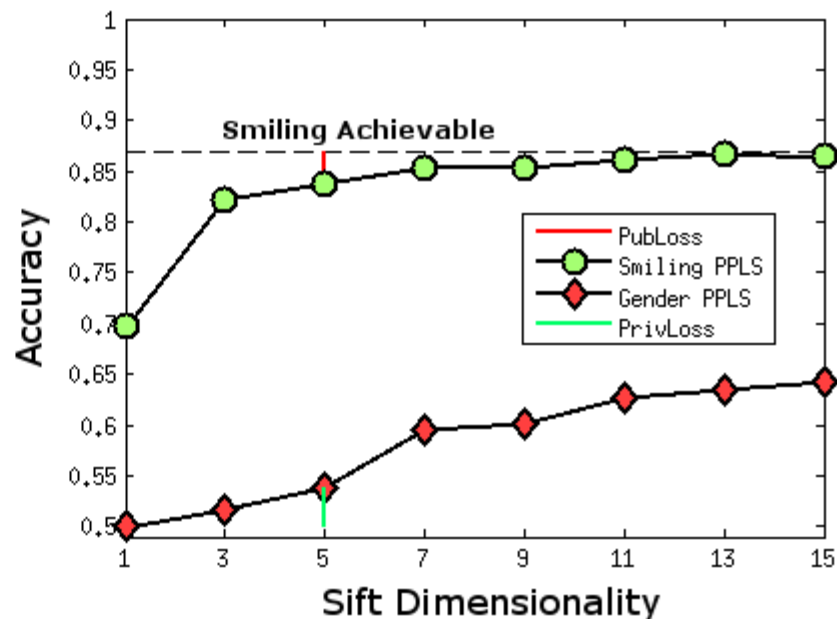
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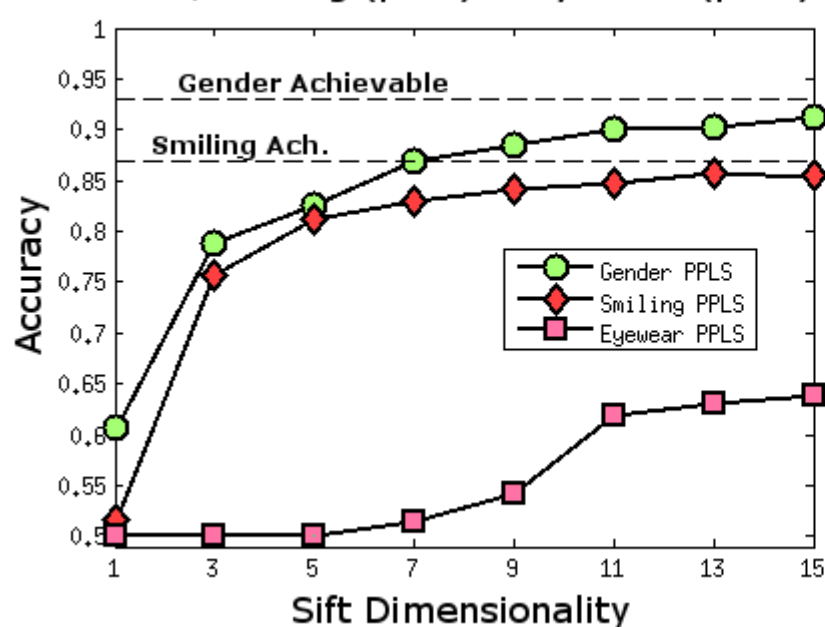
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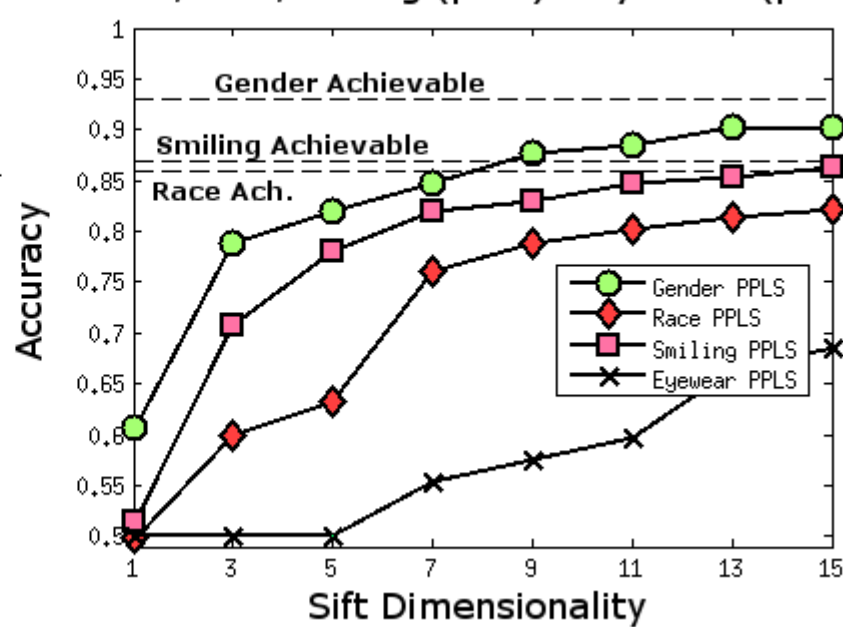
