

Spatial Sensor Web

- Interoperability and Scalability

Vincent Tao, PhD, PEng

Director, Microsoft Virtual Earth, Redmond

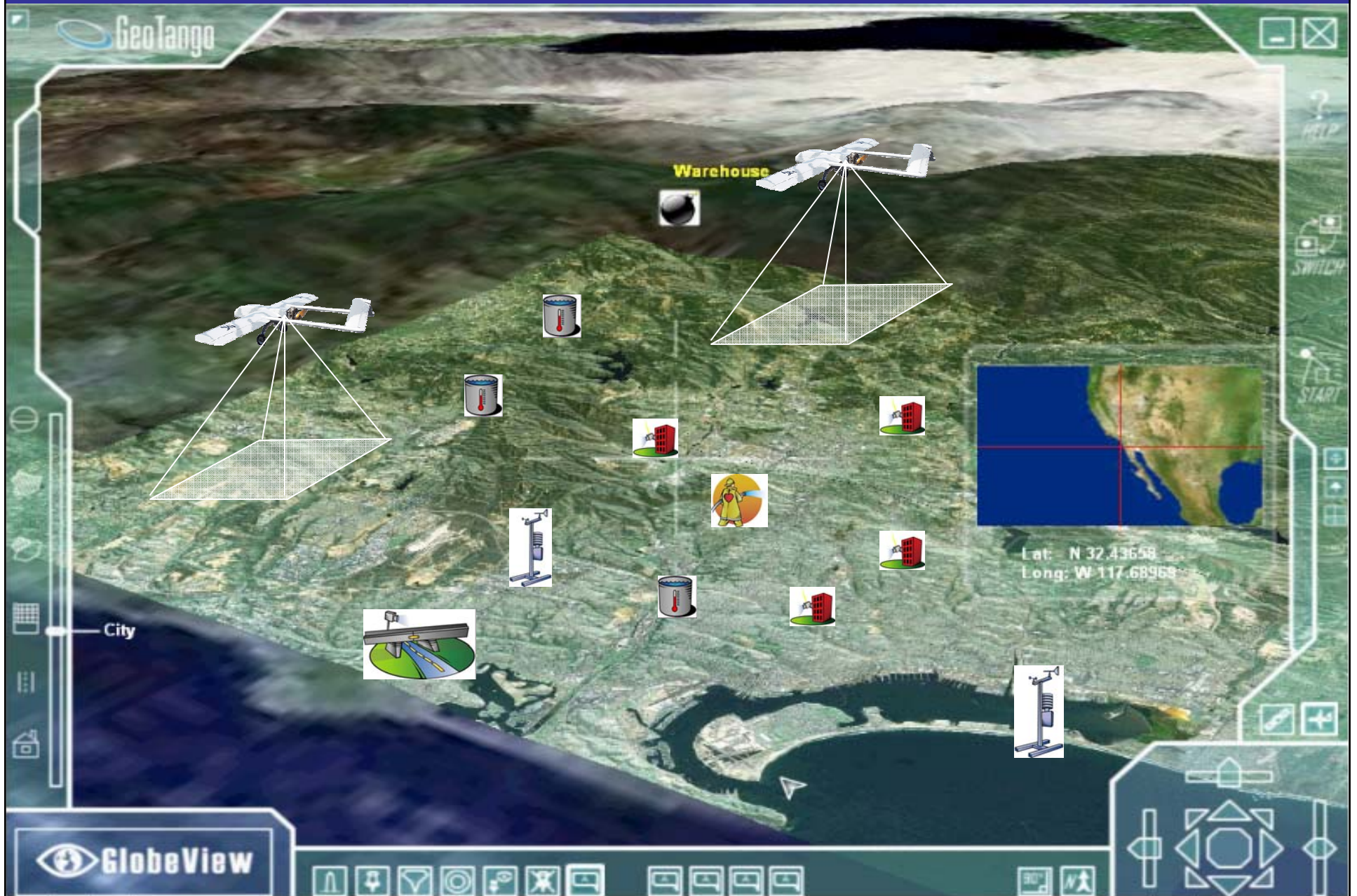
**Canada Research Chair Professor (on
leave) in Geospatial Information, York
University, Toronto**



