

Introduction to LS/LS+

Laura Elisa Celis

University of Washington

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Cutting Planes Methods

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- Consider feasibility instead of optimization.

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Given a 0-1 integer program:

- Consider feasibility instead of optimization.
- Relax given integer linear program and consider polytope satisfying constraints.
- Transform through “cuts” to integral hull of valid solutions.

Cone Formulation of LS

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Definition

K is the cone of feasible points given by the linear program.

Goal:

Determine if the set of integer points in K is nonempty.

Cone Formulation of LS

Definition

$x \in N(K)$ if and only if there is a matrix Y such that:

- The first row of Y is x .
- The diagonal of Y is x (corresponds to $x_i^2 = x_i$).
- Y is symmetric ($Y_{ij} = Y_{ji}$ corresponds to $x_i x_j = x_j x_i$).
- All rows of Y are in K (corresponds to multiplying by x_i).
- All $Y_0 - Y_i$ are in K (corresponds to multiplying by $1 - x_i$).

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Goal:

Show that $N(K)$ is stronger than K .

Validity of Cuts

Theorem

If K^0 is convex hull of 0-1 vectors in K , then $K^0 \subseteq N(K) \subseteq K$.

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Proof

Trivially, $N(K) \subseteq K$.

If x is a 0-1 vector in K^0 , the matrix $Y = xx^T$ satisfies all necessary constraints.

Proof

$$Y = \mathbf{x}\mathbf{x}^T = \begin{pmatrix} x_0x_0 & \cdots & x_0x_i & \cdots & x_0x_n \\ \vdots & \ddots & & & \vdots \\ x_ix_0 & & x_ix_i & & x_ix_n \\ \vdots & & & \ddots & \vdots \\ x_nx_0 & \cdots & x_nx_i & \cdots & x_nx_n \end{pmatrix}$$

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- Each row is in K ($x_i \cdot x$)

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- The first row is x
- The diagonal is x ($x_i^2 = x_i$)
- Symmetric ($x_i x_j = x_j x_i$)
- Each row is in K ($x_i \cdot x$)
- $Y_0 - Y_i$ is in K ($((1 - x_i) \cdot x)$).

Strength of Cuts

Theorem

n rounds of LS give the convex hull of 0-1 solutions (i.e. $K^0 = N^n(K)$).

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From before, $K^0 \subseteq N(K) \subseteq K$.

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n rounds of LS give the convex hull of 0-1 solutions (i.e. $K^0 = N^n(K)$).

Proof ($K^0 \subseteq N^n(K)$)

From before, $K^0 \subseteq N(K) \subseteq K$.

Hence, $K^0 \subseteq N^k(K)$ for all k .

Strength of Cuts

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Theorem

- $v \in H_i$ if and only if $v_i = 0$
- $v \in G_i$ if and only if $v_i = v_0$
- $F_i = H_i \cup G_i$

Then, $N(K) \subseteq \text{cone}(K \cap F_i)$.

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Proof

Let $x \in N(K)$, with corresponding Y .

Let Y_i be the i th row of Y .

Strength of Cuts

Proof (cont.)

$$\left(\begin{array}{cc|c|cc} Y_{00} & \cdots & Y_{0i} & \cdots & Y_{0n} \\ \vdots & \ddots & & & \vdots \\ \hline Y_{i0} & & Y_{ii} & & Y_{in} \\ \hline \vdots & & & \ddots & \vdots \\ Y_{n0} & \cdots & Y_{ni} & \cdots & Y_{nn} \end{array} \right)$$

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- $Y_{ii} = Y_{i0}$ implies $Y_i \in G_i$.

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- $Y_i \in K \cap G_j$.
- $(Y_0 - Y_i)_i = Y_{0i} - Y_{ii} = 0$
implies $(Y_0 - Y_i) \in H_i$.

Strength of Cuts

Proof (cont.)

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- $Y_i \in K \cap G_i$.
- $(Y_0 - Y_i) \in K \cap H_i$,

Strength of Cuts

Proof (cont.)

So:

$$x = Y_0$$

Strength of Cuts

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So:

$$\begin{aligned}x &= Y_0 \\ &= (Y_0 - Y_i) + Y_i\end{aligned}$$

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Strength of Cuts

Proof (cont.)