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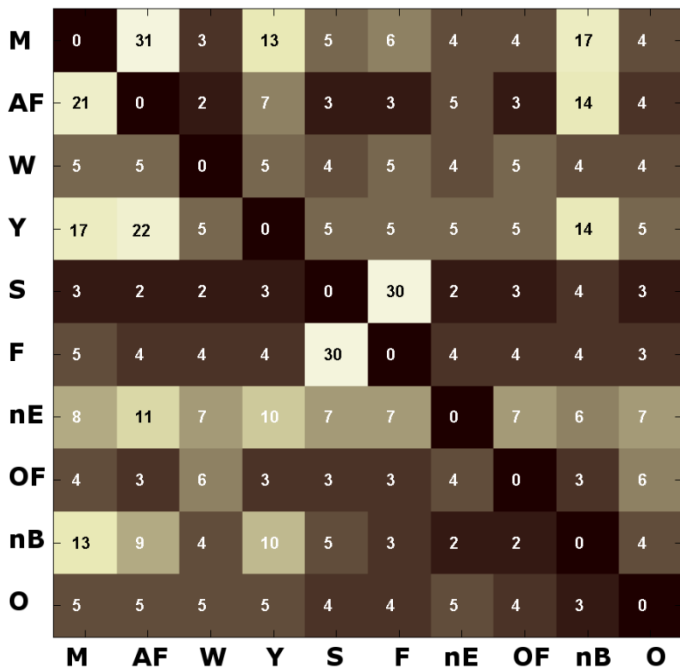
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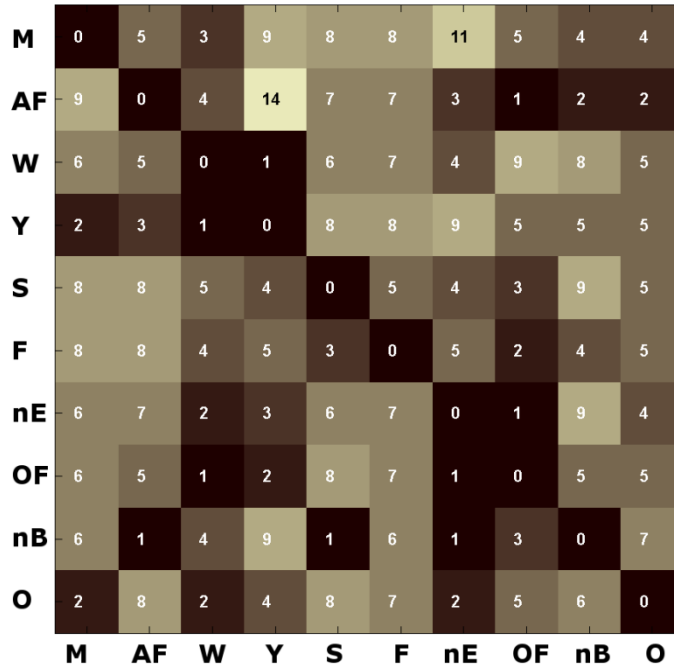
Gender, Race, Smiling (pub.) :: Eyewear (priv.)