Microsoft Virtual Earth

Build a virtual representation of the Earth for enabling users in the exploration and discovery of information

Spatial Sensor Web: An Electronic Skin of the Virtual Earth



Windows Live Local

Scratch pad

New York Buildings ▾

Add pushpin Map all Clear Sh

- 1 Empire State Building** ↑
The definitive must-see skyscraper; the view from the observation deck is fantastic.
- 2 New York Life Building** ↓
Another of the classic old NY skyscrapers...
- 3 MetLife Building** ↓
A downtown must see for generations

● [Real-time Traffic](#)



Sensor Web vs. Sensor Network

- Q: What is the implication of the traffic flow monitoring to the air quality monitoring?



Air Quality monitoring sensor network



Traffic monitoring sensor network

Challenges in Spatial Sensor Web

- **Interoperability**
- **Scalability**

Two Components for Interoperability

- *information model*
- *web service interface*

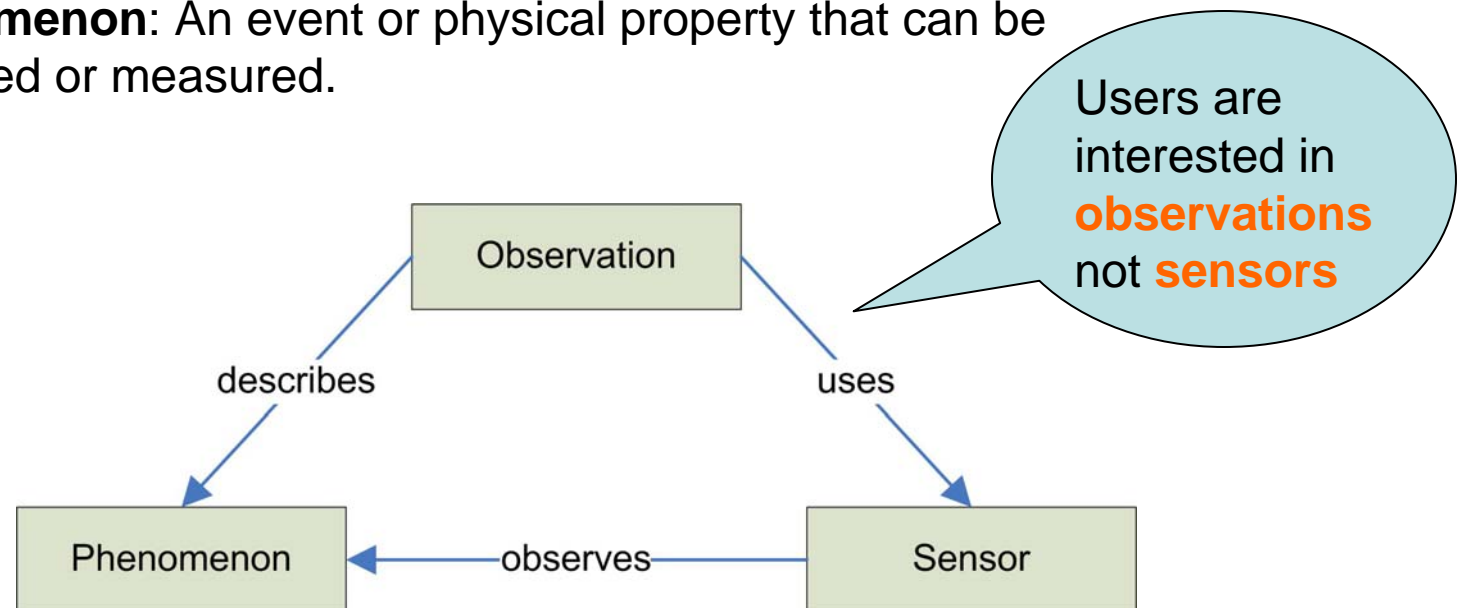
Information Model

- **What is?**

- The Standard Information Models **describe the entities** involved in the Sensor Web.