So:

$$\begin{aligned}x &= Y_0 \\ &= (Y_0 - Y_i) + Y_i \\ &\in (K \cap H_i) + (K \cap G_i) \\ &\subseteq \text{cone}(K \cap (H_i \cup G_i))\end{aligned}$$

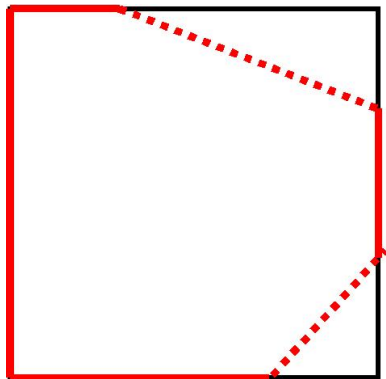
Strength of Cuts

Proof (cont.)

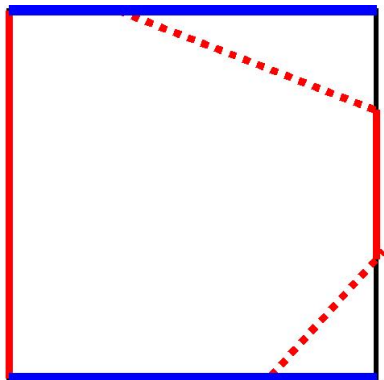
So:

$$\begin{aligned}x &= Y_0 \\ &= (Y_0 - Y_i) + Y_i \\ &\in (K \cap H_i) + (K \cap G_i) \\ &\subseteq \text{cone}(K \cap (H_i \cup G_i)) \\ &= \text{cone}(K \cap F_i)\end{aligned}$$

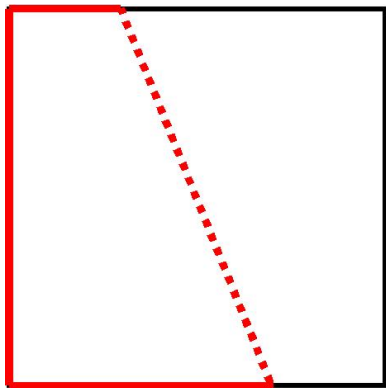
Example



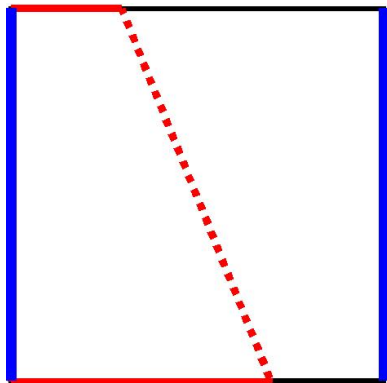
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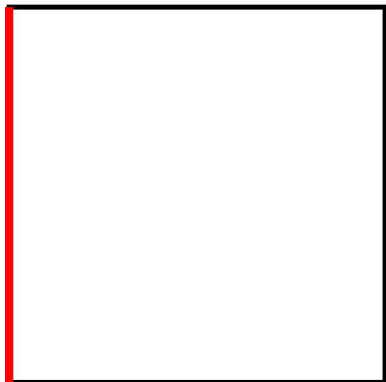
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Conclusion

In terms of cones:

$$N^t(K) = N(N^{t-1}(K)) \subseteq \text{cone}(N^{t-1}(K) \cap F_t)$$

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Since $\cap_1^n F_t$ is the vertices of hypercube,
 $N^n(K) \subseteq K^0$.

LS+

LS+ strengthens an LP in the same way as LS,
also adds squares of linear terms.

Cone Formulation of LS+

Let $x \in N_+(K)$ if and only if there is a matrix Y such that:

- The first column of Y is x
- The diagonal of Y is x
- Y is symmetric $Y_{ij} = Y_{ji}$
- All the rows of Y are in K
- For all i , $Y_0 - Y_i$ is in K
- Y is positive semidefinite.

Cone Formulation of LS+

Recall: Y positive semidefinite means: $v^T Y v \geq 0$ for all v .

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- $v^T (cA)v = c(v^T Av) \geq 0$, so cA is positive semidefinite.
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$N_+(K)$ is a convex cone.

SDP

A semi-definite program is of the form:

$$\begin{aligned} \min C \circ Y \quad & \text{s.t.} \\ A_1 \circ Y &= b_1 \\ & \vdots \\ A_m \circ Y &= b_m \\ Y &\succeq 0 \end{aligned}$$

Where C, A_1, \dots, A_m are symmetric matrices, and b_1, \dots, b_m are scalars.