### PubLoss



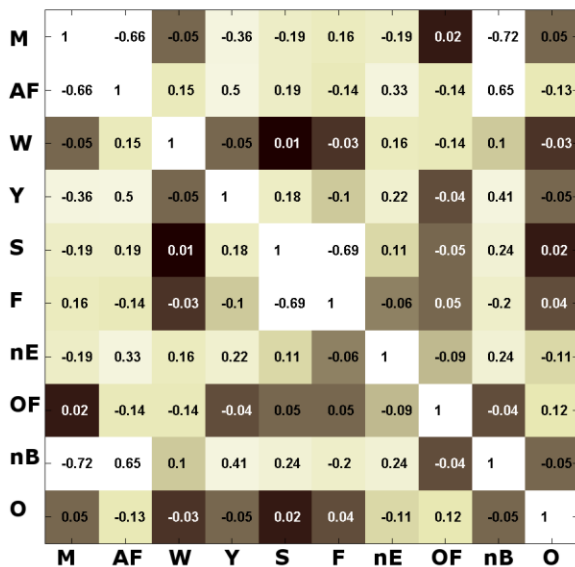
### PrivLoss



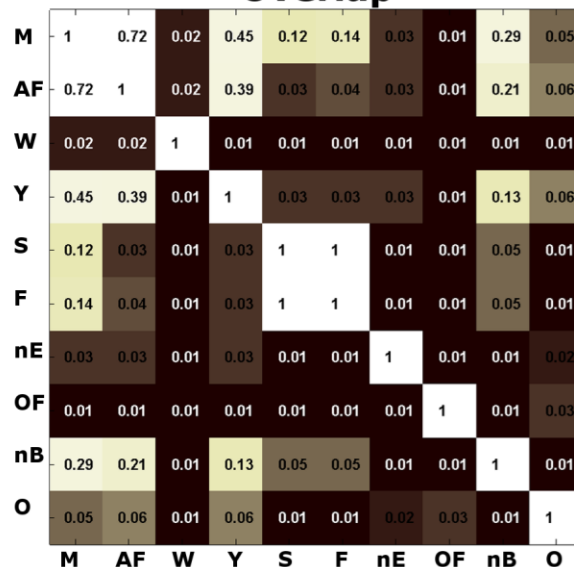
- M** - Male
- F** - Attr. Female
- W** - White
- Y** - Youth
- S** - Smiling
- F** - Frowning
- nE** - No Eyewear
- OF** - Obstr. Forehd.
- nB** - No Beard
- O** - Outdoors

### private attribute

### Correlation



### Overlap



# Conclusions

- We proposed a theoretical framework for quantitative balance between utility and privacy through policy based control of sensor data exposure.
- In our analysis we found promising results when we evaluated the PPLS algorithm in the context of automated face understanding.
- The algorithm we introduce is general, as it exploits the statistical properties of the data; and in the future it would be exciting to evaluate SensorSift in other sensor contexts.
- Available as Open Source!

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# Thanks!



Liefeng



Xiaofeng



Jaeyeon



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SecLab @ UW



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**Pervasive Computing**

Microsoft®  
**Research**



Questions?

<http://homes.cs.washington.edu/~miro/sensorSift>