- **What are these entities?**

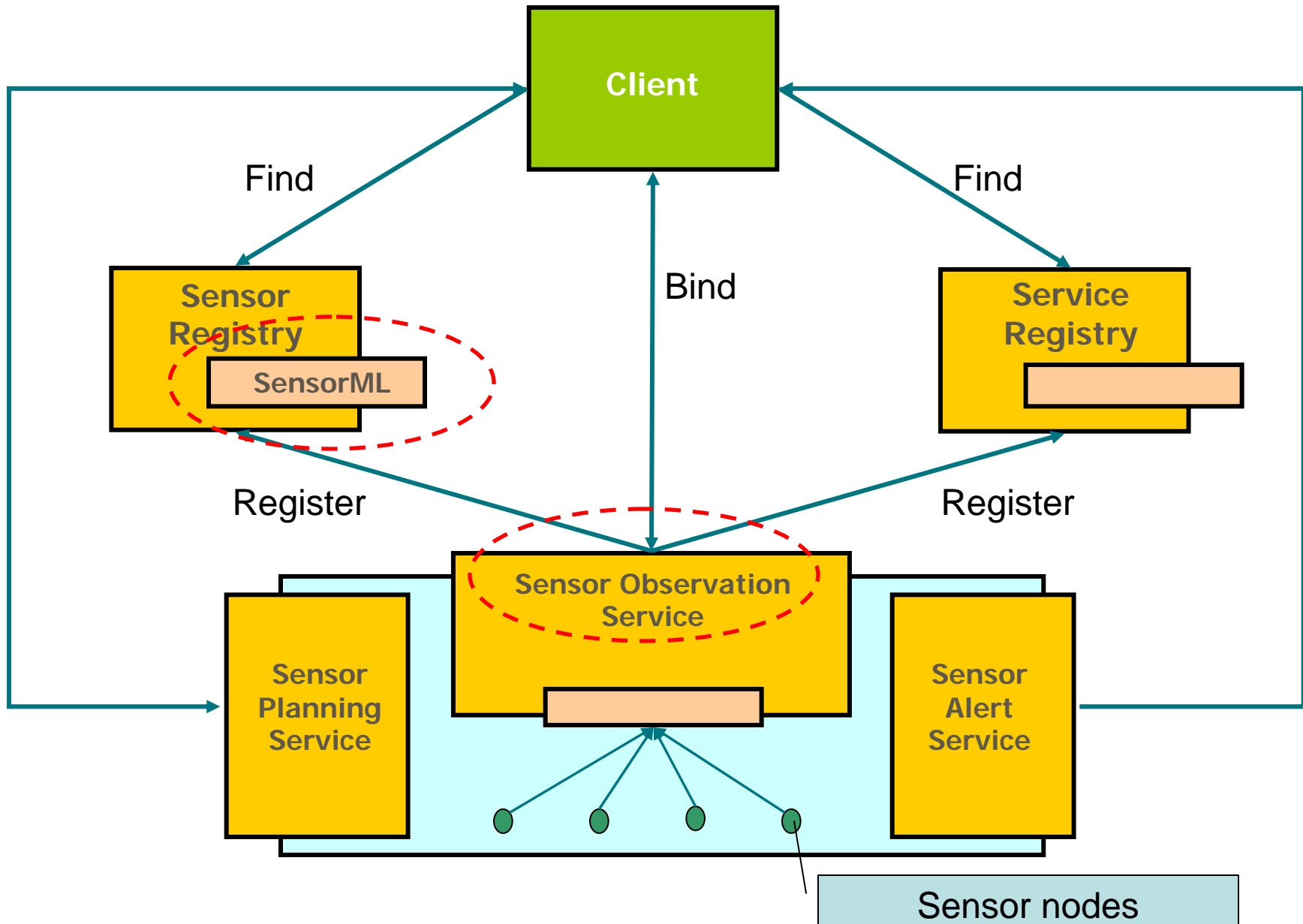
- **Observation:** An act of observing a phenomenon, with the goal of producing an estimate of the value of the phenomenon.
- **Sensor:** An entity capable of observing a phenomenon and returning an estimated value of the phenomenon.
- **Phenomenon:** An event or physical property that can be observed or measured.