Vertex Cover

LP:

$$\min \sum_{i \in V} x_i$$

$$x_i + x_j - 1 \geq 0 \quad \text{for all } (i, j) \in E$$

$$0 \leq x_i \leq 1 \quad \text{for all } i.$$

Vertex Cover

By applying LS lift rules:

$$(1 - x_i)(1 - x_j) \geq 0 \text{ for all } i, j.$$

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Since $x_i^2 = x_i$

$$\begin{aligned} 0 &\leq (1 - x_i)(x_i + x_j - 1) \\ &= (1 - x_i)(x_j - 1) \text{ for all } (i, j) \in E. \end{aligned}$$

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Or equivalently

$$(1 - x_i)(1 - x_j) \leq 0 \text{ for all } (i, j) \in E.$$

Vertex Cover

Let $x_0 = 1$.

$$\min \sum_{i \in V} (x_0 x_i)$$

$$(x_0 - x_i)(x_0 - x_j) = 0 \quad \text{for all } (i, j) \in E$$

$$(x_0 - x_i)(x_0 - x_j) \geq 0 \quad \text{for all } i, j.$$

Vertex Cover

Let $Y = U^T U$ be LS+ lifted matrix.
Let the columns of Y be (u_0, \dots, u_n) .

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Let the columns of Y be (u_0, \dots, u_n) . Then:

$$\min \sum_{i \in V} u_0 \cdot u_i$$

$$(u_0 - u_i) \cdot (u_0 - u_j) = 0 \quad \text{for all } (i, j) \in E$$

$$(u_0 - u_i) \cdot (u_0 - u_j) \geq 0 \quad \text{for all } i, j.$$

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Let $v_i = 2u_i - u_0$.

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$$\begin{aligned} \|v_i\|^2 &= v_i \cdot v_i \\ &= 4u_i \cdot u_i - 4u_i \cdot u_0 + u_0 \cdot u_0 \\ &= \|u_0\|^2 = 1 \end{aligned}$$

Vertex Cover

SDP

$$\min \sum_{i \in V} \frac{1 + v_0 \cdot v_i}{2}$$

$$(v_0 - v_i) \cdot (v_0 - v_j) = 0 \quad \text{for all } ij \in E$$

$$(v_0 - v_i) \cdot (v_0 - v_j) \geq 0 \quad \text{for all } i \in V$$

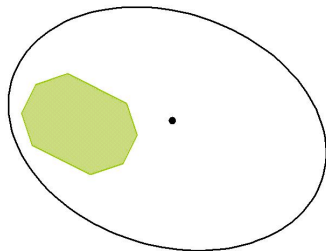
$$\|v_i\| = 1 \quad \text{for all } i \in V.$$

Separation Oracles

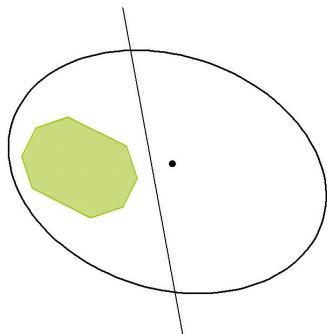
Definition

strong separation oracle - given a point x , returns that $x \in K$, or gives a separating hyperplane.

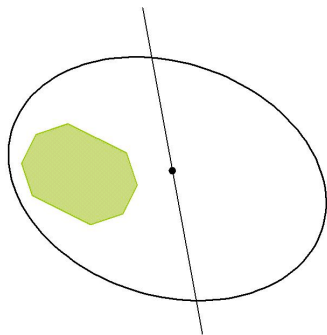
Ellipsoid Method for $N(K)$



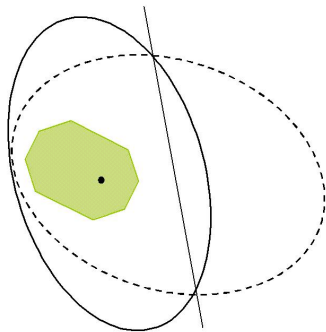
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Ellipsoid Method for $N(K)$



Ellipsoid Method for $N(K)$



Volume of ellipse decreases by $2^{\frac{1}{2n+2}}$.

Ellipsoid Method for $N_+(K)$?

$N_+(K)$ not necessarily polyhedral.

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Definition

weak separation oracle - given a point x and $\epsilon > 0$, returns that $\text{dist}(x, K) < \epsilon$ or returns a separating hyperplane h such that $\text{dist}(h, K^\perp) < \epsilon$.

Separation Problem

Theorem

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Can solve for space of Y matrices.

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Can solve for space of Y matrices.

First row, diagonal, and symmetry conditions can be checked trivially.

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Positive semi-definitiveness checked by Gaussian elimination.

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Given a weak separation oracle for K , we can solve the weak separation problem for $N_+(K)$ in polynomial time.

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Positive semi-definitiveness checked by Gaussian elimination.

Both row conditions given by separation oracle.