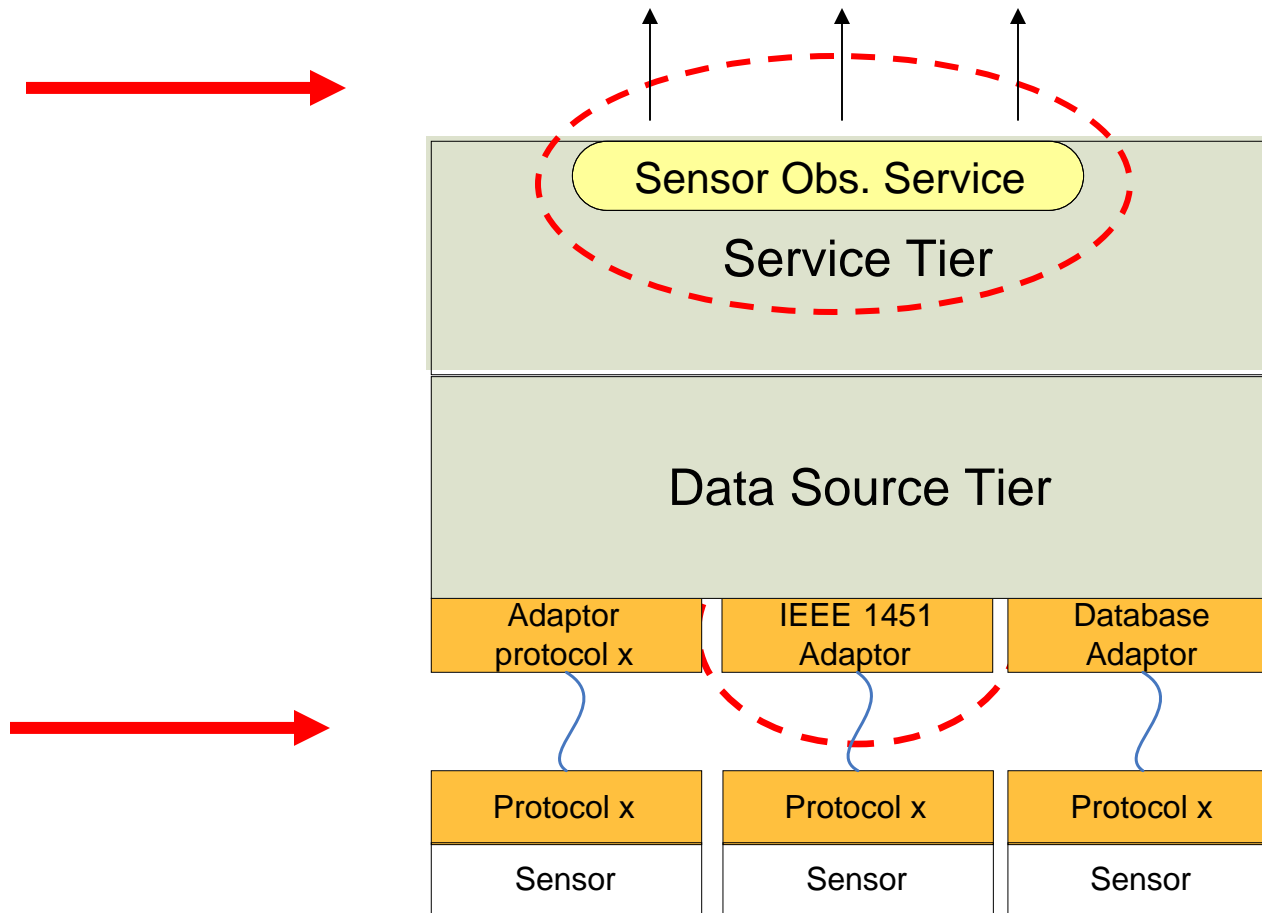
SensorML (OGC):

- **Observation characteristics**
 - Physical properties measured (e.g. radiometry, temperature, concentration, etc.)
 - Quality characteristics (e.g. accuracy, precision)
 - Response characteristics (e.g. spectral curve, temporal response, etc.)
- **Geometry Characteristics**
 - Size, shape, spatial weight function (e.g. point spread function) of individual samples
 - Geometric and temporal characteristics of sample collections (e.g. location, array, ...)
- **Description and Documentation**
 - Overall information about the sensor
 - History and reference information supporting the SensorML document

Web Service Interfaces (OCG)



Sensor Observation Services (SOS) Tiered Diagram



Scalability

The Scalability Challenge arises in several dimensions

● Numerical Scalability

- Need to large sensors and user populations of potentially millions or billions
- Need to supports large amount of simultaneous requests from the users
- Need to handle very frequent sensor join and arrivals
- Need to efficiently locate the desired sensors within the user specified geographical area

● Administrative Scalability

- Need to allow different administrative organizations to join the infrastructure while keep their autonomy

● Heterogeneous Scalability

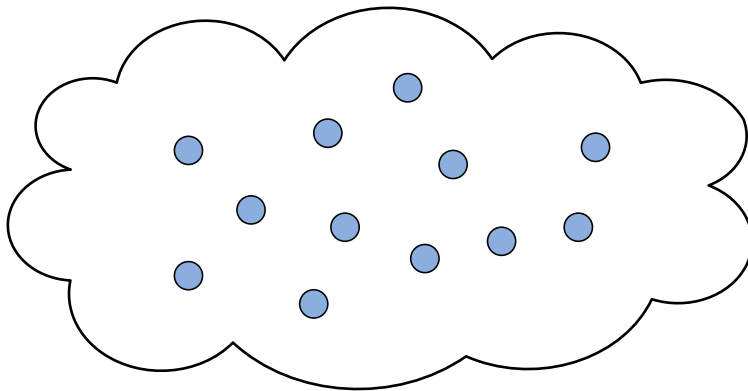
- Need to support a wide range types of sensors, from In-situ sensor networks to remote sensing satellites.

P2P Spatial Access Method (P2P-SAM)

Implement SAM using a Peer-to-Peer network

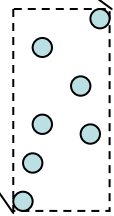
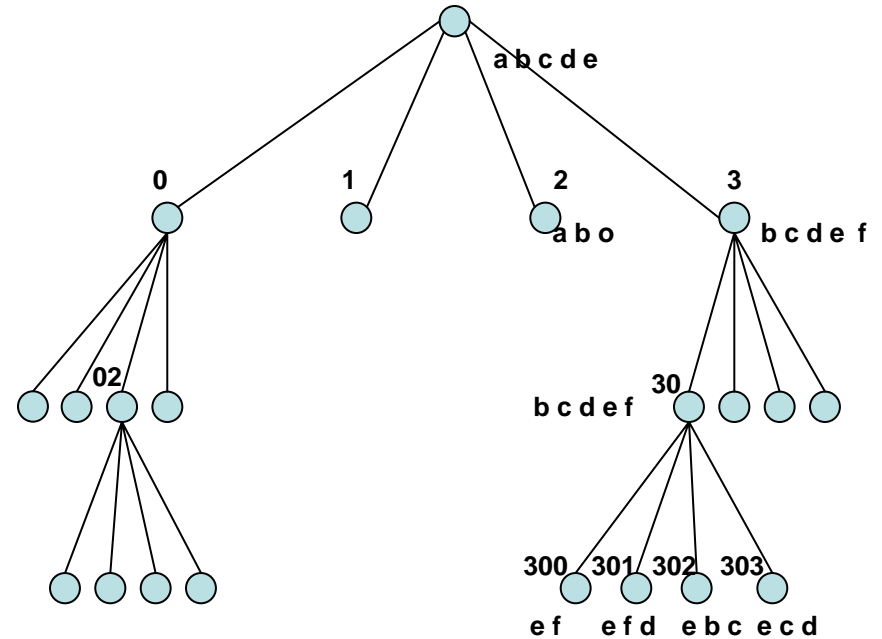
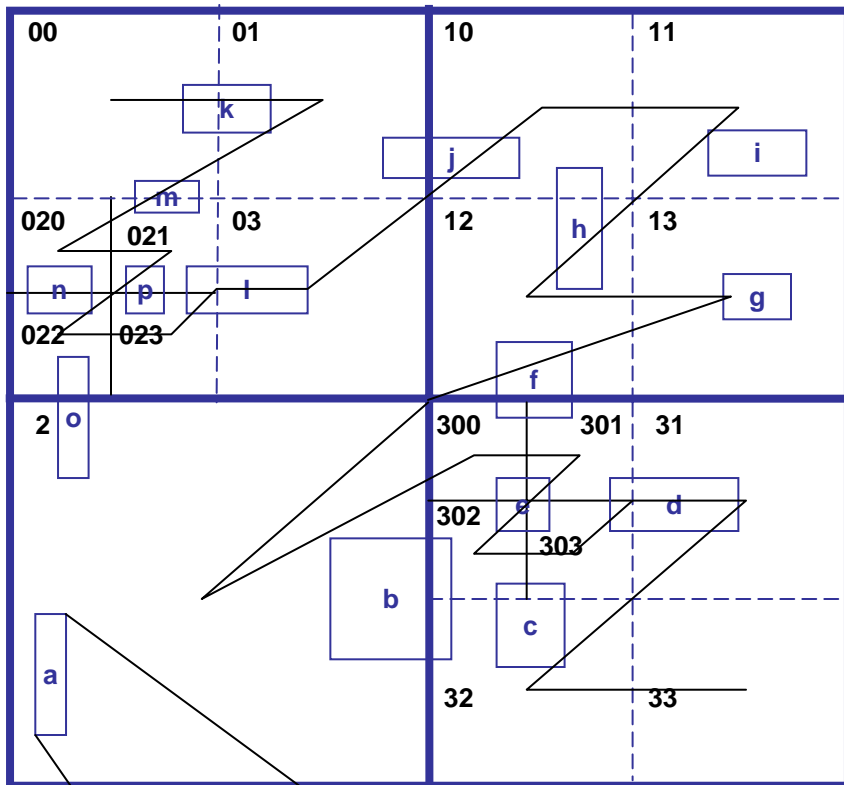
● P2P-SAM :

- Build and maintain a spatial index (e.g. a linear quad-tree) on a distributed file system implemented using a P2P network (e.g. Pastry and PAST)



1. **SLNs using DHT (Distributed Hash Table) to form a structured P2P network.**
2. **While a SLN join the DHT, it also inserts its bbox into the P2P-SAM index.**

P2P-SAM: Linear Quad-Tree (LQT)



The nodes are stored in a DHT-based distributed file system (e.g. Pastry and PAST).

When insert a node into DHT, the key is the morton code of the quad-tree leaf or quad-tree node (e.g. 303)

The value is a list of the SLNs' bboxes within the quad-tree leaf bbox and the ip-address of the SLNs.

Open Discussions

- **Sensor network vs. sensor web**
- **'Interoperability' among organizations**